

Meeting NASA's Needs with Creativity and Innovation:

"TECH & TELL"

A FY'12 Report from the JSC Office of the Chief Technologist

National Aeronautics and Space Administration

Johnson Space Center Houston, Texas

www.nasa.gov and http://www.nasa.gov/centers/johnson/technologyatjsc/home



Introduction and Overview

The Office of the Chief Technologist (OCT) has developed NASA's Space Technology Roadmaps to highlight the various technologies that are needed for NASA's missions as well as significant national needs. At the Center level, we understand that the Agency looks to its field centers to lead the development of many of these technologies, whether through our own innovation or in collaboration with industry and academic partners. Many of these relationships are managed, in part, by Center Chief Technologists (CCTs).



The Technology at JSC Logo

JSC's Chief Technologist works closely with the JSC's senior scientists, technologists and managers to sponsor and manage a substantial portfolio of technology projects along with a technology and innovation infrastructure that supports those projects. JSC's technology projects portfolio is guided by an informal technology strategy that maps to the overall JSC Strategic Implementation Plan in alignment with NASA's Strategic Plan. The overall goals of JSC's technology strategy are as follows:

Develop the Human Exploration Capabilities of Tomorrow

- Lead technology maturation efforts for human exploration
- Extend technology leadership in priority areas

Lead Advanced Development Collaborations on an International Scale

- Command partnering incentives that come from the ISS experience
- Promote effective co-developments with U.S. government and international partners, industry and academia

Excel in Technology Leadership, Management, and Innovation

- Evaluate innovative technical and business management practices
- Empower our workforce
- Emphasize the intellectual property/licensing outcomes of R&D investments

Maximize Relevance of Technology Outcomes to Life on Earth

- Promote R&D dual use developments supporting NASA and national needs
- Inspire the next generation
- Share the excitement

Continued vigilance in maintaining JSC competencies, capabilities, and a workforce skilled in their application is essential for NASA to remain a world-class hub for human space exploration. Our overall technology



Innovation 2012 at JSC

strategy was established to represent JSC's commitment to developing new technologies that support NASA's strategic goals.

Center Innovation Funds (CIF) are used by the JSC Chief Technologist's Office (JSC CTO) to support a substantial portion of JSC's portfolio of novel technologies that benefit NASA missions. These developments have the potential to address not only Center and Agency needs, but additional national needs as well.

The JSC Chief Technologist's Office

Organizationally, the JSC Chief Technologist is represented on <u>JSC's senior staff</u> and is supported by the <u>JSC Technology Working Group (JTWG)</u>. The JTWG is a Center-level advisory body that supports JSC leadership in ensuring successful integration and coordination of Center research and technology development efforts and innovation initiatives. It consists of representatives from each of JSC's line organizations that engage in research and technology development along with representatives from JSC's External Relations Office (public affairs, education and university affairs), Strategic Opportunities and Partnership Development Office (technology transfer) and the Human Exploration Development Support Office (human spaceflight technology needs).

The JSC Chief Technologist's Office (JSC CTO) is made up of a small, but specialized group of skilled and creative individuals who are truly passionate about NASA and Johnson Space Center. They are equally passionate about supporting and promoting the continued advances in technology and innovation at the Center.

The JSC CTO's primary priority is to foster an environment of creativity at the center while ensuring that JSC's technology competencies align with Agency needs. The JSC CTO is in a unique position to encourage extreme amounts of creativity and innovation to ensure continuing development of the best technologies for future missions. JSC's principal investigators are reaching for better options, seeking alternative applications, and searching for new directions to solve problems and make further human space exploration not only achievable, but more cost effective without compromising safety and reliability.

The JSC CTO is JSC's connection to the NASA Office of the Chief Technologist. In September, OCT issued a charter for the Chief Technologist's Council (*ref. "Executed: CTC Charter Signature Version" correspondence from Joyce Rhym, dated September 5, 2012*) as an advisory body to the NASA Chief Technologist. Included in the charter was an updated set of CCT roles and responsibilities accountable to the following three stakeholders:

- The Chief Technologist of the NASA Office of the Chief Technologist (OCT)
- The Director of the OCT Space Technology Program (STP)
- The Center Director

In accordance with guidance received from the CIF Program Executive that "the majority of the report should spell out the achievements and accomplishments with an emphasis/explanation of how each activity was innovative and improve a culture of innovation at the Center" (*ref.* "Final").

Report Deliverable" correspondence from Minoo Dastoor, dated August 28, 2012), the following two CCT responsibilities are highlighted below:

- Manage the NASA Center Innovation Fund (CIF) at the field Center.
- Serve as center change agent, particularly regarding the workforce's capacity to innovate

Center	STP	OCT
Role	Role	Role
X	X	
X		X

(note X, x = major, minor roles respectively)

With these responsibilities in mind, the JSC CTO leveraged the OCT CIF account with the Center Management and Operations (CM&O) Center Investments Account to support the following two categories of technology and innovation activities

Technology and Innovation Projects

- Center-Level Internal Research and Development (IR&D) Projects;
- Directorate-Level IR&D Projects; and
- Innovation Charge Account Studies

Technology and Innovation Infrastructure

- Facilities and Creative Spaces;
- Innovation Fairs and Symposia; and
- Workforce Initiatives

The details of each of these categories of activities is outlined in the following two sections.

Technology and Innovation Projects

Center-Level Internal Research and Development

For a number of cross-cutting technical areas, JSC continues to have co-existing silos of related

activities. In addition, it's important to maintain a focus on R&D priorities held at the Center

level. A Center-level IR&D account that promotes multi-organizational collaboration is one remedy to mitigate silos and emphasize Center-level priorities.

Annual proposal calls are developed by the JTWG and coordinated with JSC Senior Staff and then communicated to the JSC workforce via internal email distribution and JSC Today notices. The JTWG vets and prioritizes the solicitation response in a two-stage process and

then forwards a recommended IR&D portfolio to the JSC Chief Technologist for approval.



Assistance for Maintenance Repair by

Lui Wang

For 2012, the Center-Level IR&D proposal call was based on the intersection of the following priorities:

- Priority technology needs for Human Spaceflight;
- Priority core JSC technology competencies;
- High potential areas for technology commercialization; and
- High potential areas for technology partnerships

The Space Technology Roadmap Technology Area Breakdown Structure was used as a common taxonomy for assessing the intersections of the needs, competencies, commercialization and partnership priorities outlined above with the top 30 <u>"areas of significant overlap"</u> (see Appendix A) highlighted as the areas of focus for the proposal call.

Each project is typically authorized between \$100K and \$250K full cost. Approved activities are required to provide a mid-term status report and a year-end report to the JTWG. For multi-year projects and at the discretion of the JTWG, up to two one-year extensions may be authorized. Multi-organizational participation is required and collaboration/cost-sharing with external partners is highly encouraged.

Directorate-Level Internal Research and Development

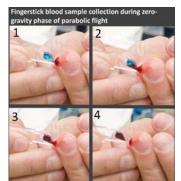
There is a concern that, in our efforts to encourage partnering and collaboration, certain Agencyunique competency areas that exist within a particular branch (or in some cases a particular

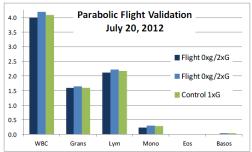
person) will atrophy or wither away completely. The idea of a discretionary IR&D account managed by each of JSC's R&D producing directorates is intended to address this concern.

FY2011 Directorate IR&D accounts included resources for the Engineering, Astromaterials Research and Exploration Science, and Human Health and Performance Directorates and the White Sands Test Facility. For FY2012, the Directorate IR&D fund was

Mars – ancient floods and a possible ocean as seen in a 2012 JSC Directorate-Level IR&D Project supported by the CIF: GIS Technology – Resource and Habitability Assessment Tool by Carlton Allen and Dorothy Oehler

expanded to include an allocation for Mission Operations and Safety and Mission Assurance Directorates. Project proposals for the Directorate-Level IR&D funding were requested in a similar manner as the Center





2012 JSC Directorate-Level IR&D Project supported by the CIF: Microgravity Cell Counter by Brian Crucian – (The fingerstick blood sample collection during gravity phase of parabolic flight and the flight validation chart)

IR&D projects with directorate management authorizing projects that address core technology competencies highlighted at the Center-level that are either uncovered or under-covered.

Each project is typically authorized up to between \$10K and \$100K full cost. Approved activities are required to provide a mid-term status report and a year-end report to the JTWG. For multi-year projects and at the discretion of the directorate management in coordination with the JTWG, up to two one-year extensions may be authorized. Though collaboration is encouraged, the Directorate IR&D fund does NOT include a partnering and multi-organizational participation requirement.

Innovation Charge Account

ICA is intended to address the need for "innovation time" recognized by the JSC Innovation and Inclusion Council. This effort also fosters a cross-Center environment of ingenuity and creativity at JSC by removing "filters" of oversight/control that sometimes inhibit promising

ideas from being developed to determine initial merit.

Semi-annual "calls for ideas" are developed by the JSC CTO and then communicated to the JSC workforce via informal email distribution and JSC Today notices. A three member "panel of recognized innovators" reviews and prioritizes submitted ideas in a two-step process before



A JSC 2012 ICA Project that received CIF support: Gesture Commanding of a Robot While Wearing EVA Gloves by Neta Ezer, Ph.D.

submitting to the JSC Chief Technologist for approval. Part of the process involves a 60second "elevator pitch" competition conducted at the JSC Collaboration Center in Building 3. The JSC workforce



A JSC 2012 ICA Project that received CIF support: Stitched Camera Array for Clearance Monitoring by Zach Drewry

is invited to attend and learn about emerging ideas and cheer on their colleagues!

ICA awards are numerous small dollar value awards, traditionally less than \$10,000 full cost, and are given to allow individuals or small collaborative groups to pursue creative ideas. ICA studies typically last no more than four months and a short briefing to the JTWG is required at the end of the activity.

JSC CIF projects moving forward: Of the 50 JSC IR&D/ICA projects supported with the Center Innovations Fund, 21 have filed a

New Technology Report through the JSC Tech Transfer Office. Several of these reports have received P1/T1 New Technology Evaluation ratings to pursue patents and additional ones have been scheduled for success story articles to be written and published.

A list of CIF-supported technology and innovation projects is included in Appendix B. Technical details for each of these projects are outlined in Appendix C. In all, over 50 CIF-funded project activities are included in this report.

Technology and Innovation Infrastructure

As NASA expands the horizons of human space exploration, its engineers and scientists must become increasingly creative in the solutions they design to meet ever more complex challenges. The JSC Chief Technologist works closely with other members of JSC senior staff to facilitate

an environment of ingenuity and creative thinking.

Facilities and Creative Spaces

There are a number of facilities and creative spaces at JSC where the Center community can gather to develop ideas and plan. <u>Creative spaces</u> are free areas around the JSC Community and Sonny Carter Training Facility that have access to Wi-Fi and are open to anyone (no locked

doors, no unnecessary layers of security). With the exception of the Building 3 Collaboration Center, these areas cannot be reserved, nor are they exclusive to any



A JSC Creative Space – The Building 3 Collaboration Center before the 2012 IR&D "Tech and Tell" event

office, program or directorate. More than a dozen of these sites are located around JSC and are designed to be comfortable, fun, open places where people can work and meet away from their normal offices. The Building 3 Collaboration Area is one of the largest and was used to host the 2012 IR&D "Tech and Tell" poster sessions.

The <u>Creative Café</u> was introduced during Innovation Day 2012 as a venue for collaborative innovation. Activities in the café included rap forums on multiple issues, panel discussions with subject matter experts including astrophysicists, space architects and astronauts, and refreshments were available for patrons throughout the day. Hundreds of people enjoyed their first taste of the Creative Café and its offerings.



Welcoming Creative Café visitors



Creative Café patrons settle with refreshments and wait for a rap forum presentation to begin.

The design layout for the café includes a space art gallery at the entrance, bistro tables for short-term casual conversations, large round tables for more focused and indepth discussions, a presentation stage and seating area for panel discussions and "rap forums", as well as a

concession area with coffee, tea, water, and light snacks all with a Parisian theme that included a hand-painted 50-foot backdrop. Due to



Rap session guest panelist takes questions from the Creative Café audience.

the positive reviews received by the JSC Chief Technologist, the venue is being scheduled and reserved for additional use during other special events throughout the year. The <u>Innovation Design Center</u> (IDC) is another part of the innovation infrastructure at JSC. The Building 348 IDC is a 5,000 ft facility where the JSC workforce can meet and conduct hands-on innovative design, fabrication and testing of ideas that are relevant to NASA's mission.



The JSC IDC - Building 348

The IDC offers both a collaboration-meeting area and a basic fabrication shop. The meeting space features a CAD workstation,

whiteboards, and wireless connectivity to assist in the discussion and maturation of

ideas, designs and technologies. For concept development, a

fabrication shop provides basic hand tools, as well as woodworking, machining, sheet metal, welding and electronics equipment, that can all be used for the hands-on development of project prototypes and working models. A new 3-D printer has also been installed and will be available for projects. Many CIF-funded IR&D and ICA investigations have been conducted in the IDC.



The IDC's well-equipped machine shop allows engineers and researchers to design and construct prototypes and models to go along with their innovative ideas.

Fairs and Symposia

Several unique learning sessions and specialized forums are sponsored by the JSC CTO to encourage and support more innovation and creativity in the workplace.

Since 2010, <u>Innovation Day</u> has become one day that is set aside annually at JSC for employees to take time out of their regular work day to participate in an environment that fosters greater collaboration and creative thinking and exposes employees to ideas, issues and perspectives expressed by individuals outside of their normal circle of associates.

During Innovation 2012, there were plenty of opportunities and options for communicating and networking with innovative people throughout the Center. Throughout the day, guest speakers and "rap forum" discussions focused on a wide variety of topics revolving around innovation and new technologies. A free lunch was offered and numerous booths were set up around the Center to exhibit new technologies and innovations developed at JSC.



Directorate representatives and co-ops staffed booths with engaging activities where participants used creative thinking to solve design or puzzle problems. The activities are often challenging, informative, interesting and yes, fun!

Innovation 2012
participants came
away with the
understanding that
innovation begins
within and there is
no "one way" to
innovate. Every
member of the JSC
team was encouraged to
bring personal passions
to work; and be inspired
to take chances and
suggest new ideas.



Innovation Day 2012 exhibitors show off NASA developments and innovative ideas while participants enjoy learning new things and using creative thinking to solve puzzles and challenges including playing a life-size "Angry Birds" game.





All of the FY 2012 Center-Level and Directorate-Level IR&D projects, as well as all of the ICA award recipients support mid-term reviews with the JTWG and participate in an out-briefing type of event at the end of their activity. For the FY 2012 projects, two half-day IR&D "Tech & Tell" Poster Sessions were held in the JSC Collaboration Center.



Principal Investigators presented their work for review during the 2012 "Tech and Tell" Poster Session

Participants' posters were displayed on easels and generally placed near other projects in a similar technical area. The principle investigators were able to showcase their projects

with the poster and a number of presenters displayed prototypes for visitors and employees from across the Center. The CIF Program Executive and several industry



A number of Principal Investigators brought prototypes with their posters to demonstrate their projects at the "Tech and Tell" event.

representatives attended and were delighted to have the chance to visit with so many innovators in a single location at the same time.

Workforce Initiatives

The JSC Chief Technologist is working with JSC's Human Resources Development Office to pilot a number of creativity training courses including *Building, Leading, and Sustaining the Innovative Organization*, conducted by Professor Ralph Katz from the M.I.T. Sloan School of Management at M.I.T and *Enhancing Your Creative Genius*, a home-grown class developed at Langley Research Center and conducted by Karen Friedt. These and other pilot efforts are all purposeful ways to demonstrate or stimulate a culture of creativity across the Center.

JSC once again participated in and sponsored a prize at the annual <u>Rice Business Plan</u> <u>Competition</u>. The 5th annual NASA Awards coordination and judging helps the JSC Tech Transfer Office and the JSC Chief Technologist identify new partners for potential innovative collaborations. The participating entrepreneurs could help us cross over gaps or increase our competencies at the Center. The competition is intended to bring innovative entrepreneurial companies or individuals together so they can showcase developed business plans and solicit start-up funds from early stage investors and venture capital firms.

New for FY'13 -- As part of a major effort to push directorate cross-over collaboration and creative, innovative new technologies, several workforce initiatives have been created. A new series of "Tech Talks" are being organized to raise awareness among the JSC community surrounding the programs and developments happening at the Center. By bringing people together to hear from and interact with subject matter experts and primary investigators, new ideas should emerge and develop. More technology needs can be met when we broaden our knowledge base and encourage team work and joint efforts.

New for FY'13 -- Another part of the workforce initiatives the JSC CTO is developing for FY'13 is a new <u>Cadre of Innovators</u>. During FY12, the JSC Cadre of Innovators idea began to grow. The groundwork has been laid out for FY13 and we will induct several candidates for membership into an elite cadre, or core group of highly qualified personnel, who will be able to give back to the community by mentoring and guiding the younger talent at JSC. They also will share their experiences at public schools and universities to encourage young minds to consider careers in science, technology, engineering, and mathematics.

Communications

Communicating JSC technology R&D efforts, opportunities, and successes are of paramount importance. For this reason, the JSC CTO works to diversify the ways we disseminate information internally <u>and</u> externally. The Office's communication specialist produced news stories and features from technology related activities and works with the JSC Public Affairs Office (PAO) to provide news for press releases and any other NASA internal or external communication venues deemed appropriate.

In addition to promoting activities and sharing information through the JSC PAO, JSC Today email messages and Around JSC articles, the JSC CTO has developed the Technology@JSC (see Appendix D) website. The site allows for more new technology and innovation success stories and information to be published.

The site went live this summer and is continuing to develop. One of the outstanding tools available to users is the JSC Technology Calendar of Events (a summary events calendar for FY'13 is included in Appendix E). It is populated with local, Agency, and national technology related events, as well as training sessions, upcoming proposal call specifics, and details for R&D project reviews.



A screen capture of the Technology at JSC homepage

To help site visitors learn more about partnering opportunities with JSC, or technology licensing details, several links are provided to the JSC Partnering Opportunities area under Featured Links. Technology News is a column updated with news features and success stories related to technology research and development at the Center and the Agency. In addition, the Technology@JSC site includes a *Technologist's Toolbox* column that features an area where technologists can find information about creative spaces around JSC, answers to frequently asked questions concerning intellectual property, and even specifics on how to request a NASA intern.

The <u>Technology@JSC</u> website offers a link under Important Information for the JSC Technology Focus Area/Roadmaps as well as the Research and Development (R&D) Partnership Database. These helpful links, along with the Upcoming Opportunities section of the site connects site visitors to Agency, Center-level, Directorate and industry-related technology calls. The JSC Chief Technologist wants the Technology@JSC website to be a one-stop shopping place for those people interested in technology related stories, R&D information and opportunities for the JSC community and beyond.

Conclusion

JSC is fully committed to bringing the excitement and reward of innovation and technology to a growing community. The Center Innovation Fund support provides a tremendous resource that helps support the JSC Chief Technologist's Office continue the mission of encouraging a culture of creativity and innovation here at the Johnson Space Center. By inspiring new ideas, bringing excitement and the reward of innovation and technology to a growing R&D community, and focusing on the technology needs of the Agency, Johnson Space Center is continuing to show its commitment to being at the forefront of human space exploration.

Appendices

- A. Technology "Areas of Significant Overlap" (Based on the Space Technology Area Breakdown Structure)
- B. FY'12 Center Innovation Fund Supported Project Charts
- C. JSC FY'12 CIF Support Project Details
- D. Technology at JSC Homepage
- E. The Year Ahead / Technology Calendar FY'13 One-Pager



Appendix A

Technology "Areas of Significant Overlap" (Based on the Space Technology Area Breakdown Structure)

AREAS OF SIGNIFICANT OVERLAP

OFFICIAL NASA ROADMAPS













• Liquid Storable

• Electric Propulsion

Solar Sail Propulsion

• Thermal Propulsion

ADVANCED (TRL <3)

Beamed Energy Propulsion

Electric Sail Propulsion

High Energy Density

• Fusion Propulsion

Materials

Tether Propulsion

TAO1 • LAUNCH PROPULSION SYSTEMS **TECHNOLOGIES**

Systems

- Propellants
- sion Technologies

LIQUID ROCKET PROPUL-SION SYSTEMS

- RP/LOX Based
- CH4/LOX Based
- Detonation Wave Engines (Closed Cycle)
- Propulsion Technologies
- AIR BREATHING
- Antimatter Propulsion Advanced Fission • Breakthrough Propulsion
 - SUPPORTING TECHNOLOGIES

TAO3 · SPACE POWER & **ENERGY STORAGE**

Power Generation

- Energy Harvesting

Distribution & Transmission

• Green Energy Impact

• Alternative Fuels

Multi-functional Structures

- Radioisotope Fission
- Fusion **ENERGY STORAGE**
- Flywheels
- Regenerative Fuel Cell Pyro & Separation Systems Power Management & Fundamental Ancillary

Propulsion Technologies DISTRIBUTION FDIR

- Management & Control PROPULSION SYSTEMS
- Wireless Power Air Launch / Drop Systems Transmission Space Tether Assist
- CROSS CUTTING Addition
- High Energy Density Materials/Propellants

REVISED-08/17/12

TA04 • ROBOTICS, **ROBOTICS & AUTONOMOUS** SYSTEMS

SENSING & PERCEPTION

- 3-D Perception Relative Position & Velocity
- Estimation Terrain Mapping, Classification
- & Characterization
- Sensor Fusion for Sampling & Manipulation Onboard Science Data

Analysis

CHEMICAL PROPULSION

- Above-Surface Mobility
 - MANIPUL ATION
 - Robot Arms
 - Modeling of Contact Dynamics
 - Mobile Manipulation
 - Robotic Drilling & Sample

HUMAN-SYSTEMS PROPULSION TECHNOLOGIES INTEGRATION

- Multi-Modal Human Systems Interaction
- Intent Recognition &
- Distributed Collaboration
- Common Human-Systems Interfaces Safety, Trust, &
- Interfacing of Robotic/ Human Proximity Operations AUTONOMY

- Dynamic Planning & Sequencing Tools Autonomous Guidance &
- Multi-Agent Coordination Adjustable Autonomy
- Terrain Relative Navigation • Path & Motion Planning with Uncertainty

AUTONOMOUS RENDEZVOUS & Docking

- Relative Navigation Sensors (long-, mid-, near-range)
- iidance Algorithms ocking & Capture
- Mission/System Managers for Autonomy/Automation

RTA Systems Engineering • Modularity/Commonality

- Verification & Validation of Complex Adaptive Systems
- Onboard Computing

TA05 • COMMUNICA & NAVIGATION COMMUNICATION

OPTICAL COMM. & NAVIGATION

- Large Apertures
- Acquisition & Tracking Atmospheric Mitigation

RADIO FREQUENCY COMMUNICATIONS • Spectrum Efficient Technologies

- Power Efficient Technologies Propagation
- Flight & Ground Systems Earth Launch & Reentry Comm. Antennas

INTERNETWORKING

- Disruptive Tolerant Networking Adaptive Network Topology Information Assurance
- Integrated Network Management Position, Navigation, and Timing • Timekeeping & Time Distribution
- Onboard Auto Navigation & Maneuver
- Sensors & Vision Processing Systems • Relative & Proximity Navigation Auto Precision Formation Flying Auto Approach & Landing
- INTEGRATED TECHNOLOGIES • Radio Systems
- Ultra Wideband Cognitive Networks
- Science from the Comm. System Hybrid Optical Comm. &
- RF/Optical Hybrid Technology
- REVOLUTIONARY CONCEPTS X-Ray Navigation
- X-Ray Communications Neutrino-Based Nav. & Tracking Quantum Key Distribution
- Quantum Communications SOIF Microwave Amplifier • Reconfigurable Large Apertures
- Using Nanosat Constellations

TA06 • HUMAN HEALTH, LIFE SUPPORT & **HABITATION SYSTEMS**

ENVIRONMENTAL CONTROL & LIFE SUPPORT SYSTEMS & Habitation Systems

Air Revitalization Vater Recovery & Management

Waste Management

Habitation EXTRAVEHICULAR ACTIVITY SYSTEMS

 Pressure Garment Portable Life Support System

• Power, Avionics & Software HUMAN HEALTH & PERFORMANCE

 Medical Diagnosis / Prognosis ong-Duration Health Behavioral Health

• Sensors: Air, Water, Microbial, etc. • Fire: Detection, Suppression, Recovery Protective Clothing / Breathing

Remediation RADIATION

• Risk Assessment Modeling





TA07 · HUMAN EXPLORATION **DESTINATION SYSTEMS**

- In-SITU RESOURCE UTILIZATION Destination Reconnaissance,
- Prospecting, & Mapping Resource Acquisition
- Manufacturing Products & Infrastructure Emplacement
 - Autonomous Logistics Management
 - Maintenance Systems Repair Systems

Systems

- EVA Mobility Surface Mobility
- Off-Surface Mobility "ADVANCED" HABITAT SYSTEMS
- Integrated Habitat Systems Habitat Evolution · "Smart" Habitats

Crew Training Planetary Safety

- Integrated Risk Assessment Tools
- CROSS-CUTTING SYSTEMS
- Construction & Assembly Particulate Contamination

TAO8 · SCIENCE INSTRUMENTS. **OBSERVATORIES & SENSOR** SYSTEMS

REMOTE SENSING INSTRUMENTS/SENSORS

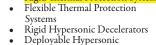
- Detectors & Focal Planes Electronics • Optical Components
- Lasers

OBSERVATORIES Mirror Systems

- Structures & Antennas Distributed Aperture IN-SITU INSTRUMENTS/SENSOR
- Particles: Charged & Neutral

TA09 ENTRY, DESCENT & ANDING SYSTEMS

AEROASSIST & ATMOSPHERIC ENTRY



DESCENT • Attached Deployable Decelerators

LANDING

Decelerators

- Trailing Deployable Decelerators Supersonic Retropropulsion
- Touchdown Systems Egress & Deployment Systems

Propulsion Systems Small Body Systems VEHICLE SYSTEMS TECHNOLOGY

Atmosphere & surface

- Separation Systems • System Integration and Analyses
- characterization • Modeling and Simulation Instrumentation and Health
- Monitoring GN&C Sensors and System

TA10 · NANO-

ENGINEERED MATERIALS & STRUCTURES

- Lightweight Structures Damage Tolerant Systems Coatings
- Thermal Protection & Control ENERGY GENERATION & STORAGE

Energy Storage Energy Generation **PROPULSION**

Adhesives

• Propellants Propulsion Components

• In-Space Propulsion SENSORS, ELECTRONICS &

- **DEVICES** Sensors & Actuators
- Nanoelectronics
- Miniature Instruments







MODELING. SIMULATION. INFORMATION TECHNOLOGY

COMPUTING

- Flight Computing
- Ground Computing Modeling
- Integrated Hardware & Software

Human-System Performance Modeling Science Modeling

SIMULATION

- Integrated System Lifecycle Simulation
- Simulation-Based Training & Decision Support Systems

INFORMATION PROCESSING

- Lifecvcle Intelligent Data Understanding
- Semantic Technologies Collaborative Science & Engineering

TA12 • MATERIALS STRUCTURES **MECHANICAL SYSTEMS &**

MATERIALS.

- Lightweight Structure
- Computational Design Flexible Material Systems

STRUCTURES

• Lightweight Concepts Design & Certification Methods

Innovative, Multifunctional Concepts MECHANICAL SYSTEMS

- Mechanism Life Extension Systems Electro-mechanical, Mechanical & Micromechanisms
- Design & Analysis Tools and Methods Reliability / Life Assessment / Health Monitoring

Certification Methods MANUFACTURING

- Intelligent Integrated Manufacturing and Cyber Physical Systems Electronics & Optics Manufacturing
- Process Sustainable Manufacturing

CROSS-CUTTING

Model-Based Certification & Sustainment Methods

TA13 GROUN GROUND & SYSTEMS PROCESSING

TECHNOLOGIES TO OPTIMIZE THE OPERATIONAL LIFE-CYCLE

- Automated Alignment, Coupling, & Assembly Systems
- Autonomous Command & Control for Ground and Integrated Vehicle / Ground

ENVIRONMENTAL AND GREEN TECHNOLOGIES

- Corrosion Prevention, Detection, & Mitigation Environmental Remediation &
- Site Restoration Preservation of Natural Fcosystems

Ålternate Energy Prototypes TECHNOLOGIES TO INCREASE RELIABILITY AND MISSION

AVAILABILITY

- Advanced Launch Technologies Environment-Hardened Materials and Structures
- Inspection, Anomaly Detection & Identification • Fault Isolation and Diagnostics
- Prognostics Technologies · Repair, Mitigation, and Recovery Technologies

Timing & Telemetry Technologies to Improve

MISSION SAFETY/MISSION RISK • Range Tracking, Surveillance & Flight Safety Technologies

Communications, Networking,

 Landing & Recovery Systems & Components Weather Prediction and Mitigation

Robotics / Telerobotics Safety Systems TA14 • THERMAL MANAGEMENT

SYSTEMS

• Heat Acquisition

& Radiative)

Heat Transfer

- CRYOGENIC SYSTEMS • Passive Thermal Control • Active Thermal Control
- Integration & Modeling THERMAL CONTROL SYSTEMS

Heat Rejection & Energ

- THERMAL PROTECTION SYSTEMS Entry / Ascent TPS Plume Shielding (Convective)
- Sensor Systems & Measurement Technologies

JSC SUPPLEMENTAL DATA

National Aeronautics and Space Administration

TA16 ORBITAL DEBRIS AND

AFROSCIENCES

- Propulsion Airframe Integration ORBITAL DEBRIS Drag Reduction
- Modeling Novel Configurations Monitoring
- Propulsion Airframe Aero Mitigation
 - - HYPERVELOCITY IMPACT

 - Experimental Investigations A17 · EMERGING TECHNOLOGIES

HYPERVELOCITY IMPACT

Space Technology Roadmaps STR • TABS **TECHNOLOGY AREA BREAKDOWN STRUCTURE**

Solid Nozzle Systems Hybrid Rocket Propulsion Hybrid Cold Gas/Warm Gas Systems Fundamental Solid Propul-• Micro-propulsion Non-Chémical Propulsion

- LH₂/LOX Based
- Propellants
- PROPULSION SYSTEMS TBCC
- Turbine Based Jet Engines (Flyback Boosters)

Air Collection & Enrichment System Fundamental Air Breathing

- Systems Auxiliary Control Systems Main Propulsion Systems
- Systems Health Management &

UNCONVENTIONAL / OTHER

Ground Launch Assist

Nuclear • Analytical Tools

SOLID ROCKET PROPULSION



Fundamental Liquid

- RBCC Detonation Wave Engines (Open Cycle)
- Ramjet/Scramjet Engines (Accelerators) Deeply-cooled Air Cycles
- Propulsion Technologies ANCILLARY PROPULSION
- (Excluding Engines) Launch Abort Systems Thrust Vector Control

Beamed Energy / Energy Conversion & Regulation TECHNOLOGY

• Detector Development

- Natural & Man-made Object Recognition
- MOBILITY Extreme Terrain Mobilit Below-Surface Mobility
- Small Body/
- - Processing
 - Supervisory Control Robot-to-Suit Interfaces
- Vehicle Systems Management & FDIR
- Control

Human Factors ENVIRONMENTAL MONITORING. SAFETY & EMERGENCY RESPONSE



SUSTAINABILITY & SUPPORTABILITY

Food Production, Processing, & Preservation "ADVANCED" HUMAN MOBILITY

Artificial Gravity MISSION OPERATIONS & SAFETY

Integrated Flight Operation

Prevention & Mitigation

Microwave / Radio Cryogenic / Thermal

& PROCESSING

- Software Modeling & Model-Checking

Frameworks, Languages, Tools & Standards

• Distributed Simulation

Simulation-Based Systems Engineering

Science, Engineering & Mission Data

Advanced Mission Systems

MANUFACTURING

Environment Special Materials

Reliability & Sustainment Test Tools & Methods

• Deployables, Docking and Interfaces

Nondestructive Evaluation

Loads and Environments

• Storage, Distribution & Conservation of Fluids

acoustics Computational Methods Robust Aero

- · Formation Flight Wake Vortex
 - VSTOL/ESTOL Reduce/Mitigate Sonic Boom • Multidisciplinary Design &

Analysis Tools Efficient Hypersonic Aero

- PROPULSION AND POWER Ouiet Propulsion • Ultraclean Propulsion &
- Alternative Fuels Fuel Efficiency Propulsion for STOL/VTOL
- Aero-Propulsion-Servo-Elasticity Robust Propulsion Hybrid Propulsion and Power

DYNAMICS, CONTROL,

Variable Cycle

Advanced Concepts Alternative Engine Cycles Intelligent Engine Integrated Power Management

Supersonic PropulsionCombined Cycle Hypersonic

NAVIGATION, GUIDANCE, AND AVIONICS Advanced Guidance Distributed Decision Uncertainty, &Flight Path

Distributed Flow Control of

Synthetic & Enhanced Vision

Vehicle Dynamics • Intelligent & Adaptive Control Fault-Tolerant IVHM

Pilot Vehicle Integration

On-Board Weather

ÚAV in the NAS • Advanced V&V Techniques Load, Vibration & Stability Control Advanced Communications

INTELLIGENT & HUMAN

Separation Assurance

Wake Vortex systems

Architecture Vulnerability

- INTEGRATED SYSTEMS. OPS. DECISION MAKING & NETWORKING • Complex Interactive Systems
- Analysis for Air Traffic Control Adaptive Air Traffic Control for Adverse Weather
- Operational Maintenance Data Task & Attention Management Environmentally Friendly

Collaborative Decision Systems

- Aviation • Super Density Operations
- Radiation Mitigation Fields & Waves Protection Systems • Radiation prediction

HUMAN SPACE FLIGHT TECHNOLOGY NEEDS*

OFFICIAL NASA ROADMAPS











CHEMICAL PROPULSION

iquid Cryogenic

Cold Gas/Warm Gas

Electric Propulsion

Solar Sail Propulsion

ADVANCED (TRL <3)

• Electric Sail Propulsion

High Energy Density

• Fusion Propulsion

Materials

Tether Propulsion

Non-Chémical Propulsion

• Micro-propulsion

• Liquid Storable

Solid

Hybrid



SOLID ROCKET PROPULSION Systems

- Propellants
- Case Materials
- Nozzle Systems Hybrid Rocket Propulsion
- Systems Fundamental Solid Propulsion Technologies

LIQUID ROCKET PROPUL-SION SYSTEMS

- LH_a/LOX Base
- CH₄/LOX Based
- Detonation Wave Engines (Closed Cycle)

(Open Cycle)

- Propellants
- Fundamental Liquid Propulsion Technologies
- AIR BREATHING PROPULSION SYSTEMS • Antimatter Propulsion
- Advanced Fission TBCC
- Breakthrough Propulsion RBCC
- Detonation Wave Engines SUPPORTING TECHNOLOGIES
- Turbine Based Jet Engines (Flyback Boosters) Ramjet/Scramjet Engines
- (Accelerators) Deeply-cooled Air Cycles Air Collection &
- **Enrichment System** Fundamental Air Breathing
- Propulsion Technologies ANCILLARY PROPULSION SYSTEMS
- Auxiliary Control Systems Main Propulsion Systems (Excluding Engines)
- Launch Abort Systems Thrust Vector Control
- Systems Health Management &
- Regenerative Fuel Cells Pyro & Separation Systems Fundamental Ancillary Propulsion Technologies

UNCONVENTIONAL / OTHER PROPULSION SYSTEMS

- Ground Launch Assist Air Launch / Drop Systems
- Space Tether Assist
- Beamed Energy / Energy Addition Nuclear
- High Energy Density Materials/Propellants

REVISED-08/10/12

ROBOTICS & AUTONOMOUS SYSTEMS

SENSING & PERCEPTION

- 3-D Perception Relative Position & Velocity
- Estimation Terrain Mapping, Classification
- & Characterization Natural & Man-made
- Object Recognition Sensor Fusion for Sampling
- & Manipulation Onboard Science Data

MOBILITY

- Extreme Terrain Mobility
- Below-Surface Mobility Above-Surface Mobility
- Small Body/Microgr Mobility
- MANIPUL ATION Robot Arms
- Modeling of Contact Dynamics
- Mobile Manipulation
- Robotic Drilling & Sample Processing

HUMAN-SYSTEMS PROPULSION TECHNOLOGIES INTEGRATION

- Beamed Energy Propulsion Multi-Modal Human
 - Systems Interaction

 - Robot-to-Suit Interfaces Intent Recognition &
 - Distributed Collaboration Common Human-Systems Interfaces
 - Safety, Trust, & Interfacing of Robotic Human Proximity perations

Management & FDIR

Autonomous Guidance &

Dynamic Planning &

Sequencing Tools

ith Uncertainty

AUTONOMOUS RENDEZVOUS

• Relative Navigation Sensors

(long-, mid-, near-range)

uidance Algorithms

ocking & Capture

Mission/System Managers

RTA Systems Engineering

Modularity/Commonality

Onboard Computing

* Can include HAT, HRP, ISS, Orion, SMD, etc. technology needs in support of future NASA missions.

for Autonomy/Automation

Verification & Validation o

omplex Adaptive Systems

AUTONOMY

Vehicle Systems

ontrol

& Docking

TAO3 · SPACE POWER & **ENERGY STORAGE**

Power Generation

- Energy Harvesting
- Radioisotope
- Fusion
- **ENERGY STORAGE**
- Flywheels
- Power Management & **DISTRIBUTION**
- Management & Control
- Wireless Power Transmission
- Conversion & Regulatio
- Cross Cutting TECHNOLOGY
- Analytical Tools • Green Energy Impact
- Multi-functional Structures Alternative Fuels

TA04 • ROBOTICS, TELE-

OPTICAL COMM. & NAVIGATION • Detector Development

TA05 • COMMUNICA & NAVIGATION

COMMUNICATION

- Large Apertures
- Acquisition & Tracking

Atmospheric Mitigation RADIO FREQUENCY COMMUNICATIONS

- · Spectrum Efficient Technologies Power Efficient Technologies Propagation
- Flight & Ground Systems Earth Launch & Reentry Comm.
- Antennas

INTERNETWORKING

- Disruptive Tolerant Networking Adaptive Network Topology Information Assurance
 - Integrated Network Management Position, Navigation, and Timing
 - Timekeeping & Time Distribution Onboard Auto Navigation &
 - Sensors & Vision Processing Systems Auto Precision Formation Flying
 - Auto Approach & Landing INTEGRATED TECHNOLOGIES
 - Radio Systems
 - Ultra Wideband Cognitive Networks
 - Science from the Comm. System Hybrid Optical Comm. &

RF/Optical Hybrid Technology REVOLUTIONARY CONCEPTS

- X-Ray Navigation X-Ray Communications
- Neutrino-Based Nav. & Tracking Quantum Key Distribution Quantum Communications
- SOIF Microwave Amplifier Reconfigurable Large Apertures Using Nanosat Constellations

TA06 • HUMAN HEALTH, LIFE SUPPORT & **HABITATION SYSTEMS**

ENVIRONMENTAL CONTROL & LIFE SUPPORT SYSTEMS & HABITATION SYSTEMS

- Air Revitalization Multi-Agent Coordination Adjustable Autonomy Water Recovery & Managemen Waste Management Terrain Relative Navigation Path & Motion Planning

EXTRAVEHICULAR ACTIVITY SYSTEMS Pressure Garment

- Portable Life Support System Power, Avionics & Software HUMAN HEALTH & PERFORMANCE
- Medical Diagnosis / Prognosis
- ong-Duration Health ehavioral Health Human Factors
- ENVIRONMENTAL MONITORING, SAFETY & EMERGENCY RESPONSE
- Sensors: Air, Water, Microbial, etc. ire: Detection, Suppression, Recover Protective Clothing / Breathing

Remediation RADIATION

- Risk Assessment Modeling ladiation Mitigation
- rotection Systems Radiation prediction







TA07 · HUMAN EXPLORATION **DESTINATION SYSTEMS**

In-Situ Resource Utilization

- Destination Reconnaissance, Prospecting, & Mapping
- Resource Acquisition
 Consumables Production Manufacturing Products
- & Infrastructure Emplacement SUSTAINABILITY &
- SUPPORTABILITY • Autonomous Logistics
- Management Maintenance System Repair Systems
- Food Production, Processing, & Preservation

"ADVANCED" HUMAN MOBILITY Systems

- EVA Mobility
- Off-Surface Mobility "ADVANCED" HABITAT SYSTEMS
- Integrated Habitat Systems Habitat Evolution Smart" Habitate

Artificial Gravity MISSION OPERATIONS & SAFETY

- Crew Training Planetary Safety Integrated Flight Operations
- Systems Integrated Risk Assessment Tools
- CROSS-CUTTING SYSTEMS Construction & Assembly
- Particulate Contamination Prevention & Mitigation

TAO8 · SCIENCE INSTRUMENTS, **OBSERVATORIES & SENSOR** SYSTEMS

REMOTE SENSING INSTRUMENTS/SENSORS

- Detectors & Focal Planes Electronics • Optical Components
- Microwave / Radio Lasers Cryogenic / Thermal
- **O**BSERVATORIES Mirror Systems
- Structures & Antennas Distributed Aperture IN-SITU INSTRUMENTS/SENSOR
- Particles: Charged & Neutral • Fields & Waves In-Situ

TA09 ENTRY, DESCENT & ANDING SYSTEMS

AFROASSIST &

- ATMOSPHERIC ENTRY Rigid Thermal Protection System lexible Thermal Protection
- igid Hypersonic Decelerators eployable Hypersonic

- DESCENT • Attached Deployable Decelerato Trailing Deployable Decelerators upersonic Retropropulsion
- LANDING
- Touchdown Systems Egress & Deployment Systems

- VEHICLE SYSTEMS TECHNOLOGY Separation Systems ystem Integration and Analyses
- Atmosphere & surface characterization
- Modeling and Simulation nstrumentation and Health
- Monitoring GN&C Sensors and Systems

TA10 NANO-**MECHANICAL SYSTEMS &**

ENGINEERED MATERIALS &

- Damage Tolerant Systems Computational Design Flexible Material Systems
- Adhesives Thermal Protection & Control ENERGY GENERATION & STORAGE

Energy Storage Energy Generation

• Lightweight Structures

STRUCTURES

Coatings

- **PROPULSION** Propellants
- Propulsion Components • In-Space Propulsion SENSORS, ELECTRONICS &
- **DEVICES** Sensors & Actuators

Nanoelectronics

Miniature Instruments





Advanced Mission Systems TA12 • MATERIALS STRUCTURES

Intelligent Data Understanding

MODELING.

SIMULATION.

Software Modeling & Model-Checki

Human-System Performance Modeling

Integrated System Lifecycle Simulation

Simulation-Based Systems Engineering

Science, Engineering & Mission Data

Collaborative Science & Engineering

Integrated Hardware & Software

Frameworks, Languages, Tools &

Simulation-Based Training &

Decision Support Systems

INFORMATION PROCESSING

Semantic Technologies

INFORMATION TECHNOLOGY

& PROCESSING

Ground C

Modeling

Science Modeling

• Distributed Simulation

COMPUTING

Modeling

SIMULATION

Lifecvcle

MATERIALS.

MANUFACTURING

Environment Special Materials

- STRUCTURES Lightweight ConceptsDesign & Certification Methods
- Reliability & Sustainment Test Tools & Methods

MECHANICAL SYSTEMS • Deployables, Docking and Interfaces ism Life Ex

- Electro-mechanical, Mechanical & Micromechanisms Design & Analysis Tools and Methods Reliability / Life Assessment / Health
- Monitoring Certification Methods MANUFACTURING

- Intelligent Integrated Manufacturing and Cyber Physical Systems Electronics & Optics Manufacturing Process
- Sustainable Manufacturing CROSS-CUTTING Nondestructive Evaluation
- Model-Based Certification & Sustainment Methods

Loads and Environments

TA13 GROUN GROUND & SYSTEMS PROCESSING

TECHNOLOGIES TO OPTIMIZE

- THE OPERATIONAL LIFE-CYCLE Storage, Distribution &
- Propulsion Airframe Aero-
- acoustics Automated Alignment, Computational Methods Coupling, & Assembly Systems Robust Aero
- Autonomous Command & Control for Ground and Integrated Vehicle / Ground

ENVIRONMENTAL AND GREEN

- **T**ECHNOLOGIES
- Corrosion Prevention
- Efficient Hypersonic Aero Detection, & Mitigation PROPULSION AND POWER Environmental Remediation & Ouiet Propulsion
- Site Restoration
- Alternate Energy Prototypes
- TECHNOLOGIES TO INCREASE RELIABILITY AND MISSION **AVAILABILITY**
- Advanced Launch Technologies Environment-Hardened
- Materials and Structures Inspection, Anomaly Detection & Îdentification
- Fault Isolation and Diagnostic rognostics Technologies

Technologies to Improve

Landing & Recovery Systems

TA14 • THERMAL MANAGEMENT

& Components

Mitigation

Safety Systems

SYSTEMS

Weather Prediction and

Robotics / Telerobotics

CRYOGENIC SYSTEMS

• Heat Acquisition

• Entry / Ascent TPS

& Radiative)

Technologies

Heat Transfer

Passive Thermal Control

Integration & Modeling

Active Thermal Contro

THERMAL CONTROL SYSTEMS

Heat Rejection & Energy

THERMAL PROTECTION SYSTEMS

Plume Shielding (Convective)

Sensor Systems & Measurement

- Integrated Power Management • Repair, Mitigation, and Recovery Technologies DYNAMICS, CONTROL, Communications, Networking, NAVIGATION, GUIDANCE, AND Timing & Telemetry AVIONICS
- MISSION SAFETY/MISSION RISK Distributed Decision • Range Tracking, Surveillance & Uncertainty, &Flight Path Flight Safety Technologies Distributed Flow Control of
 - Vehicle Dynamics • Intelligent & Adaptive Control

• Pilot Vehicle Integration

Advanced Guidance

- Fault-Tolerant IVHM On-Board Weather
- Synthetic & Enhanced Vision ÚAV in the NAS Advanced V&V Techniques
- Load, Vibration & Stability Control Advanced Communications INTELLIGENT & HUMAN INTEGRATED SYSTEMS. OPS.

DECISION MAKING &

- NETWORKING • Complex Interactive Systems Separation Assurance
- Wake Vortex systems Architecture Vulnerability Analysis for Air Traffic Control
- Adaptive Air Traffic Control for Adverse Weather Collaborative Decision Systems
- Operational Maintenance Data Task & Attention Management
- Environmentally Friendly Aviation

Monitoring Mitigation Remediation HYPERVELOCITY IMPACT

Material Composition

Experimental Investigations

A17 · EMERGING TECHNOLOGIES

TA16 • ORBITAL DEBRIS AND

HYPERVELOCITY IMPACT

ORBITAL DEBRIS

Modeling

National Aeronautics and

JSC SUPPLEMENTAL DATA

• AERONAUTICS

Propulsion Airframe Integration

AFROSCIENCES

Drag Reduction

· Formation Flight

Wake Vortex

VSTOL/ESTOL

Analysis Tools

Novel Configurations

• Reduce/Mitigate Sonic Boom

• Multidisciplinary Design &

• Ultraclean Propulsion &

Supersonic Propulsion

Aero-Propulsion-Servo-

Robust Propulsion

Advanced Concepts

Intelligent Engine

Variable Cycle

Combined Cycle Hypersonic

Propulsion for STOL/VTOL

Hybrid Propulsion and Power

Alternative Engine Cycles

Alternative Fuels

Fuel Efficiency

Elasticity

Space Administration

• Super Density Operations

Space Technology Roadmaps STR • TABS **TECHNOLOGY AREA BREAKDOWN STRUCTURE**



JSC CORE TECHNOLOGY COMPETENCIES

OFFICIAL NASA ROADMAPS













CHEMICAL PROPULSION

iquid Cryogenic

Cold Gas/Warm Gas

Non-Chemical Propulsion

Micro-propulsion

• Electric Propulsion

Solar Sail Propulsion

• Thermal Propulsion

ADVANCED (TRL <3)

Electric Sail Propulsion

High Energy Density

• Antimatter Propulsion

• Fusion Propulsion

Advanced Fission

Materials

Tether Propulsion

• Liquid Storable

Hybrid

SOLID ROCKET PROPULSION Systems

TAO1 • LAUNCH PROPULSION

• Propellants Case Materials

SYSTEMS

- Nozzle Systems
- Hybrid Rocket Propulsion Fundamental Solid Propul-

sion Technologies LIQUID ROCKET PROPUL-SION SYSTEMS

LH₂/LOX Based

RP/LOX Based

Detonation Wave Engines (Closed Cycle) Propellants

Propulsion Tech

AIR BREATHING PROPULSION SYSTEMS

 TBCC RBCC

SUPPORTING TECHNOLOGIES Detonation Wave Engines (Open Cycle)

Turbine Based Jet Engines (Flyback Boosters)

TAO3 · SPACE POWER & Ramjet/Scramjet Engines (Accelerators) Deeply-cooled Air Cycles **ENERGY STORAGE** Air Collection & **Enrichment System**

Fundamental Air Breathing

Propulsion Technologies • Energy Harvesting ANCILLARY PROPULSION SYSTEMS

Main Propulsion Systems Radioisotope (Excluding Engines)

Launch Abort Systems Fusion Thrust Vector Control

Health Management &

vro & Separation System Fundamental Ancillary Power Management & **DISTRIBUTION**

UNCONVENTIONAL / OTHER PROPULSION SYSTEMS

Ground Launch Assist Wireless Power Air Launch / Drop Systems

Space Tether Assist Beamed Energy / Energy Addition Cross Cutting

Nuclear

High Energy Density Materials/Propellants

TA04 • ROBOTICS, TELE-**ROBOTICS & AUTONOMOUS** SYSTEMS

Relative Position & Velocity

Terrain Mapping, Classification & Characterization

Object Recognition Onboard Science Data

MOBILITY

• Extreme Terrain Mobility Below-Surface Mobility Above-Surface Mobili

MANIPUL ATION

lodeling of Contact vnamics Mobile Manipulation

Robotic Drilling & Sample

HUMAN-SYSTEMS PROPULSION TECHNOLOGIES INTEGRATION • Beamed Energy Propulsion

 Multi-Modal Human ystems Interaction

Robot-to-Śuit Interface Intent Recognition &

Distributed Collaboratio ommon Human-Systems

Safety, Trust, & Interfacing of Robotic Human Proximity

AUTONOMY Vehicle Systems

Power Generation

Fission

ENERGY STORAGE

 Flywheels Regenerative Fuel Cells

Transmission Conversion & Regulation

TECHNOLOGY Analytical Tool:

 Green Energy Impact Multi-functional Structures Alternative Fuels

OPTICAL COMM. & NAVIGATION • Detector Development

COMMUNICATION

 Large Apertures Acquisition & Tracking

 Atmospheric Mitigation RADIO FREQUENCY COMMUNICATIONS Spectrum Efficient Technol

Power Efficient Technologies ropagation Earth Launch & Reentry Comm.

INTERNETWORKING

• Disruptive Tolerant Networking Adaptive Network Topology Information Assurance • Integrated Network Management

Position, Navigation, and Timing • Timekeeping & Time Distribution Onboard Auto Navigation &

Maneuver • Sensors & Vision Processing Systems Auto Precision Formation Flying

 Radio Systems Jltra Wideband Science from the Comm. System Hybrid Optical Comm. &

INTEGRATED TECHNOLOGIES

RF/Optical Hybrid Technology

REVOLUTIONARY CONCEPTS X-Ray Navigation

 X-Ray Communications Neutrino-Based Nav. & Tracking Quantum Key Distribution

 Quantum Communications SOIF Microwave Amplifier

• Reconfigurable Large Apertures Using Nanosat Constellations

TA06 • HUMAN HEALTH, LIFE SUPPORT & **HABITATION SYSTEMS**

ENVIRONMENTAL CONTROL & LIFE SUPPORT SYSTEMS & HABITATION SYSTEMS

Multi-Agent CoordinationAdjustable Autonomy Air Revitalization Vater Recovery & Management Waste Management

EXTRAVEHICULAR ACTIVITY SYSTEMS Pressure Garment

 Portable Life Support System
 Power, Avionics & Software HUMAN HEALTH & PERFORMANCE

 Medical Diagnosis / Prognosis ong-Duration Health ehavioral Health Human Factors

SAFETY & EMERGENCY RESPONSE

ensors: Air, Water, Microbial, etc. Fire: Detection, Suppression, Recovery Protective Clothing / Breathing

RADIATION

• Risk Assessment Modelin adiation Mitigation

 Protection Systems • Radiation prediction







TA07 · HUMAN EXPLORATION **DESTINATION SYSTEMS**

In-SITU RESOURCE UTILIZATION

ospecting, & Mapping Resource Acquisition

Manufacturing Products & Infrastructure Emplacement SUSTAINABILITY &

• Autonomous Logistics Management Maintenance Systems

• Repair Systems Food Production, Processing, & Preservation

Systems

EVA Mob

• Integrated Habitat Systems abitat Evolution "Smart" Habitats

MISSION OPERATIONS & SAFETY

Planetary Safety Integrated Flight Operation

CROSS-CUTTING SYSTEMS Construction & Assembly

articulate Contamination Prevention & Mitigation

TAO8 • SCIENCE INSTRUMENTS **OBSERVATORIES & SENSOR** SYSTEMS

REMOTE SENSING INSTRUMENTS/SENSORS

• Detectors & Focal Planes Electronics

Microwave / Radio Lasers Cryogenic / Thermal

Mirror Systems Structures & Antennas

Distributed Aperture In-SITU INSTRUMENTS/SENSOR • Particles: Charged & Neutral

Fields & Waves

TA09 ENTRY, DESCENT & ANDING SYSTEMS

AFROASSIST & ATMOSPHERIC ENTRY

 Flexible Thermal Protection Systems

Rigid Hypersonic Decelerators Deployable Hypersonic Decelerators

DESCENT

LANDING

• Attached Deployable Decelerators Trailing Deployable Decelerators • Supersonic Retropropulsion

• Touchdown Systems Egress & Deployment Systems

Propulsion Systems Small Body Systems

VEHICLE SYSTEMS TECHNOLOGY Separation Systems

Atmosphere & surface

characterization Modeling and Simulati nstrumentation and Health Monitoring

ENGINEERED MATERIALS &

• Lightweight Structures

Damage Tolerant Systems

Thermal Protection & Control

ENERGY GENERATION & STORAGE

STRUCTURES

Coatings

Adhesives

PROPULSION

DEVICES

Energy Storage

Energy Generation

Propulsion Components

SENSORS, ELECTRONICS &

• In-Space Propulsion

Sensors & Actuators

Miniature Instruments

Nanoelectronics

GN&C Sensors and Systems

TA10 · NANO-TECHNOLOGY

MATERIALS.

Computational Design Flexible Material System

Special Materials

• Lightweight Concepts Design & Certification Methods Reliability & Sustainment

Test Tools & Methods Innovative, Multifunctional Concer

• Deployables, Docking and Interfac Mechanism Life Extension Systems Electro-mechanical, Mechanical &

Reliability / Life Assessment / Health Monitoring

Certification Methods MANUFACTURING

Intelligent Integrated Manufacturing and Cyber Physical Systems Electronics & Optics Manufacturing Process

CROSS-CUTTING

Nondestructive Evaluation Model-Based Certification &

TA13 GROUN GROUND & SYSTEMS PROCESSING

Conservation of Fluids acoustics

 Autonomous Command & Control for Ground and Integrated Vehicle / Ground

ENVIRONMENTAL AND GREEN TECHNOLOGIES

· Corrosion Prevention. Detection, & Mitigation Environmental Remediation &

Site Restoration Preservation of Natural Eco-

 Ålternate Energy Prototypes TECHNOLOGIES TO INCREASE RELIABILITY AND MISSION **AVAILABILITY**

 Environment-Hardened Materials and Structures

Inspection, Anomaly Detection & Identification • Fault Isolation and Diagnostics

Recovery Technologies

MISSION SAFETY/MISSION RISK

• Range Tracking, Surveillance & Uncertainty, &Flight Path Flight Safety Technologies Distributed Flow Control of Vehicle Dynamics

Intelligent & AdaptiveFault-Tolerant IVHM

Mitigation Robotics / Telerobotics Safety Systems

TA14 • THERMAL MANAGEMENT SYSTEMS

CRYOGENIC SYSTEMS Passive Thermal Control

 Active Thermal Control Integration & Modeling THERMAL CONTROL SYSTEMS

 Heat Acquisition Heat Rejection & Energy

THERMAL PROTECTION SYSTEMS

 Entry / Ascent TPS Plume Shielding (Convective) & Radiative)

Sensor Systems & Me

echnologies

Novel Configurations Propulsion Airframe Aero-Computational Methods

AFROSCIENCES

Robust Aero · Formation Flight

Drag Reduction

Wake Vortex VSTOL/ESTOL

• Reduce/Mitigate Sonic Boom • Multidisciplinary Design & Analysis Tools

Propulsion Airframe Integration

PROPULSION AND POWER

• Quiet Propulsion Ultraclean Propulsion & Alternative Fuels

 Fuel Efficiency Propulsion for STOL/VTOL

Supersonic Propulsion Combined Cycle Hypersonic Aero-Propulsion-Servo-

Robust Propulsion Hybrid Propulsion and Power Variable Cycle Advanced Concepts/

Elasticity

Alternative Engine Cycles Intelligent Engine Integrated Power Management

DYNAMICS, CONTROL, NAVIGATION, GUIDANCE, AND AVIONICS

Advanced Guidance Distributed Decision

On-Board Weather

 Advanced V&V Techniques Load, Vibration & Stability

NETWORKING • Complex Interactive Systems

 Architecture Vulnerability Analysis for Air Traffic Control Adaptive Air Traffic Control

for Adverse Weather Collaborative Decision Systems

Task & Attention Management Environmentally Friendly

Aviation

JSC SUPPLEMENTAL DATA

National Aeronautics and Space Administration

TA16 • ORBITAL DEBRIS AND HYPERVELOCITY IMPACT

ORBITAL DEBRIS

 Modeling Monitoring

• Mitigation

HYPERVELOCITY IMPACT Material Composition Experimental Investigatio

A17 • EMERGING TECHNOLOGIES

Space Technology Roadmaps STR • TABS **TECHNOLOGY AREA BREAKDOWN STRUCTURE**

TA05 • COMMUNICA & NAVIGATION

SENSING & PERCEPTION

Natural & Man-made Sensor Fusion for Sampling

Analysis

Small Body/Microgravity

Robot Arms Dexterous Manipulators

Processing

pervisory Contro

Management & FDIR Dynamic Planning & Sequencing Tools

Control

 Terrain Relative Navigation Path & Motion Planning ith Uncertainty

AUTONOMOUS RENDEZVOUS & Docking elative Navigation Sensor ong-, mid-, near-range) iidance Algorithms Docking & Capture

Mechanisms/Interfaces

Verification & Validation of

Complex Adaptive Systems

Onboard Computing

Mission/System Managers RTA Systems Engineering

ENVIRONMENTAL MONITORING.

Destination Reconnaissance

SUPPORTABILITY

"ADVANCED" HUMAN MOBILITY

 Off-Surface Mobility "ADVANCED" HABITAT SYSTEMS

Artificial Gravity

• Integrated Risk Assessment Tools

• Optical Components

OBSERVATORIES





Ground Co MODELING • Software Modeling & Model-Checki Integrated Hardware & Software

Science Modeling Frameworks, Languages, Tools &

SIMULATION

 Distributed Simulation Integrated System Lifecycle Simulation Simulation-Based Systems Engineer Simulation-Based Training &

INFORMATION PROCESSING • Science, Engineering & Mission Data Intelligent Data Understanding

Collaborative Science & Engineering

TA12 • MATERIALS STRUCTURES **MECHANICAL SYSTEMS & MANUFACTURING**

Advanced Mission Systems

STRUCTURES

MECHANICAL SYSTEMS

Micromechanisms Design & Analysis Tools and Metho









TECHNOLOGIES TO OPTIMIZE THE OPERATIONAL LIFE-CYCLE • Storage, Distribution &

 Automated Alignment, Coupling, & Assembly Systems

Efficient Hypersonic Aero

systems

• Advanced Launch Technologies

 Prognostics Technologies · Repair, Mitigation, and

• Communications, Networking, Timing & Telemetry Technologies to Improve

 Landing & Recovery Systems & Components Weather Prediction and

> Synthetic & Enhanced Vision • ÚAV in the NAS

Control Advanced C INTELLIGENT & HUMAN INTEGRATED SYSTEMS. OPS. DECISION MAKING &

Separation Assurance Wake Vortex systems

Operational Maintenance Data

• Super Density Operations

REVISED-08/10/12 Note: Only ISC core competencies are highlighted.

COMMERCIALIZATION POTENTIAL – JSC PERSPECTIVE

OFFICIAL NASA ROADMAPS











• Liquid Storable

Cold Gas/Warm Gas

Non-Chémical Propulsion

• Micro-propulsion

Electric Propulsion

Solar Sail Propulsion

Thermal PropulsionTether Propulsion

ADVANCED (TRL <3)

Electric Sail Propulsion

High Energy Density

• Breakthrough Propulsion

SUPPORTING TECHNOLOGIES

• Antimatter Propulsion

• Fusion Propulsion

Advanced Fission

Materials

Solid

Hybrid



SOLID ROCKET PROPULSION Systems Propellants

- Case Materials
- Systems
- Nozzle Systems Hybrid Rocket Propulsion
- Fundamental Solid Propulsion Technologies LIQUID ROCKET PROPUL-

SION SYSTEMS LH₂/LOX Based

- RP/LOX Based CH₄/LOX Based
- Detonation Wave Engines (Closed Cycle)
- Propellants Fundamental Liquid
- Propulsion Technologies AIR BREATHING

PROPULSION SYSTEMS

- TBCC RBCC
- Detonation Wave Engines (Open Cycle) Turbine Based Jet Engines
- (Flyback Boosters) Ramjet/Scramjet Engines
- (Accelerators) Deeply-cooled Air Cycles
- Air Collection & **Enrichment System**
- Fundamental Air Breathing Propulsion Technologies ANCILLARY PROPULSION

SYSTEMS Auxiliary Control Systems

- Main Propulsion Systems (Excluding Engines)
 - Launch Abort Systems Thrust Vector Control Systems
- Health Management & Sensors
- Pyro & Separation Systems Power Management & Fundamental Ancillary Propulsion Technologies **DISTRIBUTION**

UNCONVENTIONAL / OTHER PROPULSION SYSTEMS

- Ground Launch Assist
- Air Launch / Drop Systems Space Tether Assist
- Beamed Energy / Energy Cross Cutting Nuclear
- High Energy Density

SYSTEMS

SENSING & PERCEPTION

Terrain Mapping, Classification & Characterization

Natural & Man-made Object Recognition

Onboard Science Data Analysis

- Above-Surface Mobility
- Mobility MANIPUL ATION

Robot Arms

- Dynamics
- Robotic Drilling & Sample

PROPULSION TECHNOLOGIES INTEGRATION • Beamed Energy Propulsion

- Systems Interaction
- Intent Recognition &
- ommon Human-Systems
- Safety, Trust, & Interfacing of Robotic Human Proximity

TAO3 · SPACE POWER & **ENERGY STORAGE**

Power Generation

- Energy Harvesting hemical (Fuel Cells, Heat
- Radioisotope Fission
- Fusion

ENERGY STORAGE Batteries

lvwheel egenerative Fuel Cells

FDIR

- Management & Control Distribution & Tra
- Wireless Power
- Conversion & Regulation
- TECHNOLOGY
- Analytical Tools • Green Energy Impact
- Multi-functional Structures Alternative Fuels

TA04 * ROBOTICS, **ROBOTICS & AUTONOMOUS**

Relative Position & Velocity

Estimation

Sensor Fusion for Sampling

MOBILITY

- Extreme Terrain Mobility Below-Surface Mobility
- Small Body/Microgravity

- Modeling of Contact
- obile Manipulation ollaborative Manipulatio

HUMAN-SYSTEMS

- Multi-Modal Human-
- Robot-to-Suit Interfaces
- Distributed Collaboration

AUTONOMY

 Vehicle Systems Management & FDIR

 Dynamic Planning & Sequencing Tools Autonomous Guidance &

ontrol Multi-Agent Coordination Adjustable Autonomy

Terrain Relative Navigation Path & Motion Planning ith Uncertainty

AUTONOMOUS RENDEZVOUS & Docking

Relative Navigation Sensor ong-, mid-, near-range)

 Guidance Algorithms Docking & Capture

 Mission/System Managers for Autonomy/Automation

RTA Systems Engineering • Modularity/Commonality Verification & Validation of

Complex Adaptive Systems Onboard Computing

TA05 • COMMUNICA COMMUNICATION

OPTICAL COMM. & NAVIGATION

- Detector Development Large Apertures
- Acquisition & Tracking · Atmospheric Mitigation

RADIO FREQUENCY COMMUNICATIONS

- ower Efficient Technologies Propagation
- Flight & Ground Systems • Earth Launch & Reentry Comm.

- Adaptive Network Topology
- Position, Navigation, and Timing
- Onboard Auto Navigation & Maneuver • Sensors & Vision Processing Systems
- Relative & Proximity Navigation Auto Precision Formation Flying Auto Approach & Landing
- Radio Systems
- Jltra Wideband Cognitive Networks Science from the Comm. System

Navigation Sensors RF/Öptical Hybrid Technology

- REVOLUTIONARY CONCEPTS X-Ray Navigation
- X-Ray Communications Neutrino-Based Nav. & Tracking Quantum Key Distribution
- Quantum Communications SOIF Microwave Amplifier • Reconfigurable Large Apertures

Using Nanosat Constellations TA06 • HUMAN HEALTH, LIFE SUPPORT & **HABITATION SYSTEMS**

ENVIRONMENTAL CONTROL & LIFE SUPPORT SYSTEMS &

HABITATION SYSTEMS Air Revitalization

Water Recovery & Management Habitation

EXTRAVEHICULAR ACTIVITY SYSTEMS

 Pressure Garment • Portable Life Support System • Power, Avionics & Software

HUMAN HEALTH & PERFORMANCE

 Medical Diagnosis / Prognosis ong-Duration Health Behavioral Health Human Factors

ENVIRONMENTAL MONITORING. SAFETY & EMERGENCY RESPONSE

• Sensors: Air, Water, Microbial, etc. Fire: Detection, Suppression, Recover Protective Clothing / Breathing Remediation

RADIATION

Radiation Mitigation

- Protection Systems • Radiation prediction
- Monitoring Technology Note: Evaluation is based upon competitive, commercial market potential over next decade and thus must demonstrate





TA07 · HUMAN EXPLORATION **DESTINATION SYSTEMS**

In-SITU RESOURCE UTILIZATION Destination Reconnaissance,

Prospecting, & Mapping Resource Acquisition Consumables Production

 Manufacturing Products & Infrastructure Emplacement SUSTAINABILITY &

SUPPORTABILITY Autonomous Logistics Management

Maintenance Systems

 Repair Systems Food Production, Processing. & Preservation

"ADVANCED" HUMAN MOBILITY Systems

- EVA Mobility
- "ADVANCED" HABITAT SYSTEMS • Integrated Habitat Systems Habitat Evolution

· "Smart" Habitats

Crew Training Planetary Safety Integrated Flight Operations

• Integrated Risk Assessment Tools

CROSS-CUTTING SYSTEMS Construction & Assembly

TAO8 · SCIENCE INSTRUMENTS, **OBSERVATORIES & SENSOR**

REMOTE SENSING INSTRUMENTS/SENSORS

• Detectors & Focal Planes Electronics • Optical Components

Microwave / Radio Lasers Cryogenic / Thermal

- Mirror Systems Structures & Antennas
- IN-SITU INSTRUMENTS/SENSOR • Particles: Charged & Neutral

In-Situ





Deployable Hypersonic Decelerators DESCENT • Attached Deployable Decelerators Trailing Deployable Decelerators

• Touchdown Systems

Propulsion Systems Small Body Systems

- System Integration and Analyses Atmosphere & surface characterization
- Instrumentation and Health Monitoring • GN&C Sensors and Systems

TA10 : NANO-TECHNOLOGY • NANO-

ENGINEERED MATERIALS &

- Damage Tolerant System Coatings
- Thermal Protection & Control **ENERGY GENERATION & STORAGE**

PROPULSION

STRUCTURES

Lightweight Structures

- In-Space Propulsion SENSORS, ELECTRONICS &
- **DEVICES** Sensors & Actuators



MODELING. SIMULATION. INFORMATION TECHNOLOGY & PROCESSING

COMPLITING

- Flight Computing
- Ground Computing Modeling
- Software Modeling & Model-Checki Integrated Hardware & Software
- Modeling Human-System Performance Modeling Science Modeling

rameworks, Languages, Tools &

SIMULATION

- Distributed Simulation Integrated System Lifecycle Simulatio
- Simulation-Based Systems Engineer Simulation-Based Training & Decision Support System

Science, Engineering & Mission Data

Lifecvcle Intelligent Data Understandi

INFORMATION PROCESSING

Collaborative Science & Engineering Advanced Mission Systems

TA12 • MATERIALS STRUCTURES **MECHANICAL SYSTEMS & MANUFACTURING**

MATERIALS.

- Environment
- **S**TRUCTURES Design & Certification Methods

Computational Design

- Test Tools & Methods Innovative, Multifunctional Concepts MECHANICAL SYSTEMS • Deployables, Docking and Interfa
- Mechanism Life Extension Systems Electro-mechanical, Mechanical & Design & Analysis Tools and Methods Reliability / Life Assessment / Health
- Monitoring Certification Methods
- MANUFACTURING Manufacturing Processes Intelligent Integrated Manufacturing and Cyber Physical Systems
- Electronics & Optics Manufacturing rocess Sustainable Manufacturing

CROSS-CUTTING

Model-Based Certification & Sustainment Methods

TA13 GROUN GROUND &

- Storage, Distribution & Conservation of Fluids
- Coupling, & Assembly Systems
 - · Formation Flight
 - VSTOL/ESTOL • Reduce/Mitigate Sonic Boom • Multidisciplinary Design &

Analysis Tools Efficient Hypersonic Aero

- PROPULSION AND POWER • Ouiet Propulsion
- Ultraclean Propulsion & Alternative Fuels Fuel Efficiency
- Propulsion for STOL/VTOL Supersonic Propulsion Combined Cycle Hypersonic
- Aero-Propulsion-Servo-Elasticity Robust Propulsion
- Hybrid Propulsion and Power Variable Cycle Advanced Concepts
- Alternative Engine Cycles Intelligent Engine Integrated Power Management
- DYNAMICS, CONTROL, NAVIGATION, GUIDANCE, AND AVIONICS Advanced Guidance
- Distributed Decision Uncertainty, &Flight Path Distributed Flow Control of
- Vehicle Dynamics Intelligent & AdaptiveFault-Tolerant IVHM
- On-Board Weather Synthetic & Enhanced Vision

Advanced V&V Techniques

- Load, Vibration & Stability Control Advanced Communications INTELLIGENT & HUMAN INTEGRATED SYSTEMS. OPS.
- DECISION MAKING & NETWORKING • Complex Interactive Systems Separation Assurance
- Wake Vortex systems Architecture Vulnerability Analysis for Air Traffic Control
- Adaptive Air Traffic Control for Adverse Weather Collaborative Decision Systems Operational Maintenance Data
- Task & Attention Management Environmentally Friendly Aviation
- Super Density Operations

JSC SUPPLEMENTAL DATA

National Aeronautics and

Space Administration

TA16 • ORBITAL DEBRIS AND HYPERVELOCITY IMPACT

ORBITAL DEBRIS

- Modeling
- Monitoring • Mitigation
- HYPERVELOCITY IMPACT
- A17 · EMERGING TECHNOLOGIES

Space Technology Roadmaps STR • TABS **TECHNOLOGY AREA BREAKDOWN STRUCTURE**

Spectrum Efficient Technologi

INTERNETWORKING

- Integrated Network Management
- Timekeeping & Time Distribution
- INTEGRATED TECHNOLOGIES
- Hybrid Optical Comm. &
 - Surface Mobility Off-Surface Mobility

Artificial Gravity MISSION OPERATIONS & SAFETY

- Systems
- Particulate Contamination Prevention & Mitigation

SYSTEMS

- **O**BSERVATORIES
- Distributed Aperture
- Fields & Waves





• Supersonic Retropropulsion LANDING

Rigid Thermal Protection Systems

Rigid Hypersonic Decelerators

Egress & Deployment Systems

- VEHICLE SYSTEMS TECHNOLOGY • Separation Systems
- Modeling and Simulation

Energy Storage Energy Generatio

 Propellants Propulsion Components









Reliability & Sustainment

SYSTEMS PROCESSING

TECHNOLOGIES TO OPTIMIZE THE OPERATIONAL LIFE-CYCLE

Integrated Vehicle / Ground

ENVIRONMENTAL AND GREEN

Detection, & Mitigation

Alternate Energy Prototypes

TECHNOLOGIES TO INCREASE

• Advanced Launch Technologies

Inspection, Anomaly Detection

Fault Isolation and Diagnostics

Communications, Networking,

MISSION SAFETY/MISSION RISK

• Range Tracking, Surveillance &

Flight Safety Technologies

TA14 • THERMAL MANAGEMENT

Landing & Recovery Systems

& Components

Mitigation

Safety Systems

SYSTEMS

Weather Prediction and

Robotics / Telerobotics

CRYOGENIC SYSTEMS

• Heat Acquisition

Heat Transfer

Passive Thermal Control

Integration & Modeling

Heat Rejection & Energy

• Entry / Ascent TPS

& Radiative)

Technologies

Active Thermal Contro

THERMAL CONTROL SYSTEMS

THERMAL PROTECTION SYSTEMS

Plume Shielding (Convective)

Sensor Systems & Measurement

Materials and Structures

RELIABILITY AND MISSION

Environment-Hardened

Prognostics Technolo

Timing & Telemetry

Technologies to Improve

Recovery Technologies

• Repair, Mitigation, and

& Identification

nvironmental Remediation &

Preservation of Natural Eco-

TECHNOLOGIES

AVAILABILITY

Corrosion Prevention

ite Restoration

- Novel Configurations Propulsion Airframe Aeroacoustics Automated Alignment,
- Computational Methods Robust Aero Autonomous Command & Control for Ground and

AFROSCIENCES

Drag Reduction

Propulsion Airframe Integration

- Experimental Investigations Wake Vortex

REVISED-08/10/12

PARTNERSHIP POTENTIAL – JSC PERSPECTIVE

National Aeronautics and Space Administration



OFFICIAL NASA ROADMAPS











CHEMICAL PROPULSION

Cold Gas/Warm Gas

Electric Propulsion

Solar Sail Propulsion

• Thermal Propulsion

ADVANCED (TRL <3)

• Fusion Propulsion

Advanced Fission

Materials

High Energy Density

• Breakthrough Propulsion

SUPPORTING TECHNOLOGIES

• Antimatter Propulsion

Propellant Storage &

Tether Propulsion

Non-Chémical Propulsion

• Micro-propulsion

• Liquid Storable

Solid

Hybrid



SOLID ROCKET PROPULSION

- Systems
- Propellants
- Case Materials
- Nozzle Systems Hybrid Rocket Propulsion
- Systems Fundamental Solid Propulsion Technologies

LIQUID ROCKET PROPUL-

- SION SYSTEMS
- LH₂/LOX Based RP/LOX Based
- CH₄/LOX Based
- Detonation Wave Engines (Closed Cycle)
- Propellants
- Fundamental Liquid Propulsion Technologies

AIR BREATHING PROPULSION SYSTEMS

- TBCC
- RBCC Detonation Wave Engines
- (Open Cycle) Turbine Based Jet Engines
- (Flyback Boosters) Ramjet/Scramjet Engines
- (Accelerators) Deeply-cooled Air Cycles
- Air Collection & Enrichment System
- Fundamental Air Breathing Propulsion Technologies ANCILLARY PROPULSION

SYSTEMS Auxiliary Control Systems

- Main Propulsion Systems (Excluding Engines)
- Launch Abort Systems Fusion Thrust Vector Control
- Systems Health Management &
- Pyro & Separation Systems Fundamental Ancillary Propulsion Technologies **DISTRIBUTION**

UNCONVENTIONAL / OTHER FDIR PROPULSION SYSTEMS

- Ground Launch Assist Air Launch / Drop Systems
- Space Tether Assist
- Beamed Energy / Energy Addition
- Nuclear
- High Energy Density Materials/Propellants

REVISED-08/14/12

TA04 * ROBOTICS, TELE-**ROBOTICS & AUTONOMOUS** SYSTEMS

SENSING & PERCEPTION

- 3-D Perception Relative Position & Velocity
- Estimation Terrain Mapping, Classification
- & Characterization
- Natural & Man-made Object Recognition
- Sensor Fusion for Sampling & Manipulation

Onboard Science Data MOBILITY

Analysis

- Extreme Terrain Mobility Below-Surface Mobility
- Above-Surface Mobility Small Body/Microgravity

Mobility

MANIPUL ATION

- Robot Arms Modeling of Contact
- Dynamics
- Mobile Manipulation Robotic Drilling & Sample

HUMAN-SYSTEMS PROPULSION TECHNOLOGIES INTEGRATION

- Beamed Energy Propulsion • Multi-Modal Human- Electric Sail Propulsion Systems Interaction
 - Robot-to-Suit Interfaces
 - Intent Recognition &
 - Distributed Collaboration Common Human-Systems Interfaces
 - Safety, Trust, & Interfacing of Robotic/ Human Proximity Operations

Dynamic Planning &

ontrol

Sequencing Tools

Autonomous Guidance &

Multi-Agent Coordination Adjustable Autonomy

Terrain Relative Navigation

Path & Motion Planning

AUTONOMOUS RENDEZVOUS

• Relative Navigation Sensors

(long-, mid-, near-range)

ith Uncertainty

TAO3 · SPACE POWER & AUTONOMY • Vehicle Systems **ENERGY STORAGE** Management & FDIR

Power Generation

- Energy Harvesting
- Radioisotope
- Fission
- **ENERGY STORAGE**

Flywheels

 Regenerative Fuel Cells Power Management &

Wireless Power

Transmission

Cross Cutting

• Analytical Tools

• Alternative Fuels

• Green Energy Impact

TECHNOLOGY

Management & Control

Conversion & Regulatio

Multi-functional Structures

iidance Algorithms ocking & Capture Mission/System Managers

& Docking

- for Autonomy/Automation RTA Systems Engineering
- Modularity/Commonality Verification & Validation o
- omplex Adaptive Systems

Onboard Computing

TA05 • COMMUNICA & NAVIGATION COMMUNICATION

OPTICAL COMM. & NAVIGATION

- Detector Development Large Apertures
- Acquisition & Tracking Atmospheric Mitigation

RADIO FREQUENCY COMMUNICATIONS

- Spectrum Efficient Technologies Power Efficient Technologies Propagation
- Flight & Ground Systems Earth Launch & Reentry Comm. Antennas

INTERNETWORKING

- Disruptive Tolerant Networking Adaptive Network Topology Information Assurance
- Integrated Network Management Position, Navigation, and Timing Timekeeping & Time Distribution
- Onboard Auto Navigation & • Sensors & Vision Processing Systems
- Auto Precision Formation Flying Auto Approach & Landing
- INTEGRATED TECHNOLOGIES • Radio Systems
- Ultra Wideband Cognitive Networks Science from the Comm. System Hybrid Optical Comm. &

• RF/Optical Hybrid Technology

- REVOLUTIONARY CONCEPTS X-Ray Navigation
- X-Ray Communications Neutrino-Based Nav. & Tracking Quantum Key Distribution
- Quantum Communications SOIF Microwave Amplifier
- Reconfigurable Large Apertures Using Nanosat Constellations

TA06 • HUMAN HEALTH, LIFE SUPPORT & **HABITATION SYSTEMS**

ENVIRONMENTAL CONTROL & LIFE SUPPORT SYSTEMS & HABITATION SYSTEMS

- Air Revitalization Water Recovery & Managemen
- Habitation

EXTRAVEHICULAR ACTIVITY SYSTEMS

- Power, Avionics & Software
- HUMAN HEALTH & PERFORMANCE
- Medical Diagnosis / Prognosis Long-Duration Health ehavioral Health

ENVIRONMENTAL MONITORING. SAFETY & EMERGENCY RESPONSE

Remediation RADIATION

- Risk Assessment Modeling
- Radiation prediction







TA07 • HUMAN EXPLORATION **DESTINATION SYSTEMS**

- In-SITU RESOURCE UTILIZATION Destination Reconnaissance,
- Prospecting, & Mapping Resource Acquisition
 Consumables Production
- Manufacturing Products & Infrastructure Emplacement
- SUSTAINABILITY & SUPPORTABILITY • Autonomous Logistics

Repair Systems

Management Maintenance System

Food Production, Processing, & Preservation "ADVANCED" HUMAN MOBILITY Systems

- EVA Mobility
- Surface Mobility Off-Surface Mobility
- Integrated Habitat Systems Habitat Evolutio Smart" Habitate

Artificial Gravity MISSION OPERATIONS & SAFETY

"ADVANCED" HABITAT SYSTEMS

- Planetary Safety
- Integrated Flight Operations • Integrated Risk Assessment Tools
- CROSS-CUTTING SYSTEMS Construction & Assembly
- Particulate Contamination Prevention & Mitigation

TAO8 · SCIENCE INSTRUMENTS, **OBSERVATORIES & SENSOR**

REMOTE SENSING INSTRUMENTS/SENSORS

• Detectors & Focal Planes

- Electronics • Optical Components Microwave / Radio
- Lasers Cryogenic / Thermal

OBSERVATORIES Mirror Systems

- Structures & Antennas Distributed Aperture IN-SITU INSTRUMENTS/SENSOR • Particles: Charged & Neutral
- Fields & Waves In-Situ

TA09 ENTRY, DESCENT & ANDING SYSTEMS

AFROASSIST &

- ATMOSPHERIC ENTRY Rigid Thermal Protection System lexible Thermal Protection
- Rigid Hypersonic Decelerators • Deployable Hypersonic Decelerators

DESCENT

- Attached Deployable Decelerators Trailing Deployable Decelerators • Supersonic Retropropulsion
- Touchdown Systems

- System Integration and Analyses • Atmosphere & surface
- Modeling and Simulati nstrumentation and Health

TA10 · NANO-

ENGINEERED MATERIALS & STRUCTURES Lightweight Structures

 Coatings Adhesives Thermal Protection & Contro

ENERGY GENERATION & STORAGE Energy Storage

Energy Generatio **PROPULSION**

- Propellants Propulsion Components
- In-Space Propulsion SENSORS, ELECTRONICS &
- **DEVICES** Sensors & Actuators Nanoelectronics





MODELING. SIMULATION. INFORMATION TECHNOLOGY & PROCESSING

COMPUTING

- Flight Computing
- Ground Computing Modeling
- Integrated Hardware & Software Human-System Performance Modeling

Science Modeling

• Software Modeling & Model-Checki

SIMULATION

- Distributed Simulation Integrated System Lifecycle Simulation
- Simulation-Based Systems Engineer Simulation-Based Training & Decision Support System

INFORMATION PROCESSING

- Science, Engineering & Mission Data Lifecvcle
- Intelligent Data Understanding
- Collaborative Science & Engineering Advanced Mission Systems

TA12 • MATERIALS STRUCTURES **MECHANICAL SYSTEMS & MANUFACTURING**

MATERIALS.

Computational Design Flexible Material Systems Environment

Reliability & Sustainment

MECHANICAL SYSTEMS • Deployables, Docking and Interfaces

- Electro-mechanical, Mechanical & Micromechanisms
- Reliability / Life Assessment / Health Monitoring Certification Methods

and Cyber Physical Systems Electronics & Optics Manufacturing Process

Sustainable Manufacturing CROSS-CUTTING

- Model-Based Certification & Sustainment Methods
- Loads and Environments

TA13 GROUN GROUND & SYSTEMS PROCESSING

TECHNOLOGIES TO OPTIMIZE THE OPERATIONAL LIFE-CYCLE

Control for Ground and

ENVIRONMENTAL AND GREEN

Detection, & Mitigation

• Preservation of Natural Eco

Alternate Energy Prototypes

TECHNOLOGIES TO INCREASE

RELIABILITY AND MISSION

Environment-Hardened

& Îdentification

Materials and Structures

Fault Isolation and Diagno

Prognostics Technologies

Recovery Technologies

Communications, Networking,

MISSION SAFETY/MISSION RISK

• Range Tracking, Surveillance &

Flight Safety Technologies

TA14 • THERMAL MANAGEMENT

Landing & Recovery Systems

& Components

Mitigation

Safety Systems

SYSTEMS

Weather Prediction and

Robotics / Telerobotics

CRYOGENIC SYSTEMS

Heat Acquisition

Entry / Ascent TPS

& Radiative)

Technologies

• Passive Thermal Control

• Active Thermal Control

Integration & Modeling

THERMAL CONTROL SYSTEMS

Heat Rejection & Energy

THERMAL PROTECTION SYSTEMS

Plume Shielding (Convective)

Sensor Systems & Measurement

· Repair, Mitigation, and

Timing & Telemetry

Technologies to Improve

Inspection, Anomaly Detection

Environmental Remediation &

TECHNOLOGIES

AVAILABILITY

Corrosion Prevention

Site Restoration

- Storage, Distribution & Automated Alignment,
- acoustics Computational Methods Coupling, & Assembly Systems Robust Aero Autonomous Command & · Formation Flight
- Wake Vortex Integrated Vehicle / Ground VSTOL/ESTOL
 - Reduce/Mitigate Sonic Boom • Multidisciplinary Design & Analysis Tools

• Efficient Hypersonic Aero PROPULSION AND POWER

 Ouiet Propulsion • Ultraclean Propulsion &

AFROSCIENCES

Drag Reduction

Novel Configurations

Propulsion Airframe Aero-

Propulsion Airframe Integration

- Alternative Fuels Fuel Efficiency
- Supersonic Propulsion Combined Cycle Hypersonic

Propulsion for STOL/VTOL

- Aero-Propulsion-Servo-• Advanced Launch Technologies Elasticity Robust Propulsion
 - Hybrid Propulsion and Power Variable Cycle Advanced Concepts/
 - Alternative Engine Cycles Intelligent Engine Integrated Power Management DYNAMICS, CONTROL,

NAVIGATION, GUIDANCE, AND AVIONICS Advanced Guidanc Distributed Decision

- Uncertainty, &Flight Path Distributed Flow Control of Vehicle Dynamics
- Intelligent & AdaptiveFault-Tolerant IVHM On-Board Weather
- ÚAV in the NAS Advanced V&V Techniques Load, Vibration & Stability Control

Synthetic & Enhanced Vision

Advanced Communications INTELLIGENT & HUMAN INTEGRATED SYSTEMS. OPS. DECISION MAKING &

- NETWORKING • Complex Interactive Systems Separation Assurance
- Wake Vortex systems Architecture Vulnerability Analysis for Air Traffic Control Adaptive Air Traffic Control
- for Adverse Weather Collaborative Decision Systems Operational Maintenance Data Task & Attention Management
- Environmentally Friendly Aviation • Super Density Operations

ORBITAL DEBRIS Modeling

TA16 • ORBITAL DEBRIS AND

HYPERVELOCITY IMPACT

- Monitoring • Mitigation

HYPERVELOCITY IMPACT

- Experimental Investigations
- A17 · EMERGING TECHNOLOGIES

Space Technology Roadmaps STR • TABS **TECHNOLOGY AREA BREAKDOWN STRUCTURE**

Pressure Garment SYSTEMS

- Human Factors
- ensors: Air, Water, Microbial, etc. • Fire: Detection, Suppression, Recovery Protective Clothing / Breathing
- Radiation Mitigation rotection Systems







LANDING Egress & Deployment Systems

VEHICLE SYSTEMS TECHNOLOGY

characterization

Monitoring GN&C Sensors and Systems

Damage Ťolerant System

Special Materials **S**TRUCTURES Lightweight ConceptsDesign & Certification Methods

Test Tools & Methods Innovative, Multifunctional Conc

Design & Analysis Tools and Methods

MANUFACTURING Intelligent Integrated Manufacturing











Miniature Instruments



Appendix B

FY'12 Center Innovation Fund Supported Project Charts

FY'12 Center Innovation Fund Supported Projects

JSC Center-Leve	I Internal Re	esearch & D	evelo	pment Proj	ects
Project Title	P.I.	Notional TA Roadmap Crosswalk	CIF FTEs	CIF Procurement / Travel	Notes
Game Changing Augmented Reality Training and Assistance for Maintenance Repair	Lui Wang	4.4, 4.5, 6.3, 7.5	1.00		Leveraged with \$100.0K CM&O Resources
Mini Total Organic Carbon Analyzer (miniTOCA)	Dr. Paul Mudgett	6.1, 6.2, 6.3	0.25		Leveraged with \$100.0K CM&O Resources
Multifunctional Composite Structure Phase II	David R. Lowry	12.2.2	1.00		Leveraged with \$100.0K CM&O Resources
Sensor Risk Mitigation Technology Development for ADR	Anthony Griffith	4, 5, 11	0.85		Leveraged with \$100.0K CM&O Resources
Spacesuit Evaporator-Absorber-Radiator (SEAR)	Grant C. Bue	6	0.40		Leveraged with \$99.3K CM&O Resources
In-Space Manufacturing Development and Demonstration	Michael Waid	12.2	1.00		Leveraged with \$100.0K CM&O Resources
Development of a Wide-Spectrum Organic Analysis Instrument	Scott Messenger	8	0.50		Leveraged with \$85.0K CM&O Resources
Brine Recovery in Containment (BRIC)	Karen D Pickering	6.2.1	1.00		Leveraged with \$100.0K CM&O Resources
Hybrid Li-ion Supercapacitor/Li-ion Battery System for Extended Performance	J. Jeevarajan	2, 3, 4	0.60		Leveraged with \$100.0K CM&O Resources
A Ground Testbed to Advance US Capability in Autonomous Rendezvous and Docking	C D'Souza	4, 5, 11	1.00		Leveraged with \$100.0K CM&O Resources
Active Radiation Shielding Utilizing High Temperature Superconducting Magnets	Shayne Westover	6, 7	1.00		
Miniature Exercise Device (MED)	Cherice Moore	6, 12	1.00		
Multi-Phase Methane Heat Transfer Testing/Modeling for Regenerative Cooling	John "J.C." Melcher	2.1.2.1	1.00		
CIF Total for Center-Level IR&D Projects			10.60	0	Leveraged with \$984.3K CM&O Resources

FY'12 Center Innovation Fund Supported Projects

JSC Directorate-Lev	JSC Directorate-Level Internal Research & Development Projects										
Project Title	P.I.	Notional TA Roadmap Crosswalk	CIF FTEs	CIF Procurement / Travel	Notes						
Multi-Phase Flow Experiment for Suborbital Testing	Katy Hurlbert	2.0, 3.0, 6.0, 7.0, 14.0	0.50		Leveraged with \$50.0K CM&O Resources						
LOX/Methane Regeneratively-Cooled Rocket Engine Development	Robert Morehead	2.1	1.00		Leveraged with \$100.0K CM&O Resources						
Flight Deck of the Future: e-textile iGear Flight Deck of the Future: Virtual Windows	Cory Simon & Helen Neighbors	4.0, 5.0, 6.0, 7.0, 12.1, 12.2, 12.3,	1.40		Leveraged with \$90.0K CM&O Resources						
GeoLab Sample Handling System	Cindy Evans	4.4, 7.4, 8.0, 11.1, 11.2,	0.10		Leveraged with \$25.0K CM&O Resources						
Curation Technology for Future Sample Return Missions	Carlton Allen	7, 8	0.10		Leveraged with \$30.0K CM&O Resources						
Habitat Particle Impact Monitoring System	John Opiela & Eugene Stansbery	7.4, 7.5	0.30		Leveraged with \$40.0K CM&O Resources						
GIS Technology: Resource and Habitability Assessment Tool	Carlton Allen	7.1	0.10		Leveraged with \$20.0K CM&O Resources						
Ionic Monopropellant Contamination and Det.	Mark McClure	2.1	0.10		Leveraged with \$40.0K CM&O Resources						
Microgravity Cell Counter: A Simple Hand-held Low-cost Device for In-flight WBC/Differential	Brian Crucian	6.3	0.34		Leveraged with \$11.1K CM&O Resources						
CIF Total for Directorate-Level IR&D Proje	3.90	0	Leveraged with \$406.1K CM&O Resources								

FY'12 Center Innovation Fund Supported Projects

JSC	Innovation Ch	arge Account	Projec	ets	
Project Title	P.I. Notiona P.I. Roadm Crossw		CIF FTEs	CIF Procurement / Travel	Notes
Electrospray Ionization for Water Monitoring	William T. Wallace	6.4		\$10.0K	
Testbed For Aerothermal Test Technique Development	A. Brandon Oliver	11.3		\$8.0K	
Rocket Fuel Synthesis by Fisher-Tropsch Process	Rama K. Allada	2.1		\$6.4K	
Modeling Limbless Locomotion using ADAMS Software	Prashant S. Rao	11.2		\$10.0K	
Pitch Synchronous Segmentation of Speech Signals	Aniko Sandor	5.2		\$8.5K	
Augmented Reality to Enhance Crew Medical Training	Lui Wang	11.1		\$15.0K	
Parachute Cord Tension Sensor	Satish C. Reddy	9.3		\$10.0K	
Unmanned Micro-g Flight Program	Matthew Hart	11.3		\$10.0K	
Non-Powered Spectrophotometry for Lighting	Toni Anne Clark	Not Applicable to Spring Call		\$9.0K	
Coupled Human-Space Suit Mobility Studies	Lindsay T. Aitchison	Not Applicable to Spring Call		\$10.0K	
A Novel Scheme for Spacecraft Manual Control	Stan G. Love	Not Applicable to Spring Call		\$3.0K	Leveraged with CM&O FTE
Novel Ultrasound Assessment of Dynamic Muscle	Jessica Scott	Not Applicable to Spring Call		\$10.0K	· ·
Crew Health And Recreation Gear Exercise Device	Michael Li	Not Applicable to Spring Call		\$10.0K	
Compact Termination for Structural Soft-goods	Robert Wilkes Jr.	Not Applicable to Spring Call		\$10.0K	
Inside-Out Manufacturing of Composite Structures	Charles S. Hill	Not Applicable to Spring Call		\$6.0K	Leveraged with CM&O FTE
Future Autonomous and Automated Systems Testbed	Angela Lenort	Not Applicable to Spring Call		\$10.0K	
Interface Anywhere	Max Haddock	Not Applicable to Spring Call		\$10.0K	
Gesture Commanding of a Robot with EVA Gloves	Neta Ezer	Not Applicable to Spring Call		\$10.0K	
Stitched Camera Array for Clearance Monitoring	Zachary Drewry	Not Applicable to Spring Call		\$10.0K	
A solar powered, ceramic oxygen concentrator	John Graf	Not Applicable to Spring Call		\$9.2K	
Radiation mitigation theory	Carl Swopes	Not Applicable to Spring Call		\$11.5K	
Instrumented Suit HUT for Ergonomic Assessment	Sudhakar Rajulu	Not Applicable to Spring Call		\$9.3K	Leveraged with CM&O FTE
Textile Strain Gauge for Inflatable Structures	Doug Litteken	Not Applicable to Spring Call		\$7.0K	Leveraged with CM&O FTE
Ion Mobility Spectrometry for Water Monitoring	William T. Wallace	Not Applicable to Spring Call		\$10.0K	
Variable property fluids for dynamic environments	Thomas J Cognata	Not Applicable to Spring Call		\$9.6K	
Nano-Antenna For Terahertz Medical Imaging	Shian Hwu	Not Applicable to Spring Call		\$10.0K	
An Electrochemical Approach to ID Bacteria	Daniel P. Gazda	Not Applicable to Spring Call		\$10.0K	
Integration of Voice and Gesture	David Overland	Not Applicable to Spring Call		\$6.0K	
Dilatant Material For Advanced Exercise Equipment	Phil Callen	Not Applicable to Spring Call		\$8.0K	
Hybrid Windows and Mosaic Video	Helen Neighbors	Not Applicable to Spring Call		\$7.0K	Leveraged with CM&O FTE
Single-sided Temporary Adhesion in Zero-G	George Studor	Not Applicable to Spring Call		\$0.5K	Leveraged with CM&O FTE
CIF Total For ICA Projects			0	\$274.0K	

FTEs: 14.5 CIF Procurement/Travel: \$274.0K

CIF Totals for FY12 Supported Projects at JSC



Appendix C

JSC FY'12 CIF Support Project Details Center-Level IR&D Game Changing Augmented Reality Training and

Assistance for Maintenance Repair

PROJECT MANAGEMENT

Lui Wang / ER; 281-483-8074 & <u>lui.wang-1@nasa.gov</u>

Collaboration: Douglas Wong/SF Human Engineering; Robert Tweety/SD ARED Instructor

Project Overview

Research and Develop Augmented Reality (AR) electronic procedure system (AReProc). Combines Hardware, Software, & Procedure Content to create a new user experience to perform maintenance repair tasks that could dramatically improve human performance and situational awareness.

Relevance / Value to NASA

NASA consistently searches for efficiencies in astronaut training. The portable, AReProc system will:

- Enable self-sustaining autonomous operations
- Increase crew autonomy and reduce crew reliance of ground and electronic paper based procedures
- Increase crew task efficiency and performance
- Reduce human error

Objectives & Outcomes

The objectives were to:

- Improve the robustness of vision tracking and image registration
- Improve the over all system packing, usability and hardware/software
- Assess feasibility to leverage GPGPU supercomputing capability

The outcomes of the project were:

- Identified and evaluated new COTS AR hardware software
- Identified and evaluated new COTS Head Mounted Display technologies
- Refactored AR vision tracking and registration algorithms for GPU based computation

Infusion Potential

The technology will be matured and infused through series of demonstration with increasing fidelity from ISS training facility to on-orbit ISS DTO demonstrations. The ISS Program is striving to minimize crew time spent on training and reliance on ground support for operations.

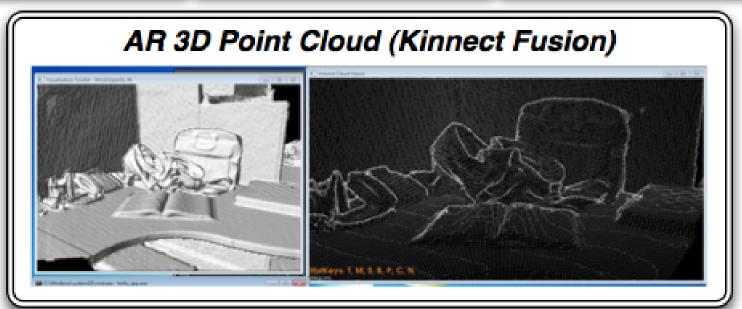
NASA Technology Area Roadmap

- 4.0/4.4 Human Systems Interaction (Just-in-Time human performance support),
- 4.0/4.5 Autonomy (enable crew autonomous operation and reduce dependency on ground support),
- 6.0/6.3 Human Health and Performance (enhance situational awareness, reduce cognitive overload),
- 7.0/7.5 Mission Operations & Safety (reduce human error, improve operational) efficiency).

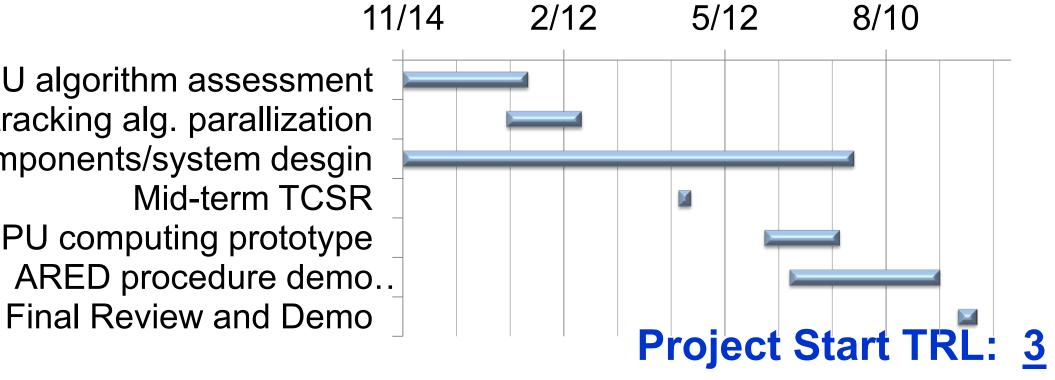


HMD Evaluation - Image Quality Comparison





GPU algorithm assessment Vision tracking alg. parallization AR components/system desgin Mid-term TCSR GPU computing prototype ARED procedure demo...



FinishTRL: 5

Mini Total Organic Carbon Analyzer-TOCA

PROJECT MANAGEMENT

Paul Mudgett/SF2 with Anna Clements/EC3 281-483-8766/paul.d.mudgett@nasa.gov

PROJECT OVERVIEW

 MiniTOCA project seeks to miniaturize and drastically simplify the TOCA water quality monitor to cut consumables, reduce power by 90% and reduce massvolume footprint by 95%.

RELEVANCE/ VALUE TO NASA

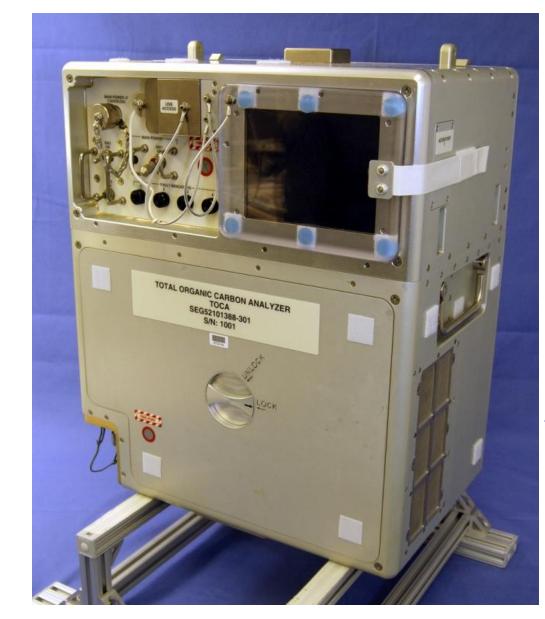
 The water supply on longer term deep space missions will be recycled water. Like on ISS, TOCA is required to verify recycled water purity, but the Exploration TOCA will need to be small (hand-held).

OBJECTIVES & OUTCOMES

- With industry partner OI Analytical of College Station and Bioastronautics staff we are iteratively designing and testing subsystems, breadboarding, then calibrating to analyze water samples.
- The primary product of this first year of development will be a report, but early breadboards may be available for demo.

INFUSION POTENTIAL

- ISS provides a perfect opportunity to validate MiniTOCA using real recycled water as an FY14-15 Tech Demo. This allows time for operational hardware to be built for deep space Exploration missions.
- OI Analytical created a commercial bench top TOCA from the reactor invented during ISS TOCA development. We envision a similar commercial development for a highly miniaturized TOCA.





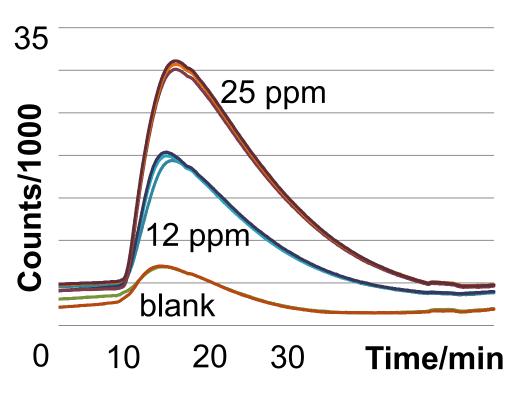


Current State of Art
ISS TOCA

Mass: 34 kg Volume: 67 L Power: 64 W

The Team (L to R)
Karl Williams/OI
Heather Mera/Wyle
Paul Mudgett/NASA
Don Segers/OI
Jeff Milstead/L-M
Eli Williams/OI





Data: TOC solution challenges for Breadboard 2.0

NASA TECHNOLOGY ROADMAP

• This project is directly applicable to TA-06

Human Health, Life Support, and Habitation
Systems, aligning specifically with 6.4

Environmental Monitoring, Safety, and
Emergency Response.

PROJECT DEVELOPMENT SCHEDULE

Major Tasks & Reviews	Nov	Jan	Mar	Apr	Jul	Aug	Sep
Kickoff & Team Meetings	7th	17th	13th	26th	13th	17th	7th
JTWG detailed TCSR #1				17th			
Design & Develop Subsystems							
Test and Optimize Subsystems							
Build & optimize breadboards							
2012 IR&D Poster Session						7th	
Test integrated breadboard 3.0							
Final report & demonstration							
JTWG detailed TCSR #2							27th

Project Start TRL (1-9): 2 Current TRL (1-9): 3

Multifunctional Composite Structure

PROJECT MANAGEMENT

Innovator: David Lowry, JSC ES-2 (281) 483-0272 david.r.lowry@nasa.gov

Collaborators: Dr. Eric Christiansen JSC-KX, Dr. Steven Koontz JSE-ES, Dr. Shantaram Pai, GRC-SXO,

Dr. Ethiraj Venkatapathy ARC-TS, Dr. Alan Parker DRC-RS (Collaborators are on Global)

Composite Sandwich Habitable Pressurized Structure for deep space travel. Permeability, Radiation, & MM/OD shielding are built into the structure; along with fiber optic sensor technology for Structural & Thermal Health Monitoring. 3-D woven fabric and bonded window technologies are being developed in concert for a complete habitable composite system. To enable this technology & help prepare a clear path to certification, material system modeling and probabilistic design & analysis are also being developed.

RELEVANCE/ VALUE TO NASA This project addresses the critical need for multifunctional deep space structure (lightweight, compact, robust, shielding (radiation/MM/OD, Permeability), & informative (Structural health monitoring) as described in the TA-12 Oct Roadmap Report, and confirmed by the NRC.

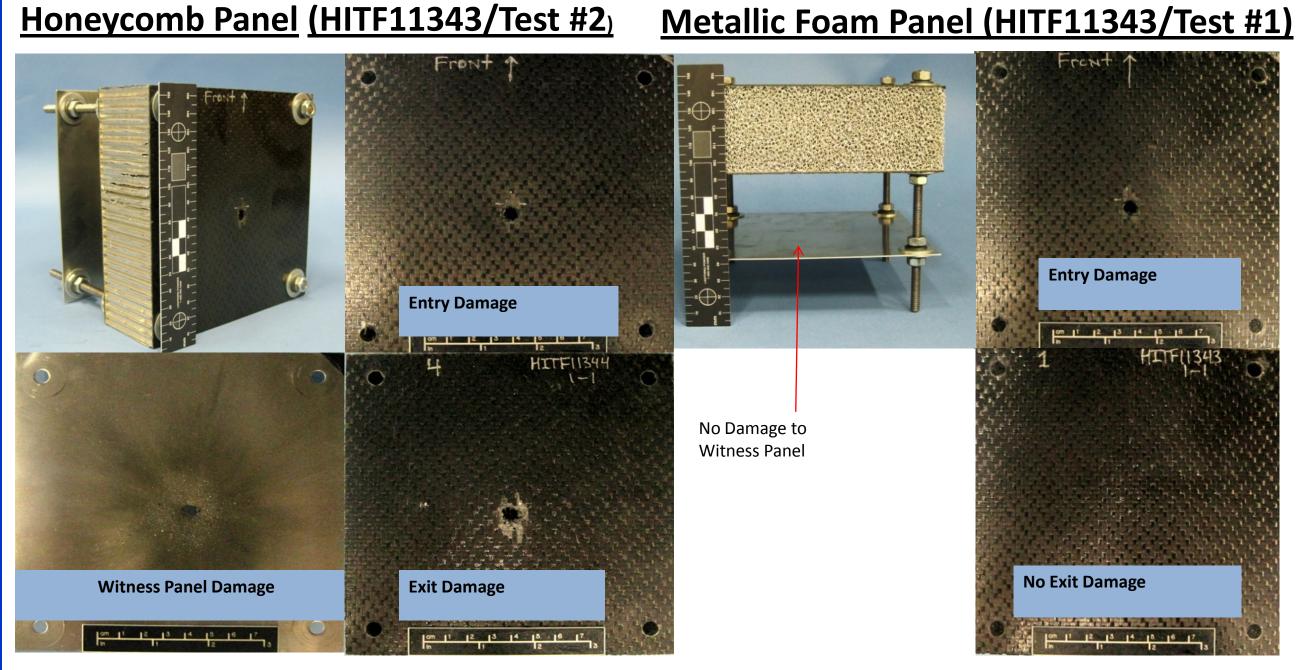
OBJECTIVES & OUTCOMES

On track for a Phase III to narrow parameters during Phase II and then begin producing demonstrators with notable capability at significant weight savings.

Further narrow design parameters to enable TRL advancement toward production

Products include test data, demo hardware, test results, & reports

INFUSION POTENTIAL Part of MMSEV AES, supports DSH AES, tied to DRC test development and ARC Composite Heat shield Development, OCT Composite Heat Shield, Chrysler Motors is working on disclosure agreement and the Navy is interested.

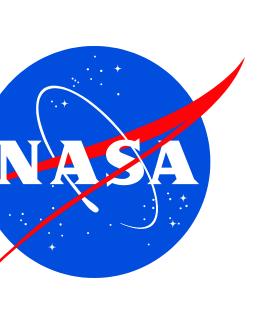


NASA TECHNOLOGY AREA ROADMAP

12.2.2.1.1 Lightweight Concepts (Non-Autoclave Primary Structure)
12.2.2.2.3 Design & Certi Methods (Probabilistic Design/ Rapid Mat'l Dev)
12.2.2.3.3 Reliability & Sustainment (Heath Monitoring-embedded sensors)
12.2.2.5.2 & 6 Innovative, Multifunctional Concepts (Integrated MM/OD /Radiation/Permeability

PROJECT DEVELOPMENT SCHEDULE

Project Development Schedule:	1 st Qtr	2 nd Qtr	3 rd Qtr	4 th Qtr
Structural testing/model correlation (.025 WYE)				
Low ρ Specimen Mfg , Test (0.1 FTE)				
Probabilistic Material Property Dev. (1.0 FTE)				
Formability/Out of Autoclave Dev. (\$1K)				
Radiation Analysis and Testing (\$7K)				
Bonded Windows				
Begin Embedded SHM system (\$20K)				
Mid –Term and Final Reports			.	*



Sensor Risk Mitigation Technology Development for ADR

PROJECT MANAGEMENT

Anthony Griffith, EA3, 281-244-5813, <u>anthony.d.griffith@nasa.gov</u>
Dr. Brian Kent AFRL/RY, (937) 528-8831, <u>brian.kent@wpafb.af.mil</u>
Dr. John Junkins, Texas A&M University, (979) 845-3912, <u>junkins@tamu.edu</u>

PROJECT OVERVIEW

This project is developing and maturing Active Debris Removal (ADR) spacecraft sensors and techniques to dramatically reduce the weight, power, complexity and cost over existing means. The project is producing an autonomous, high speed, and un-tethered air bearing sled system capable of 3-DOF ground testing for this purpose.

RELEVANCE/ VALUE TO NASA

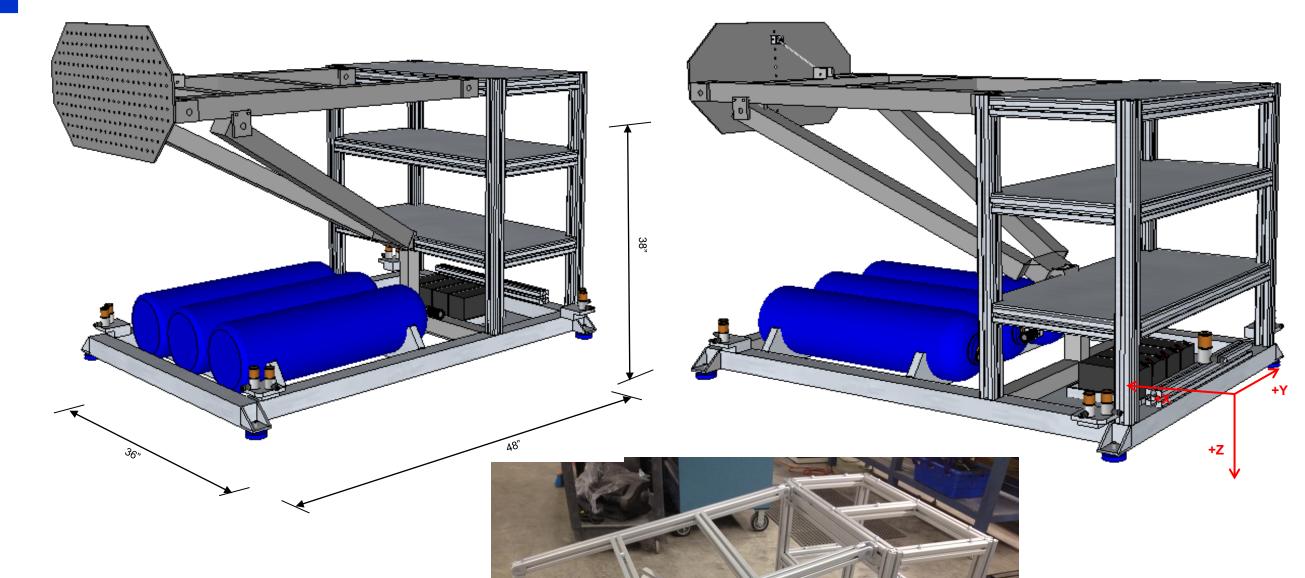
• The sled system has applications far broader than the debris mission – potentially to any vehicle which performs rendezvous and docking operations, particularly to an uncooperative target.

OBJECTIVES & OUTCOMES

- The project has held four TIMs to develop the requirements and systems design of the sled, in cooperation with its development partners
- The principle deliverable for the project is an operational sled, built in JSC B348, ready for air bearing testing beginning in FY13.

INFUSION POTENTIAL

• The testing performed through this project will potentially revolutionize the state of the art regarding Prox Ops sensors. Reducing the cost, weight and complexity of operational remote sensors will allow a fielded system to be operated much more cost effectively and with greater potential for commercialization.



NASA TECHNOLOGY AREA ROADMAP

- Orbital debris is a major concern for national security and in-space mission infrastructure. An operational system requires advances in sensor systems, (TA 4.0.0 and 5.0.0), as well as advancing modeling and processing (TA 11.0.0). JSC Topic and Subtopic(s) Technology Addressed: #3 (3.10) and #1 (1.4)
- By developing ADR technology, JSC will advance the ability for automatic change detection via imagery and greatly reduce the mass needed for the sensor systems.

PROJECT DEVELOPMENT SCHEDULE

	L_	Task Name	Duration	Start	Finish	4th Quarter	1st Quarter	2nd Quarter	3rd Quarter	4th 0
	0					Oct Nov Dec	Jan Feb Mar	Apr May Jun	i Jul Aug	Sep Oct
1	-	Kick-off	1 day	Mon 10/3/11	Mon 10/3/11					
2	1111	Requirements Development	32 days	Tue 10/4/11	Tue 11/15/11	<u> </u>				
3	-	TIM 1 @ JSC(B 348)	1 day	Wed 11/16/11	Wed 11/16/11	<u> </u>				
4		Sensor Design	41 days	Thu 11/17/11	Thu 1/12/12		<u>.</u>			
5	-	TIM2 @ JSC (B 348)	1 day	Mon 1/16/12	Mon 1/16/12		K			
6	H	TCSR#1	0 days	Tue 4/17/12	Tue 4/17/12			4/17		
7	111	Brassboard Sensor Development	105 days	Mon 1/23/12	Fri 6/15/12				_	
8	111	TIM3 @ JSC (B 348)	1 day	Mon 6/18/12	Mon 6/18/12			i i		
9	II.	Brassboard Sensor Testing	52 days	Frl 6/22/12	Mon 9/3/12					
10	111	Final Report Generation	18 days	Mon 9/3/12	Wed 9/26/12					
11	THE STATE OF	Final TCSR	0 days	Thu 9/27/12	Thu 9/27/12					♦ 9/2

Project Start TRL (1-9): 3

Current TRL (1-9): 4

Spacesuit Evaporator-Absorber-Radiator (SEAR)

PROJECT MANAGEMENT

Grant Bue/JSC/EC Scott Cupples/JSC/XA

281.483.5271 281.483.1125

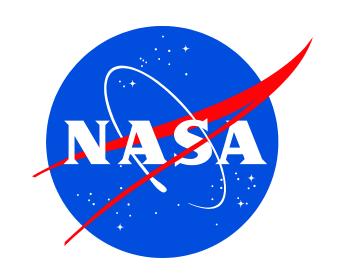
grant.c.bue@nasa.gov j.s.cupples@nasa.gov

Ed Hodgson/HSWL 860.660.2888

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Mike Izenson/Creare 603.640.2405

Weibo Chen/Creare 603.640.2425 wbc@creare.com



PROJECT OVERVIEW

This project combines two proven technologies, Spacesuit Water Membrane Evaporator (SWME) and Lithium Chloride Absorber Radiator (LCAR), into a nonventing system for thermal control. The venting and valving between the technologies was tested in relevant thermal vacuum conditions. A thermal fluid model is being built and correlated to the test data. This model would be used to support a conceptual design of a full scale system for an ISS DTO demonstration. This one of two follow-on projects to FY '11 ICA Sustainability Call: "Liquid Desiccants for Environmental Control."

RELEVANCE/ VALUE TO NASA

For decades NASA JSC has sought a practical method for regenerable, robust non-venting heat rejection: SEAR promises to be such a system

OBJECTIVES & OUTCOMES

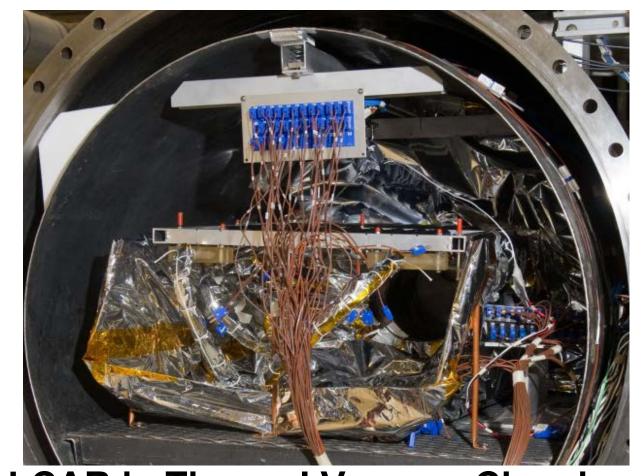
- •Built 1/5 scale radiator, 1/3 scale absorber and combined with SWME
- •Achieved integrated SEAR operation rejecting EVA heat loads with minimal loss of water in relevant thermal vacuum environments
- •Achieved sustained operation with high radiator temperatures and low cooling loop temperatures required for human thermal comfort
- •Performance capability is compatible with anticipated system environments, heat loads, and surface area available for radiator integration
- •Realized significant opportunity for further optimization of design and performance
- •Using model to design a full-scale SEAR system suitable for an ISS DTO

INFUSION POTENTIAL

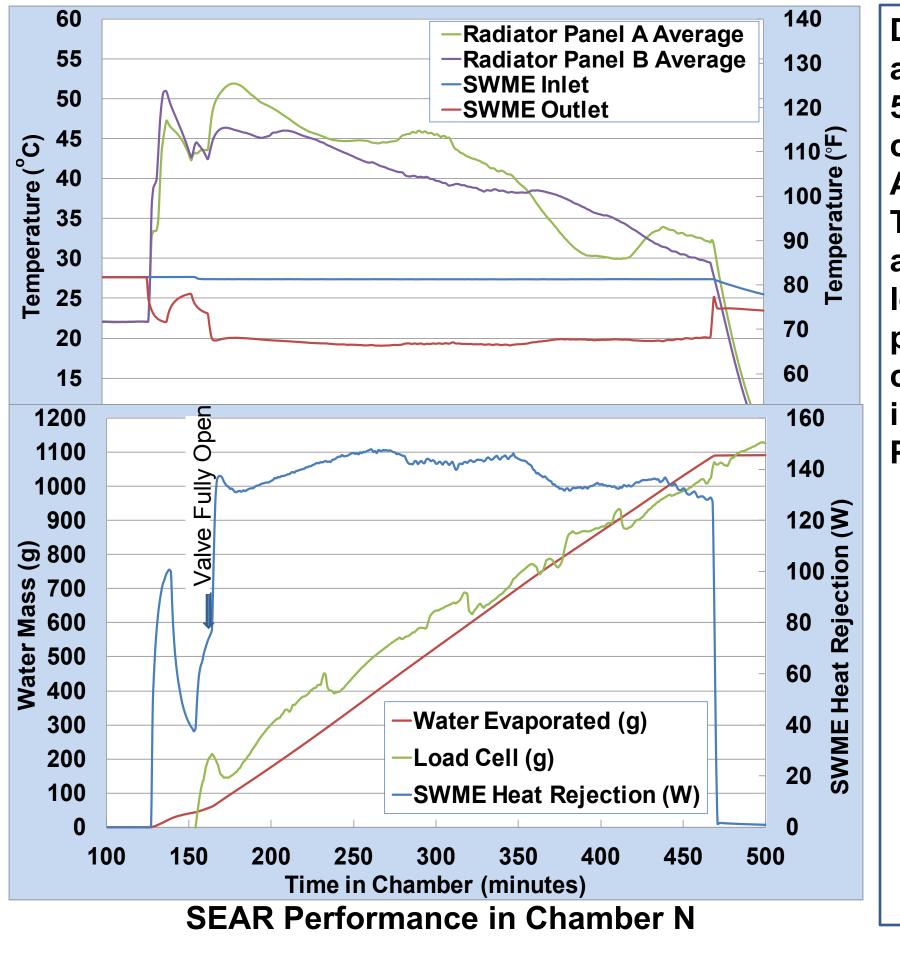
The final ISS DTO product points to future proposals for advancing technology to TRL7. The ISS program would serve as a science platform for the technology while benefiting from reduced consumable use. Technology could then be incorporated multifunctionally into the Advanced Portable Life Support System (PLSS) housing.



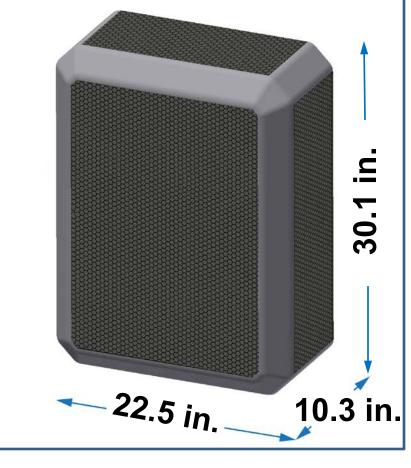
LCAR Test Article



LCAR in Thermal Vacuum Chamber



DTO concept incorporates absorption radiator into a 5-panel honeycomb composite structure in the Advanced PLSS housing. This multifunctional approach provides at least 500W radiation and protects the PLSS components with minimal impact on PLSS and Suit Port design envelopes.



NASA TECHNOLOGY AREA ROADMAP

□ NASA OCT Grand Challenge Addressed: <u>Space Colonization</u>

This non-venting system directly addresses the need for "..effective close-loop systems ..."

NASA Technology Area Roadmap Addressed: Human Health, Life Support and

Habitat ion Systems As an EVA thermal acquisition/rejection system this technology meets the need for "crewed missions venturing beyond LEO will require technologies for high reliability, reduced mass, self-sufficiency, and minimal logistical needs..."

PROJECT DEVELOPMENT SCHEDULE

Final Report (Sep 27)

Creare Form HS
Phase III 90 GSA

Procurement

Test Build-up

Midterm-Report (Apr 17)

Chamber N TherVacTest

Analysis and Correlation

DTO Design, Modeling



In-space Manufacturing & Repair

PROJECT MANAGEMENT

PM: Michael Waid, ES7, 281-483-1257, michael.c.waid@nasa.gov

Karen Taminger, LaRC, 757-864-3131, karen.m.taminger@nasa.gov

JSC Collaborators: EG, ER, EV, EP, KX, NT, DX

PROJECT OVERVIEW

- Develop and Demonstrate Concept of Operations for Inspace Manufacturing & Repair
- Electron Beam Technology for In-space Repair, Joining, and/or Fabrication of Near-Net-Shape Parts
- Integrate using JSC Integrated Power, Avionics, & Software (iPAS) and Dextrous Manipulator Testbed (DMT) Labs

RELEVANCE/ VALUE TO NASA

- Structural Repair of ISS Micrometeoroid Orbital Debris (MMOD) Damage
- Sparing & Contingency Parts on Exploration Missions.

OBJECTIVES & OUTCOMES

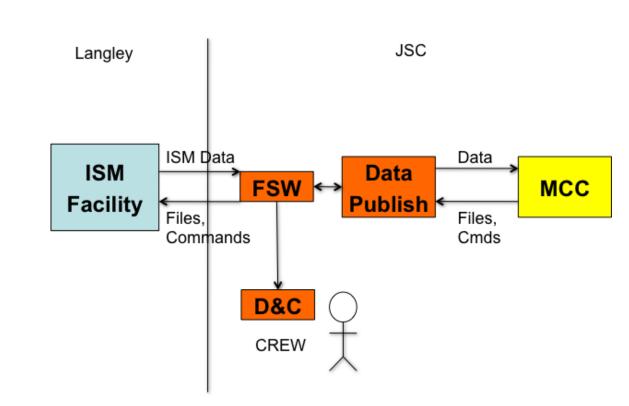
- ISS Repair ConOps, including iGOAL Graphics Simulation
- Remote Electron Beam Manufacturing/Repair iPAS Demo
- DMT Robotics Testing Using Rapid Prototyped E-beam Gun
- Ground Demo of ISS MMOD Damage Repair
- Ground E-beam Material Property Statistical Testing

INFUSION POTENTIAL

- ISS Repair: Mitigate ISS Risk #4669 for Pressurized Module Leaks with E-Beam Repair System
- Advanced Exploration Systems: Supportability for Deep Space Habitat and/or Waypoint Missions

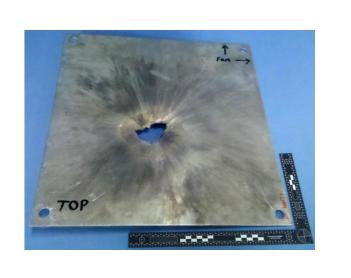


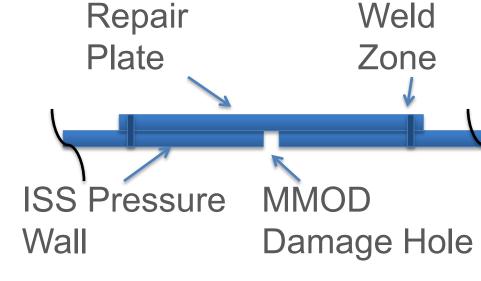




DMT Testing

iPAS Remote Demo Concept







MMOD Test Panel

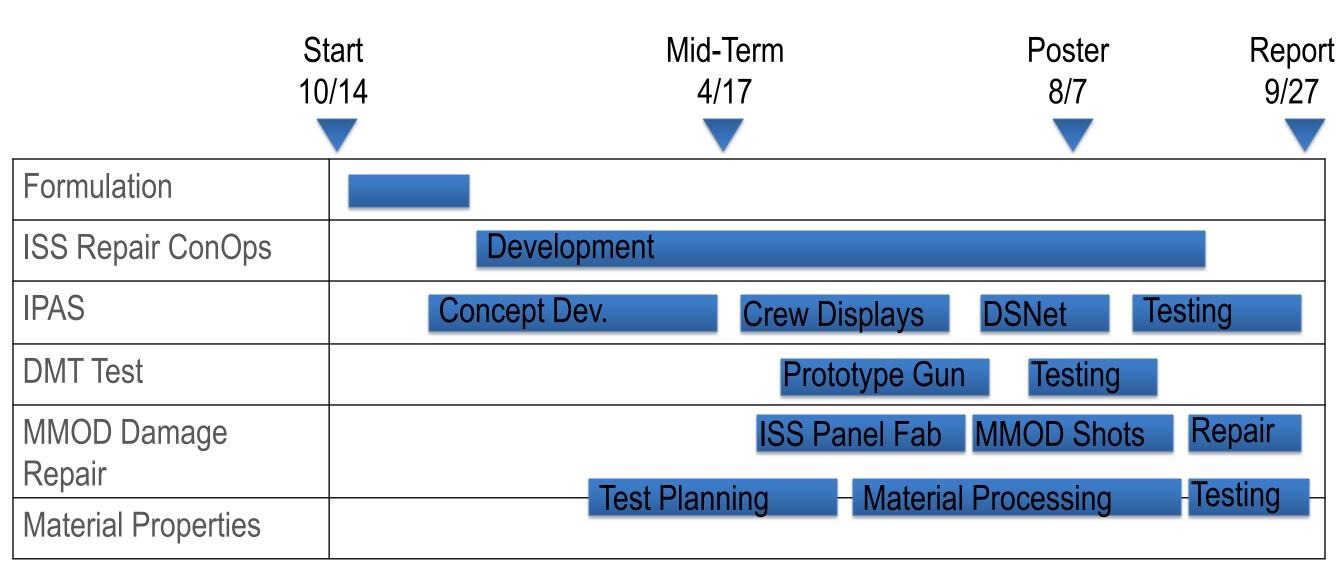
E-beam Structural Repair

Part from E-beam Preform

NASA TECHNOLOGY AREA ROADMAP

•TA12 2.4.1 Manufacturing Processes: In-space Assembly, Fabrication, and Repair

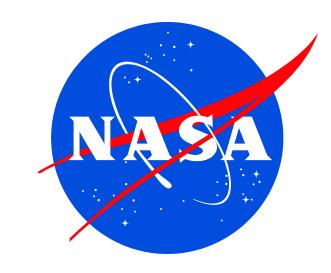
PROJECT DEVELOPMENT SCHEDULE





Current TRL (1-9): 3-4

Wide-Spectrum Organic Analysis Instrument



PROJECT MANAGEMENT

Scott Messenger, KR/ARES & Simon Clemett ESCG/ARES 4-2786; scott.r.messenger@nasa.gov; simon.j.clemett@nasa.gov; Collaborators: Laura Labuda (EC), Stan Love (CB), John James (SF)

PROJECT OVERVIEW

• We designed and constructed a unique laser organic mass spectrometer to organic species with great sensitivity on micrometer spatial scales. The instrument can be used to analyze mixtures of molecules in complex materials without extraction, purification, or other complex sample preparation. With our collaborators at JSC, we will use the instrument in a wide range of applications, beginning with analysis of ISS waste water samples and toxicology studies of asteroidal and lunar dust.

• RELEVANCE/ VALUE TO NASA

• This is a unique instrument with unprecedented analytical capabilities – it will help to maintain the technical and scientific leadership of JSC and NASA and will add value to past, present and future missions.

OBJECTIVES & OUTCOMES

- In FY1 we constructed a Xe-tripling cell that efficiently produces VUV photons. This year we incorporated the VUV source into a two-step laser organic mass spectrometer.
- The resulting instrument measures a wide range of organic molecules with an unprecedented combination of sensitivity and spatial resolution.
 INFUSION POTENTIAL
- We have begun using the instrument in funded research and we will soon begin analysis of NASA mission samples and a wide range of samples from JSC collaborators. The technology is being considered for a patent and may have commercial potential.

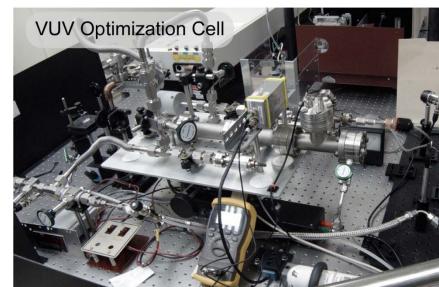
Top L) The Xe tripling cell undergoing testing

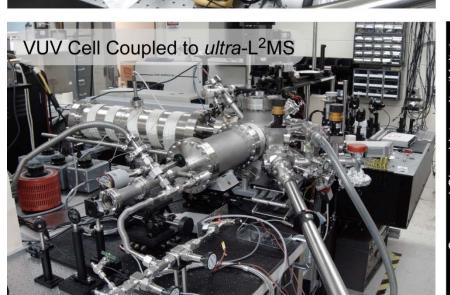
Center L) VUV cell coupled to mass spectrometer

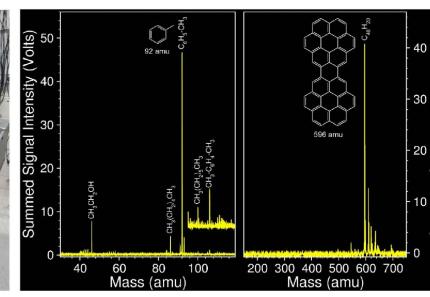
Center R) First mass spectra obtained by VUV ionization

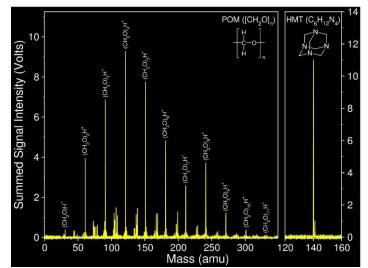
Bottom L) Polymer test materials measured by two-step VUV laser mass spectrometry

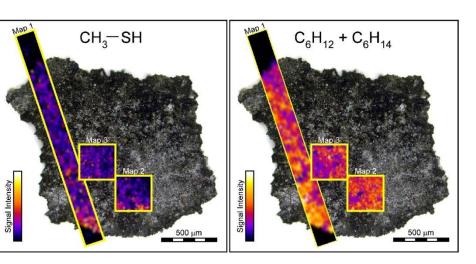
Bottom R) Spatial maps of organic compounds measured in an ancient meteorite with 10 micrometer spatial resolution







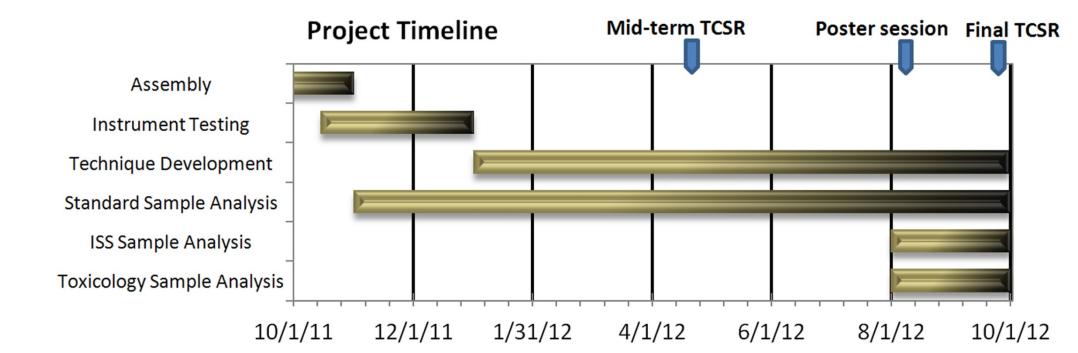


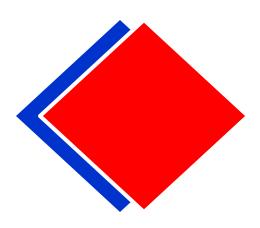


NASA TECHNOLOGY AREA ROADMAP

•TA08/Science Instruments, Observatories, & Sensor Systems: In situ instruments Microscopic organic analysis directly supports planetary science missions, including sample return missions Stardust, Genesis, OSIRIS-REx, and future lunar and Mars sample return missions.

PROJECT DEVELOPMENT SCHEDULE

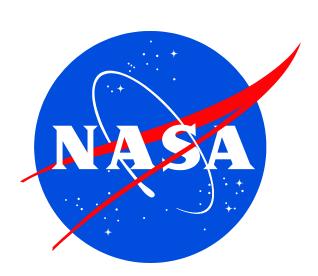




Project Start TRL (1-9): 5

Current TRL (1-9): <u>7</u>

Brine Recovery in Containment (BRIC)



PROJECT MANAGEMENT

Karen Pickering, Ph.D. / EC3. and Torin McCoy/SF2. 281-483-2688, karen.d.pickering@nasa.gov

PROJECT OVERVIEW

•The Brine Residual in Containment (BRIC) project aims to close the water recovery loop by enabling water to be extracted from concentrated wastewater brines. BRIC is based on an in-place drying concept within a sealed disposal container. The design is intended to accommodate the three phases of brine processing, liquid, gas and solid, while reducing the potential for system fouling and exposure of crew to toxic and hazardous brine material. BRIC is described in technology disclosure MSC-24964-1, which will be published in an upcoming issue of NASA Tech Briefs.

RELEVANCE/ VALUE TO NASA

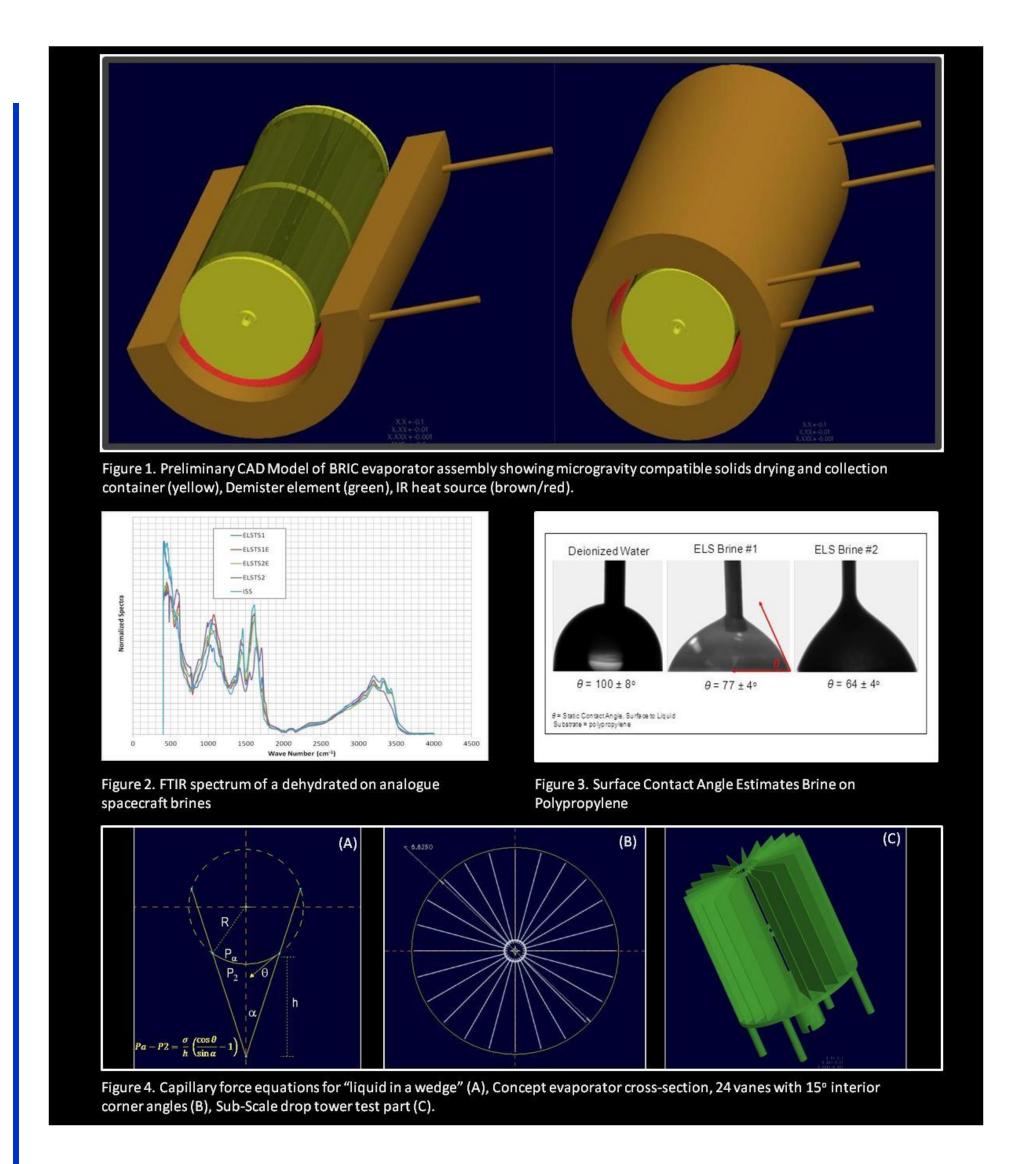
•The NASA OCT Grand Challenge addressed is to Expand human presence in space. The NASA Technology Area Roadmap Addressed is TA06 / Human Health and Habitation Systems, Environmental control and Life Support System.

OBJECTIVES & OUTCOMES

- Characterize physical properties of brines.
- Develop microgravity-compatible evaporator design.

INFUSION POTENTIAL

 The technology will be infused into a system-level environmental control and life support system, support deep-space habitats or other exploration missions. The system will be demonstrated through integrated testing conducted by the AES program.



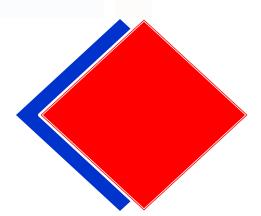
NASA TECHNOLOGY AREA ROADMAP

• Increasing the overall water recovery percentage is identified as a major challenge on Technology Roadmap TA06, WBS 2.1, with a goal of 98% water recovery by 2015. **Goal** *cannot be achieved without brine water recovery.*

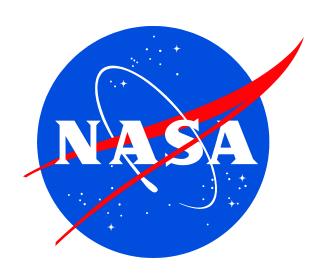
PROJECT DEVELOPMENT SCHEDULE

		2012														
ID	Task Name	Sep	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov
1	Investigate physical properties of brine													35%		
2	Develop process control protocol												7:	5%		
3	MidTerm TCSR								• '	4M7						
4	Develop evaporator subsystem													85%		
5	Review Evaporator Design Concept(s)			·		·							<	\$ 8/31		
6	Final Report													\ \ \ \	9/28	

• Milestones: Mid-term TCSR, 4/17/12; Review Evaporator Design, 8/30/12; Final TCSR 9/27/12.



Hybrid Li-ion Supercapacitor / Li-ion Battery System for Extended Performance



Dr. Judith Jeevarajan, EP5, D.R. Pratt, EP5, J. Graika, EP5, M. Martinez, EP5 and Daniel Harrison, ER4

judith.a.jeevarajan@nasa.gov; 281-483-4528

PROJECT OVERVIEW

- •The lithium-ion supercapacitors with a working voltage of 3.8 V to 2.5 V (can charge up to 4.2 V) can be efficiently used to charge li-ion batteries on an as-needed basis.
- •The li-ion supercapacitors can be store charge from various sources (solar, wind, water) for long periods. The li-ion battery can be reduced to half the capacity (required for nominal EVA) and designed to allow charging of one battery by the supercaps while the other is providing power (to Rover, Suit or other terrestrial applications).

RELEVANCE/ VALUE TO NASA

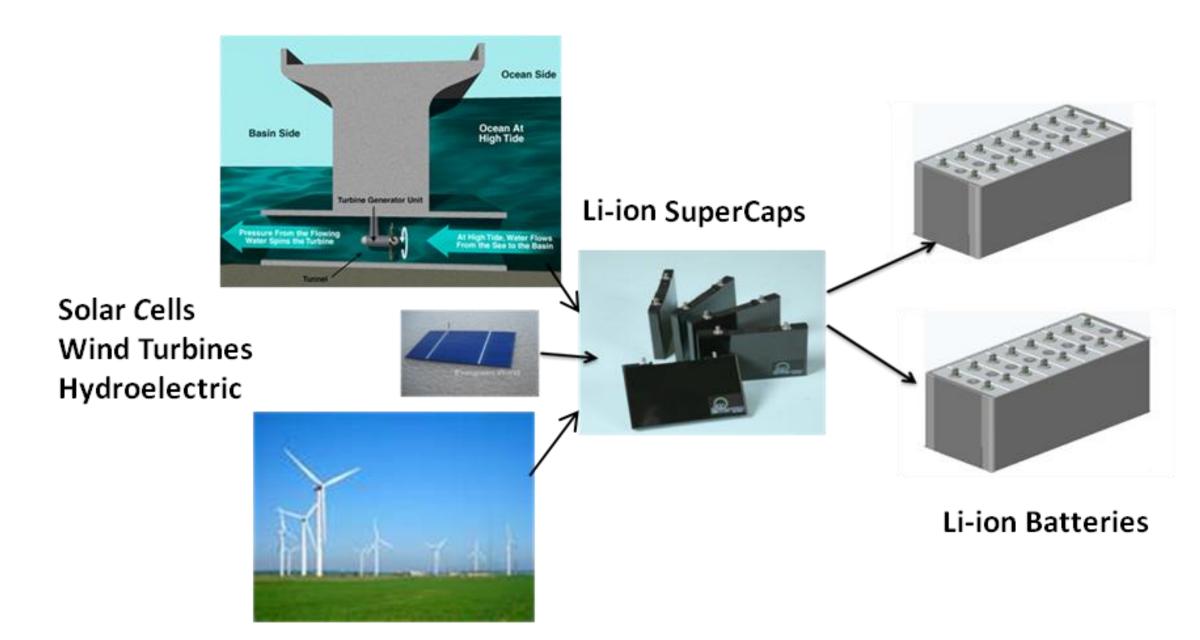
• The use of the supercaps to safely charge batteries extends the period of performance required from a battery while reducing the battery size by half.

OBJECTIVES & OUTCOMES

- Completed supercapacitor performance and safety test.
- Developing and testing supercapacitor /battery modules.

INFUSION POTENTIAL

- The design can be used to reduce the size of the batteries used in the Advanced EVA suit for future NASA space missions. Collaboration has been established with the Robotics and EVA Suit team for technology infusion.
- This can be extended to grid applications (wind energy and energy regeneration/harvesting) as well as to store energy from other sources such as tide (hydroelectric).



NASA TECHNOLOGY AREA ROADMAP

(TA 2 / TA 3 / TA 4) Ultra-high energy density power systems

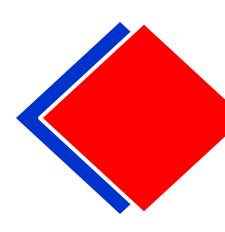
• The energy challenge is to obtain a power system that runs longer, supports high demands and weighs less (<5 kg). This system will provide ultrahigh energy density and longer runtime to safely meet the needs of the future EVA missions.

PROJECT DEVELOPMENT SCHEDULE

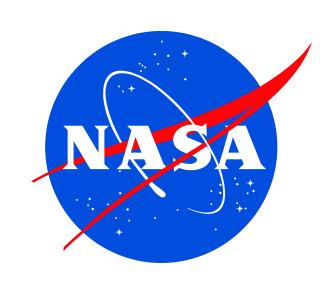
Task	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	July	Aug	Sep
Project start												
Procure Li-ion Capacitors and test												
Circuit board design, supercap module buildup, battery / supercap design buildup												
Mid-Term TCSR												
Test to optimize runtime at IDC												
Field Demo and/or demo in the IDC												
Final system design reporting to EVA and ER and Center IRD Panel												



Current TRL: 4



A Ground Testbed to Advance US Capability in Autonomous Rendezvous and Docking



PROJECT MANAGEMENT

Christopher D'Souza, EG6 (281)483-8246, chris.dsouza@nasa.gov

PROJECT OVERVIEW

 This project will develop the capability to field an AR&D system which can be applied to any mission needing to rendezvous and dock with another vehicle. A ground test-bed comprising algorithms, flight software implemented and tested in a target flight processor and validated with scenarios and missions of interest to NASA has been developed.

RELEVANCE/ VALUE TO NASA

 The US does not have a mature Autonomous Rendezvous and Docking (AR&D) capability, falling behind even our allies in this area; yet it is a cornerstone in any human spaceflight roadmap as we take on the mantle of active debris removal and venture beyond LEO. This effort seeks to remedy this for the Agency.

OBJECTIVES & OUTCOMES

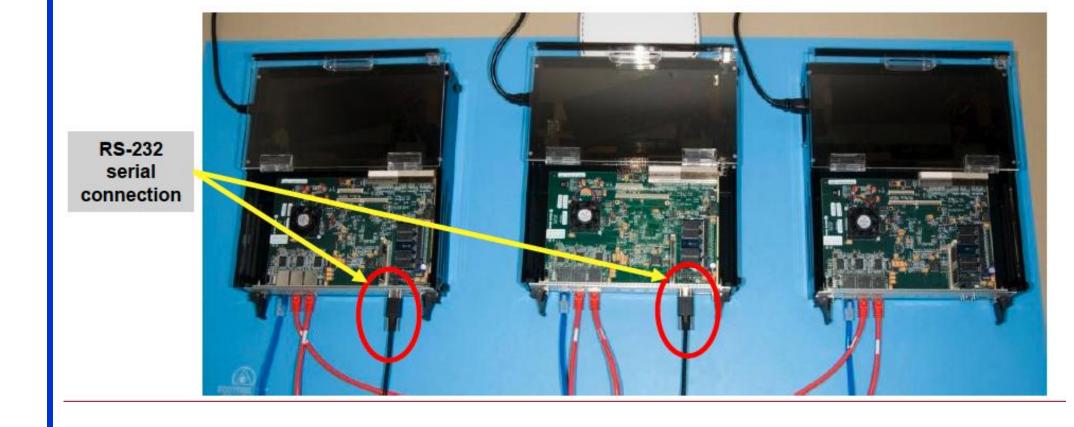
- Implemented AR&D Algorithms and Software on a Target Flight Processor (WR SBC750GX running vxWorks ARINV 653)
- Goal: AR&D Software Integrated into iPAS

INFUSION POTENTIAL

• This project will develop a standardized US capability to provide an 80% solution for any future AR&D mission; the remaining 20% will have to be tailored to suit unique mission needs and constraints. The AR&D FSW will be ready for incorporation into any NASA AR&D mission, whether human or robotic, cooperative or uncooperative, LEO, GEO, NEO, or deep-space.

Wind River (WR) SBC750GX board running vxWorks ARINC 653 platform





NASA TECHNOLOGY AREA ROADMAP

 Project will develop both algorithms (Robotics, Tele-Robotics and Autonomous Systems), incorporate sensors (Communications and Navigation) and simulation software (Modeling, Simulation, Information Technology and Processing) to support development and testing of autonomous rendezvous and docking capability. (WBSL 4.0.0, 5.0.0, 11.0.0)

PROJECT DEVELOPMENT SCHEDULE

Project Development
Oct Nov Dec Jan Feb Mar Apr May Jun Jul Aug Sep
Schedule:
FY12 Project Start
CFS (Core FSW) Develomt
Mid-Term TCSR (4/17/12)

Oct Nov Dec Jan Feb Mar Apr May Jun Jul Aug Sep

Mar Apr May Jun Jul Aug Sep

Oct Nov Dec Jan Feb Mar Apr May Jun Jul Aug Sep

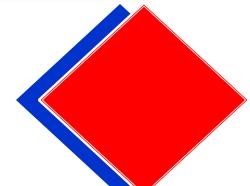
Oct Nov Dec Jan Feb Mar Apr May Jun Jul Aug Sep

Oct Nov Dec Jan Feb Mar Apr May Jun Jul Aug Sep

Target Flt Processor Implmt MMSEV / Waypoint / iPAS Scenario Testing Write Report

Final TCSR (9/27/12)





Project Start TRL (1-9): <u>4</u>

Current TRL (1-9): <u>5</u>

Active Radiation Shielding Study

Shayne Westover, PI – EP4/Propulsion Systems (281.483.2446, shayne.c.westover@nasa.gov)

Dan Fry, Ph.D., Science PI – SF2/Environmental Factors (281.483.2281, dan.j.fry@nasa.gov)

Scott Winter, Collaborator – NC2/SE&I (281.483.6855, d.s.winter@nasa.gov)

PROJECT OVERVIEW

• The deep space radiation environment is energetic and presents great risk to astronauts. Passive shielding becomes massive for long duration deep space missions. This study assesses the applicability of magnetic shielding to protect against exposure from Solar Proton Events (SPEs).

RELEVANCE/ VALUE TO NASA

• Radiation shielding is a technical challenge that needs to be addressed to enable human exploration of space.

OBJECTIVES & OUTCOMES

- Plasma sheathing tests performed while leveraging recent results from Rutherford Appleton Lab research.
- Synchrotron radiation effects from particle momentum change also analyzed. Data review and analysis complete.
- Deliverable will be in the form of a final report.

INFUSION POTENTIAL

- Future studies might consider mass, power, scalability, and additional architectural concepts for a space habitat.
- High Temperature Superconductors (HTS) may be used to generate the protective magnetic space shield. HTS have multiple applications currently being developed in the energy sector.



NASA TECHNOLOGY AREA ROADMAP (level 2)

- •TA06: Human Health, Life Support & Habitation Systems Radiation
- •TA07: Human Exploration Destination Systems Mission Operations & Safety

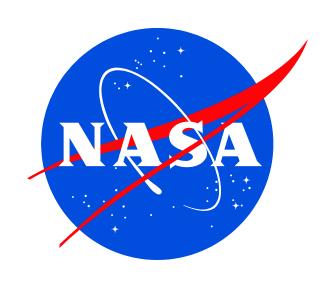
PROJECT DEVELOPMENT SCHEDULE

(Oct 2011 - Sept 2012)

Studies Development Schedule	May	June	July	August	Sept
IR&D					9/27/12
TCSR	5/12	✓			
MIT Analysis		6/12			
Test Data Review			7/12 ✓		
Architecture - CAD work		8/12	2		
Final Report					9/12

Project Start TRL (1-9): <u>1</u>
Current TRL (1-9): <u>1</u>

Miniature Exercise Device (MED)



PROJECT MANAGEMENT

Project Leader: JSC/ER3/Cherice Moore; 281-483-8780; cherice.moore-1@nasa.gov

Collaborators: JSC/SK2/Linda Loerch; 281-483-2557;

linda.loerch-1@nasa.gov

PROJECT OVERVIEW

As we travel beyond low earth orbit, smaller, lighter, highly effective exercise devices to aid in maintaining crew health will be required. The MED demonstrates compact, motion-system technology required to reduce the volume and weight of resistive exercise equipment.

RELEVANCE/ VALUE TO NASA

Every extended duration space mission with people will require high-performing exercise equipment to prevent physiological degradation. To provide these capabilities often requires considerable mass and volume. The current ISS resistive exercise of >1,200 lbs. will need to be reduced while maintaining current performance. MED provides high loading (expected to be >280 lbs./unit) with small mass & volume. Two MED units could provide an ISS ARED-equivalent loading capability.

OBJECTIVES & OUTCOMES

Project objective planned to prepare a functional prototype.

Outcomes:

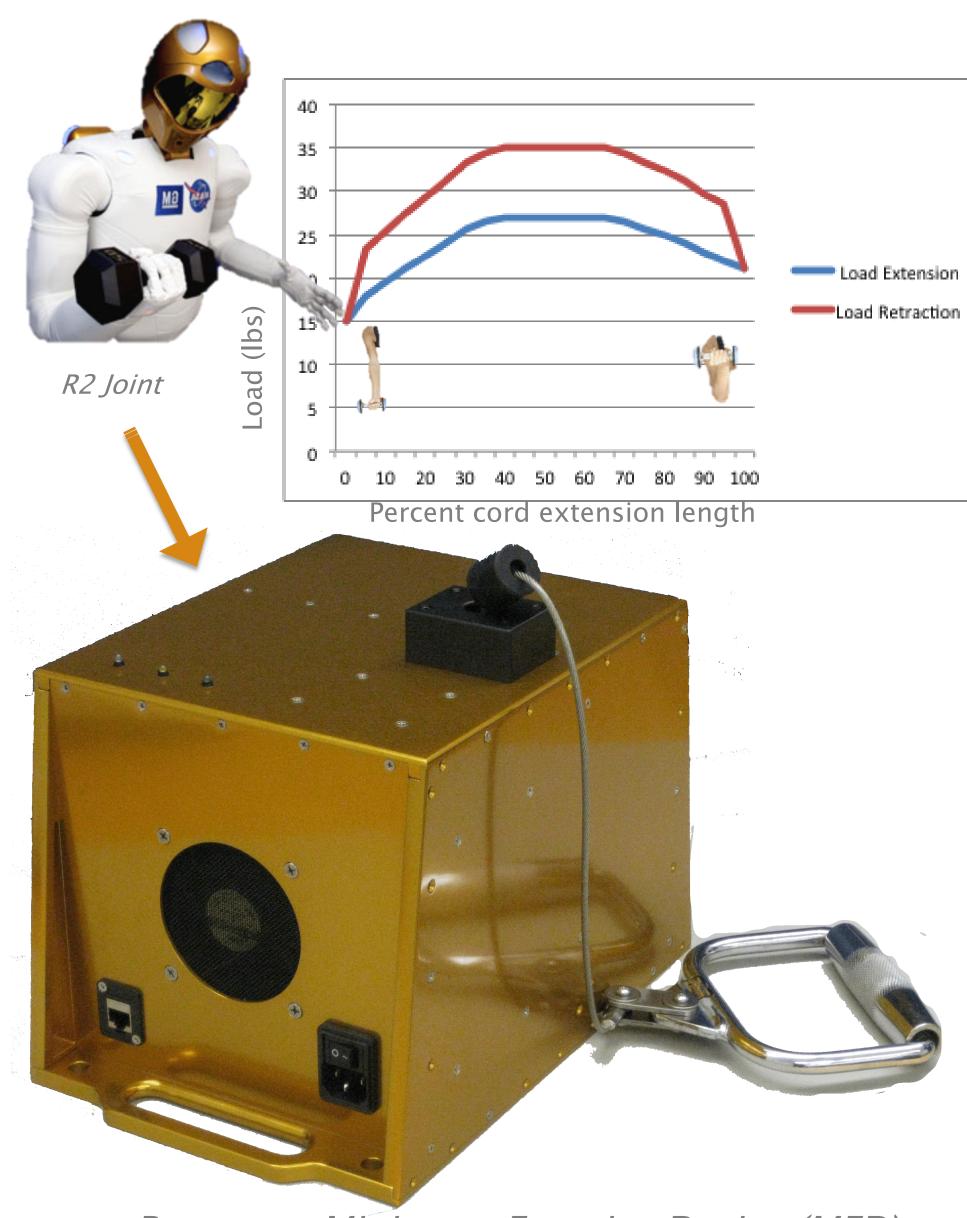
- Accomplished the MED Mechanical & Electrical design, development, and fabrication.
- Completed the MED Software design.
- Worked with SK to start assessing variable load curves to use with MED.

INFUSION POTENTIAL

Once the prototype is proven, several infusion options are available:

- To integrate MED during ARED exercise to off-set loads from the shoulders & lower back to the lower body
- To fly an SDTO MED for performance assessment for resistive exercise on ISS via ISTAR (From the ISS evaluation, further design refinement for exploration would be prepared.)
- To create a compact, commercially-sponsored and viable exercise unit

JSC/ER4/Reginald Berka; 281-483-5391; reginald.b.berka@nasa.gov JSC/ER4/Elliott Potter; 281-483-5229; elliott.e.potter@nasa.gov JSC/ER6/Charlotte Hudgins; 281-483-5845; charlotte.s.hudgins@nasa.gov JSC/ER6/Jeevan Perera; 281-483-5814; jeevan.s.perera@nasa.gov JSC/ER3/Javier Lucero; 281-244-5979; javier.lucero-1@nasa.gov



Prototype Miniature Exercise Device (MED)

DESCRIPTION

The Robonaut and ARED derived MED not only is small (approximately 20 pounds and less than 1 ft³), but will also provides new exercise technology through the ability to vary the eccentric and concentric loading throughout the cord displacement cycle to optimize muscle strength building.

NASA TECHNOLOGY AREA ROADMAP

• TA06.3/Human Health, Life Support & Habitation System (Human Health and Performance)

Sept Oct Nov Dec Jan Feb Mar Apr May June July Aug Sept

Project Start

Performance/Design TIM

Mech/Elect Development

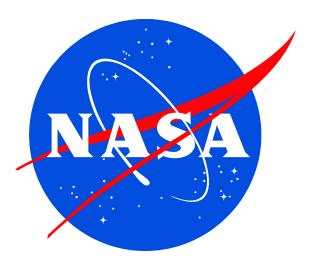
Software Development

JTWG Mid-Term TCSR

Poster Session/ JTWG Final TCSR

<- IRD FTE Funding ->

Multi-Phase Methane Heat Xfer



PROJECT MANAGEMENT

J.C. Melcher, Ph.D. / JSC-EP4, J. Bruggemann / WSTF-RD, Prof. A. Choudhuri / Univ. Texas @ El Paso (281) 244-6427, john.c.melcher@nasa.gov, (575) 525-7659, jeremy.bruggemann@nasa.gov

PROJECT OVERVIEW

•Conduct laboratory scale study of regeneratively cooled rocket engine heat transfer using methane. Measure fluid and wall temperatures through multiple states and phase changes. Regen engine analytic model generated and validated with data. Innovative approach for subcritical methane boiling heat transfer.

RELEVANCE/ VALUE TO NASA

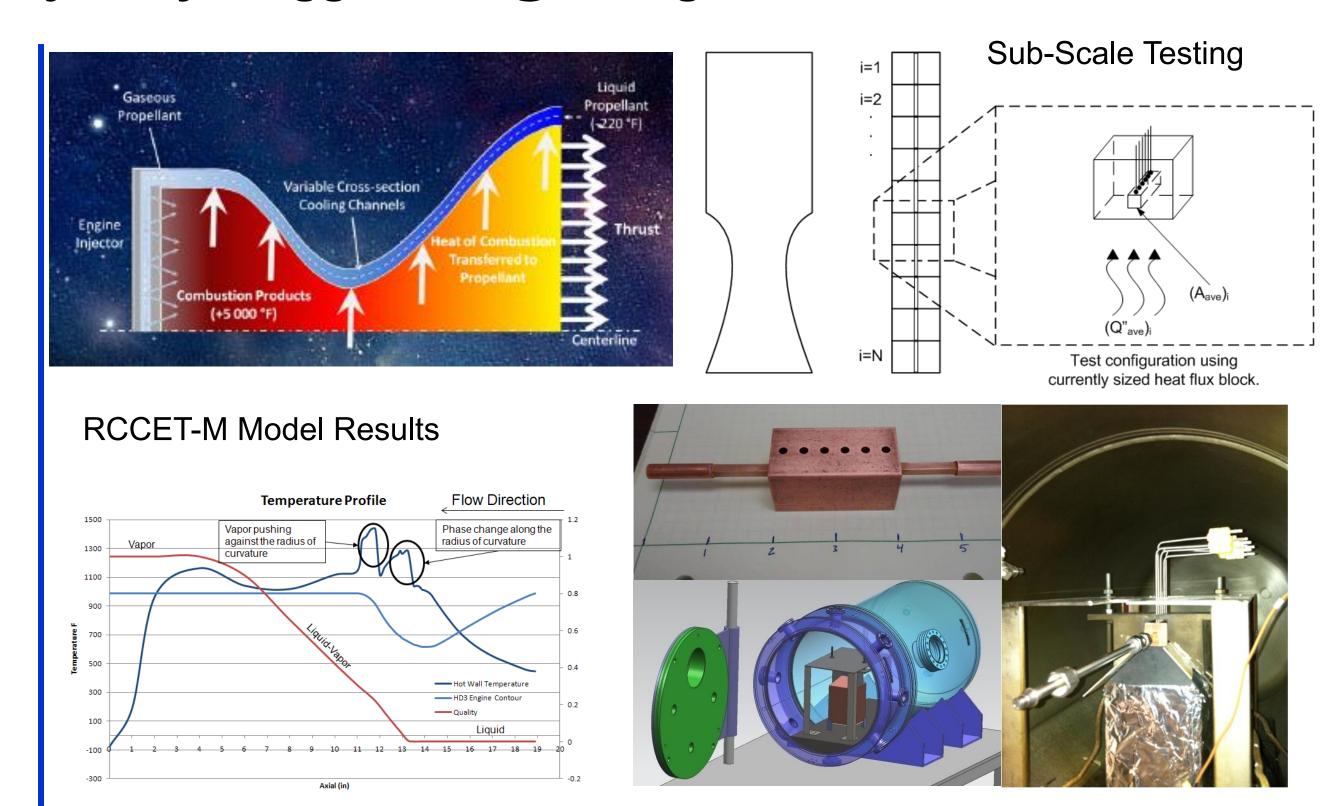
 Heat transfer experiments advance the fundamental understanding of two-phase methane, which enable high-performance "green propellant" rocket engines

OBJECTIVES & OUTCOMES

- 1st article design in testing at UTEP, based on Morpheus engine. 2nd test article and radial heating block in design review stage with enhanced instrumentation.
- JSC in-house design tool, Regeneratively Coooled Combustor Equilibrium Tool for Matlab (RCCET-M), baselined and in-use. Validation from UTEP data.

INFUSION POTENTIAL

 Regen-cooled main engine technology will be used on the Human Exploration and Operations Mission Directorate (HEOMD) Advanced Exploration Systems (AES) Project Morpheus vertical test bed, enabling lunar lander and ISRU tech demo missions

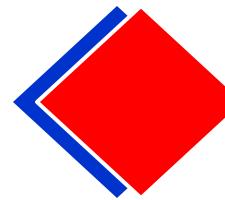


NASA TECHNOLOGY AREA ROADMAP

•Regen engine heat transfer studies enable highperformance cryogenic LO2/Methane propulsion: TA 2.0 In-Space Propulsion Technology, 2.1 Chemical Propulsion, 2.1.2.1 liquid cryogenic LO2/CH4.

PROJECT DEVELOPMENT SCHEDULE

Project Development Schedule	CY2011 Q4 (Oct-Dec)	CY2012 Q1 (Jan-Mar)	CY2012 Q2 (Apr-June)	CY2012 Q3 (July-Sept)
Experiment Activation (LN2) / Hardware Buildup	10/24 – 12/31 1: 10/24 Experiment C	Experiment TF	RR: 3/29	
Hardware Buildup/ Phase 1 LCH4 testing	Experiment	Buildup: 2/9-3/29	Testing: 3/29 -6/11	Phase 2 design
Phase 2 Testing w/Enhanced Instrumentation				R: 7/26 Buildup: 7/26-8/2 Test: 8/6-8/31
Data Analysis/Final Report/Poster Session			Mid-Term TCSR: 5/8	9/3 - 9/26 Session: 8/7★ Final TCSR: 9/27★

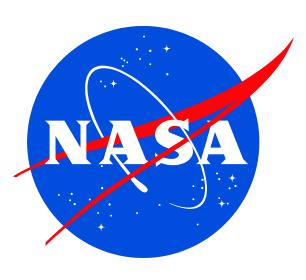




Appendix C

JSC FY'12 CIF Support Project Details Directorate-Level IR&D

Multi-Phase Flow Experiment for Suborbital Testing (MFEST)



PROJECT MANAGEMENT

Kathryn Hurlbert, Ph.D., EC8/Special Projects Branch, x34546, katy.m.hurlbert@nasa.gov, & Ralph Marak, EC7/Tools & Equipment Branch

PROJECT OVERVIEW

 The primary objective of MFEST is to conduct a pathfinder, suborbital flight experiment that focuses on two-phase fluid flow and separator operations through a representative launch, suborbital, and entry profile

RELEVANCE/ VALUE TO NASA

 MFEST will test a two-phase flow system and vortex separator concept under representative suborbital launch, zero-g, and entry; two-phase flow and separators are used in numerous technical areas (e.g., life support, thermal systems, science)

OBJECTIVES & OUTCOMES

- Hardware and documentation located and rejuvenated; precursor ground testing is continuing, and parabolic flight testing is scheduled for September 2012
- Partnerships in place with Space Engineering Research Center (SERC) at Texas A&M, and Advanced Cooling Technologies (ACT)

INFUSION POTENTIAL

- The separator is suitable for both ground and aerospace applications, but has not yet been tested for long-duration space environment as proposed herein
- ACT is one commercial company that intends to market the separator for commercial and government applications

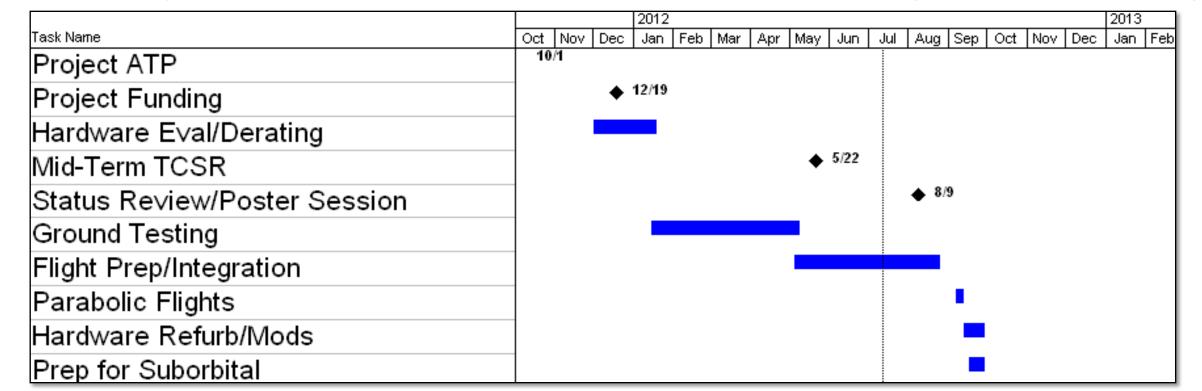


NASA TECHNOLOGY AREA ROADMAP

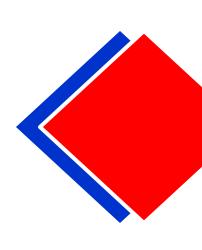
- The proposed experiment can be applicable to technologies designated in multiple draft OCT Space Technology Roadmaps:
 - TA02, In-Space Propulsion Technologies
 - TA03, Space Power and Energy Storage
 - TA06, Human Health, Life Support and Habitation Systems
 - TA07, Human Exploration Destination Systems
 - TA14, Thermal Management Systems

PROJECT DEVELOPMENT SCHEDULE

* NOTE: Project is proposed to continue into FY13, with request for additional funding and planned suborbital flight



Project Start TRL: 5 Projected TRL: 7/8



LOX/Methane Regeneratively-Cooled Rocket Engine Development

PROJECT MANAGEMENT

Rob Morehead/EP4, Lee Wilson/ES6 281-224-5670, robert.l.morehead@nasa.gov; 281-483-8533, robert.l.wilson@nasagov Phase 1: Regen test section added to existing JSC LOX/Methane Engine

PROJECT OVERVIEW

- Using liquid methane as a coolant, design, build, and test fire a regeneratively cooled oxygen/methane combustion chamber.
- Develop low-cost processes to model and test high heat flux heat transfer into subcritical liquid methane.

RELEVANCE/ VALUE TO NASA

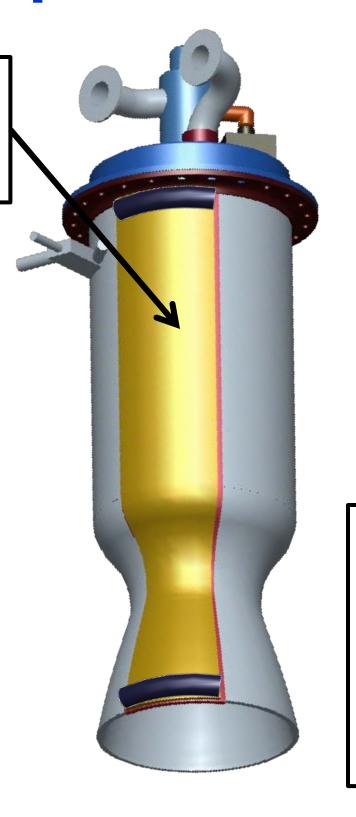
- Methane is non-toxic, space storable, and producible on foreign planets...but few full-scale methane engines have been developed.
- This project will markedly improve the NASA knowledge base for methane and subcritical regeneratively cooled engines.

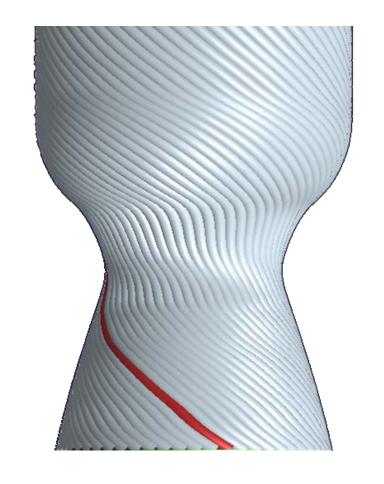
OBJECTIVES & OUTCOMES

- Phase 1 experiment in manufacture; fluid passages designed using code developed under companion center-level IR&D project (Multi-Phase Methane Heat Transfer). Studies for phase 2 full-scale chamber in work.
- Deliverables: a Morpheus-class functional combustion chamber, validation for JSC's regenerative cooling heat transfer model, and publishable test data from hot-fire tests.

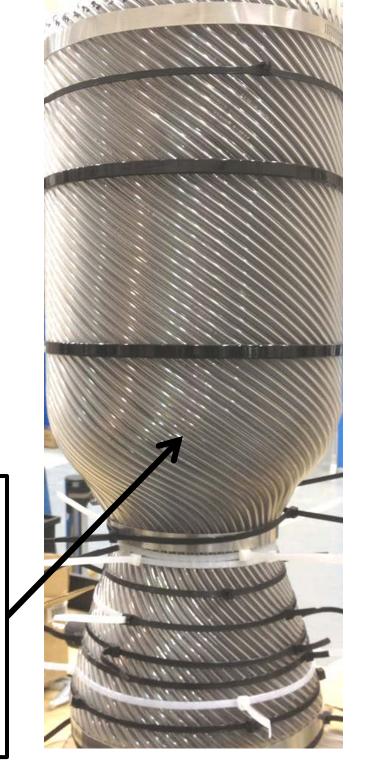
INFUSION POTENTIAL

- This project will provide baseline data for any future methane-based regeneratively cooled rocket engines, such as for Morpheus-type landers or those that burn methane produced by an ISRU reactor
- This technology could also be used in commercial applications for high-Q heat exchangers using liquid methane as the coolant.





Proof of concept for potential manufacturing method of Phase 2 full-scale regen chamber:
Single-pass constant-diameter tubing brazed to form solid wall (plastic shown here)



NASA TECHNOLOGY AREA ROADMAP

•This project enables high-performance cryogenic LO2/Methane propulsion: TA 2.0 In-Space Propulsion Technology, 2.1 Chemical Propulsion, 2.1.2.1 liquid cryogenic LO2/CH4.

PROJECT DEVELOPMENT SCHEDULE

Project Development Schedule	2011 Q4	2012 Q1	2012 Q2	2012 C	23	2012 Q4
Analytical Modeling and Sub Scale Testing		11/1/11 –	8/15/12			
Partial Regen Chamber Dev. and Testing			1/20– 9/15			
Partial Regen CDR			5/1 7 ★			
Full Scale Combustion Chamber Design			4/2	21-9/31		
Mid-Term TCSR			6/5 ★			
Full Scale Chamber CDR				9/31	*	
Full Scale Chamber Manf. and Testing					9,	/1-12/15
Final TCSR / Final Report				8/20	*	1/15/13

Project Start TRL (1-9): 3

Current TRL (1-9): 4

Project End TRL (1-9): 5

Flight Deck of the Future:

Electronic-textile System for the Evaluation of Wearable Technology (E-SEWT)

PROJECT MANAGEMENT

Cory Simon, EV3; cory.l.simon@nasa.gov Tim Kennedy, EV4; timothy.f.kennedy@nasa.gov

PROJECT OVERVIEW

The E-SEWT is a reconfigurable garment that integrates displays, controls, and sensors. Its modular interface allows for rapid prototyping of new functionality and its e-textile antennas enable accurate indoor tracking.

RELEVANCE TO NASA

The E-SEWT brings information and control to the astronaut, improving situational awareness and efficiency.

OUTCOMES

Developed Functioning Prototype s

- Removable electronic textile swatches
- Power and data network in garment
- Wireless data exchange with base station

Developed new manufacturing processes

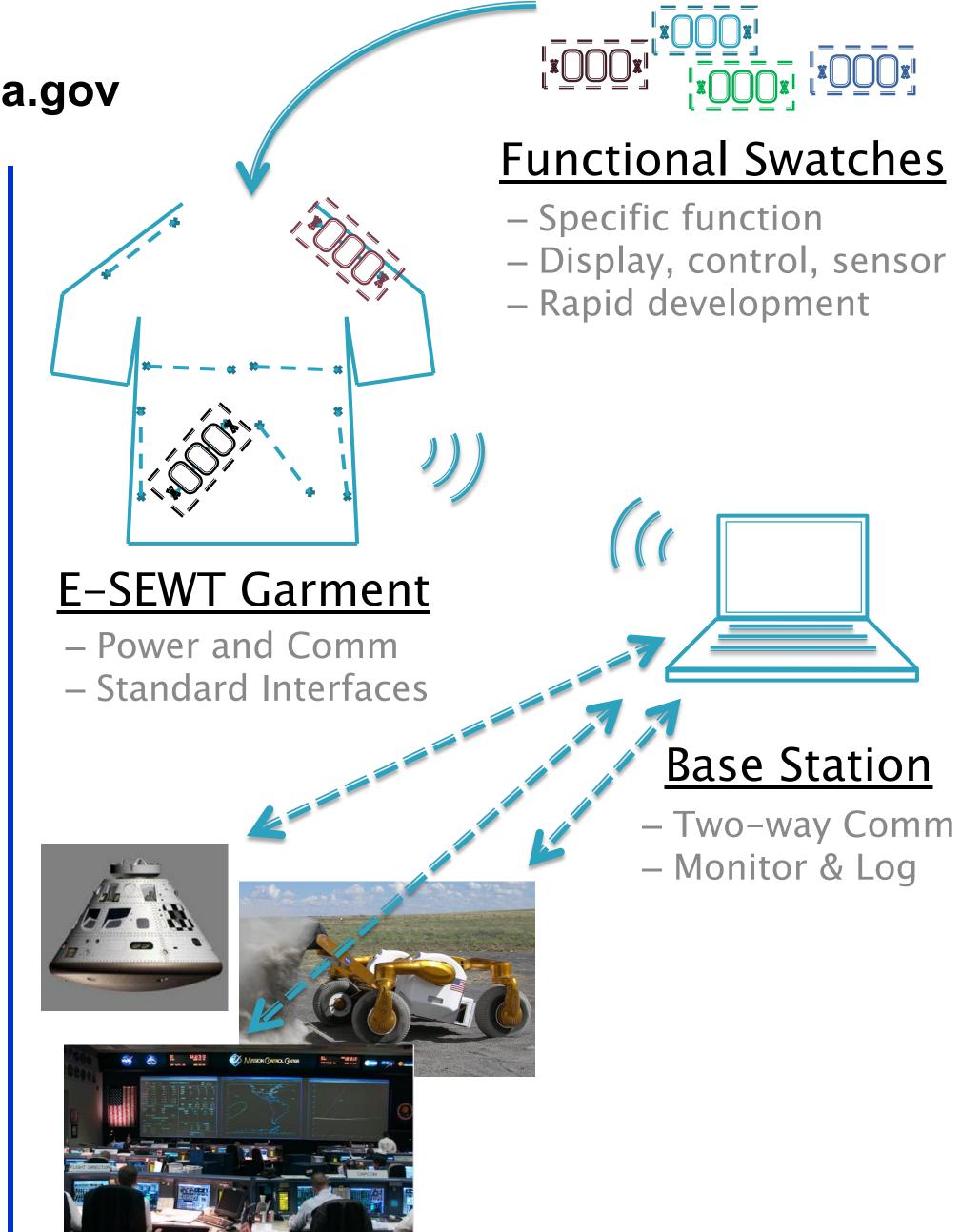
Established university partnerships

NASA TECHNOLOGY ROADMAP

TA05 Communication & Navigation; TA06
 Human Health, Life Support & Habitation; TA07
 Human Exploration Destination; TA04 Robotics,
 Tele-Robotics and Autonomous Systems

DEVELOPMENT SCHEDULE

	1 st Qtr	2 nd Qtr	3 rd Qtr	4 th Qtr
Start				
Subsys De	ev —			
Prototype	1			
Midterm				
Poster Se	ssion			
Prototype	2		-	
Project En	id			



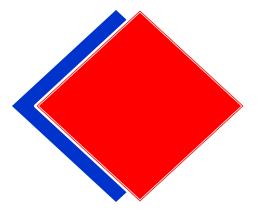
Other Systems

- Local or Remote
- Send Data and Alerts
- Receive Data and Commands

INFUSION POTENTIAL

E-textile antennas will be integrated into Robonaut 2 for use on ISS. The E-SEWT prototype will be integrated into the Flight Deck of the Future for testing and use during IPAS evaluations.

E-SEWT technology and processes have applications in health, sport and extreme environments. University and industry partnerships will help facilitate commercial infusion.



Virtual Windows

NASA

PROJECT MANAGEMENT

Helen Neighbors/EV3 (Lead); Collaborators: T. Scott West/WE, Shelby Thompson/SF3, Max Haddock/EV3

helen.neighbors@nasa.gov; x30811

PROJECT OVERVIEW

• Investigate the potential benefits of Virtual Windows in future space craft design via real-time video scenestitching using images from multiple cameras, plus alternative display configurations and control input methods for scene and perspective change.

RELEVANCE/ VALUE TO NASA

• Virtual Windows can enhance external viewing capability beyond available physical windows and may aid in psychological health on long duration missions.

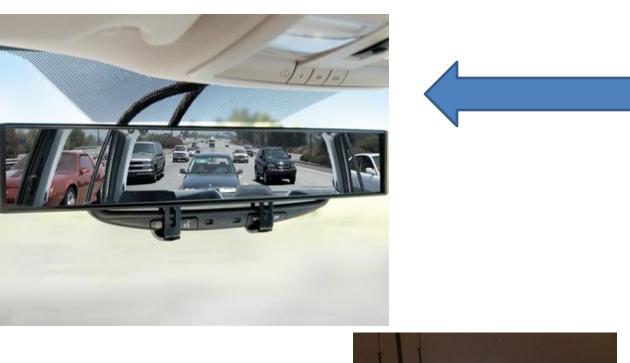
OBJECTIVES & OUTCOMES

- Develop low latency solution for real time video scenestitching of multiple camera images
- Further assessment of portable window and display tiling concepts
- Demonstrate and evaluate capability in operational setting

INFUSION POTENTIAL

- System prototypes to be deployed on Gen1B MMSEV rover to evaluate effectiveness in eliminating blind spots.
- Real time video aspect could supplement or replace recorded video used in commercial applications wherein interactive and scenic views are utilized for aesthetic and psychological benefits.

Virtual Rear View Mirror





Portable Window

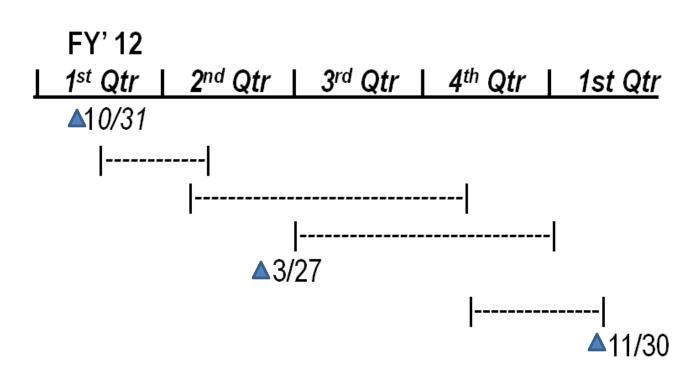
NASA TECHNOLOGY AREA ROADMAP

• Virtual Windows applies to TA07.4 Advanced Habitat Systems by supplementing the number of real windows required in future spacecraft and helping to assure crew psychological heath

PROJECT DEVELOPMENT SCHEDULE

Project Development Schedule:

- FY'12 Project start
- Planning & Design
- Procurements
- FPGA Development
- Mid-term TCSR & Demo
- Integration &Test
- Final Demo, TCSR & Report



Project Start TRL (1-9): <u>2</u>
Current TRL (1-9): <u>3</u>

GeoLab Robotic Sample Manipulator

PROJECT MANAGEMENT

Cynthia Evans, Ph.D., KT; p. (281)483-0519; cindy.evans-1@nasa.gov; Michael Calaway and Mary Sue Bell, Ph.D. KT/Jacobs ESCG

Collaborators: Zheng Li, Ph.D., University of Bridgeport (2012 X-Hab Challenge Award)

PROJECT OVERVIEW

• Design/ build prototype geological sample holder for GeoLab glovebox in the Deep Space Habitat (DSH). Leverages from earlier GeoLab work and 2012 collaboration with U. of Bridgeport; this proposal extended the Bridgeport product for full glovebox operations by including a translation track, increasing the DOF and whole-glovebox operations, and including motors and controllers for remote control, enabling precise sample control and efficient crew operations.

RELEVANCE/ VALUE TO NASA

• Tests science operations and surface-based curation protocols for sample manipulation and preliminary examination in a reduced gravity environment. Tests robotic tools for human science operations.

OBJECTIVES & OUTCOMES

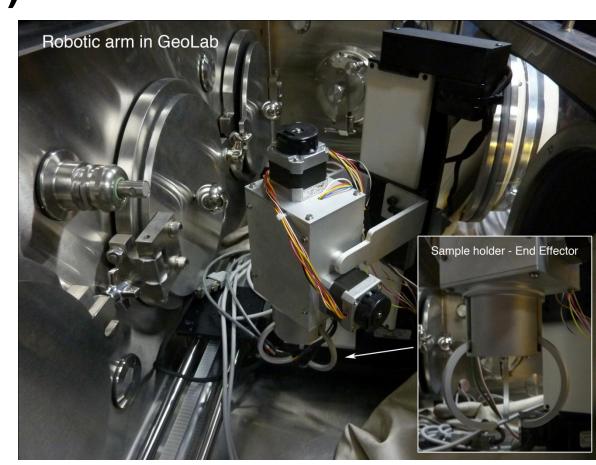
• Integrate a robotic sample manipulator in the DSH-based GeoLab to assist astronauts and support scientists in preliminary examination of astromaterials. Addresses recommendations about enhanced, efficient glovebox operations; increased geometric control of examination. Leverages human activities with robots.

INFUSION POTENTIAL

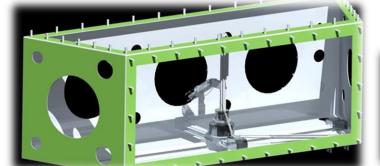
• Infusion strategy: GeoLab operational test results are folded into AES science operations concepts, including definition of geoscience sample handling protocols and tools. Enables future partnerships with new glovebox and clean room technologies.

Project Start TRL (1-9): <u>3</u> Current TRL (1-9): <u>4-5</u>





Left: GeoLab integrated into DSH Top: Robotic arm inside GeoLab



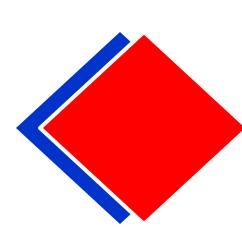


CAD models: inside glovebox; end effector.

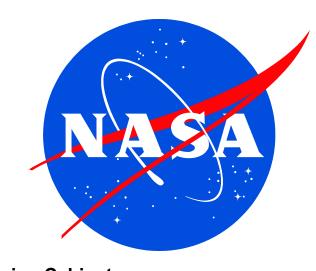
NASA TECHNOLOGY AREA ROADMAP

TA04 Robotics (Human Systems Interactions), TA07: Human Exploration Systems (Integrated Habitat systems). TA08: Science Instrumentation, TA11: Modeling, Simulation, IT (Collaborative science/ engineering)

	Sept-	Nov-	Jan-	Mar-	May-	Jul-	C 1
GeoLab Robotic Manipulator	Oct	Dec	Feb	Apr	Jun	Aug	Sept
Robotic Arm SDR	Х						
Robotic Arm PDR and CDR		Х					
Construction and Progress Repors			Χ	Х			
Delivery to JSC					Χ		
Mid-term TCSR					Χ		
Integration into GeoLab and DSH						Χ	
Procedure Development and Training						Χ	
Preliminary Tests, final DSH operations						Χ	Х
IR&D Poster and Final Report						Χ	Χ



Curation Technology for Future Sample Return Missions: Organic Cleanliness Baseline Study



PROJECT MANAGEMENT

Carlton C. Allen, Michael J. Calaway, Judith H. Allton, and Patti J. Burkett **Astromaterials Acquisition and Curation Office (KT)** 281-483-5126; carlton.c.allen@nasa.gov

PROJECT OVERVIEW

Future human and robotic missions to the Moon, Mars, asteroids and comets will require handling and storing atromaterial samples free of inorganic and organic contamination and possibly preserving these samples at low temperatures. Current astromaterial collections from the Apollo, Genesis, and Stardust missions have mainly been concerned with inorganic contamination for clean preservation at ambient temperatures. Little is known about the current state of organic contamination in JSC curation laboratories. This project was developed to determine a baseline for current curation technology and test how well existing curation cleaning procedures lowered organic contamination. The results provide a foundation to develop new cleaning procedures that would result in lowering organic contamination for handling and long-term storage of future returned samples. In addition, the results from this study enable new technology and techniques to be used in current curation facilities and help develop the next generation sample return missions.

RELEVANCE/ VALUE TO NASA

The Planetary Science Decadal Survey 2013 - 2022 recommended Mars, Moon, asteroids and comets as the highest priority sample return missions. In support of these missions, the Decadal Survey stated that such missions "present new challenges, including curation of organics uncontaminated by Earth's biosphere and volatiles requiring low temperature curation and distribution."

OBJECTIVES & OUTCOMES

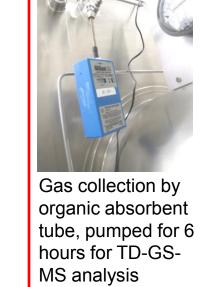
- Detailed understanding of organic contamination levels through time in Astromaterials Curation laboratories – ACCOMPLISHED.
- Decreased organic contamination in Astromaterials Curation laboratories **COMPLETE IN** YEAR 2
- Proven techniques and equipment to support new sample return missions with increasingly stringent requirements for organic contamination control – **COMPLETE IN YEAR 3**.

INFUSION POTENTIAL

- This project will directly improve current Astromaterials Curation laboratory operations and lay the groundwork for sample curation of all future human and robotic missions.
- State-of-the-art cleaning and monitoring developed for handling returned samples have direct application to NASA hardware cleaning requirements and potential use for the biotechnology, semiconductor, and nanotechnology industry.

Advanced Curation Cabinet





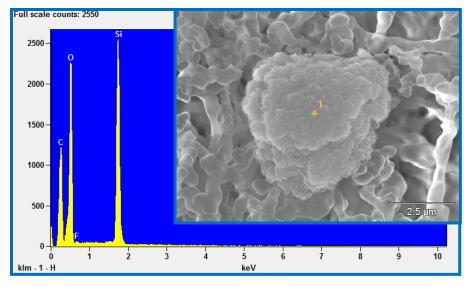
List of Organic Testing

- 4 Airborne molecular organics by pure Si wafer exposure for Thermal Desorption Gas Chromatography Mass Spectroscopy (TD-GC-MS) analysis.
- ♣ Airborne molecular organics by absorbent tube for Thermal Desorption Gas Chromatography Mass Spectroscopy (TD-GC-MS) analysis.
- ♣ Surface organics on stainless steel by exposure of Methylene Chloride solvent with NVR/FT-IR spectroscopy and Gas Chromatography Mass Spectroscopy (GC-MS) analyses.
- ♣ Liquid particle counts of all ultrapure water used for cleaning
- 4 Organic particle identification by Scanning Electron Microscopy (SEM) on Millipore filters used during cabinet cleaning procedure.

<u>Lunar Processing Cabinet</u>



Two sets of 8 inch Silicon Wafers Exposed for 24 hours for TD-



Possible oxidized silicone particle

	Lunar Process	ing Cabinet A	AP-11, 307-41	Advanced Curation Cabinet						
Detected Organics by TD-GC-MS	Vertical Wafer Exposure (ng/cm²)	Surface Wafer Exposure (ng/cm²)	Organics in Air Absorbent Tube (ng/L)	Vertical Wafer Exposure (ng/cm²)	Surface Wafer Exposure (ng/cm²)	Organics in Air Absorbent Tube (ng/L)				
Hydrocarbons	, ,		, ,	, ,	, ,	, , ,				
Low boilers C7-C10	< 0.1	0.2	1.2	0.4	0.4	0.6				
Medium boilers >C10-C20	1.8	2.5	3.8	7.1	9.6	18.8				
High boilers >C20	0.1	0.2	< 0.1	1.1	1.8	0.1				
Sum >= C7	1.9	2.9	5	8.6	11.8	19.5				

Hydrocarbon results show that a new type of degreaser is needed to replace the Apollo era Freon 113 cleaning to further reduce organic contamination levels.

NASA TECHNOLOGY AREA ROADMAP

- TA07: Human Exploration Systems (Integrated Habitat and science systems)
- TA08: Science Instrumentation

PROJECT DEVELOPMENT SCHEDULE

	ОСТ	NOV	DEC	JAN	FEB	MAR	APR	MAY	JUN	JUL	AUG	SEP
Start Project												
Historical Data Compilation		_										
Advanced Cabinet Cleaning					-							
Lunar Cabinet Cleaning												
Cabinet Testing						-						
Mid-term TCSR												
Interpret Results									-			
Poster Session												
Final Report												

Project Start TRL (1-9): 3

Current TRL (1-9): 4

Habitat Particle Impact Monitoring System (HIMS)

PROJECT MANAGEMENT

John N. Opiela (ESCG/Jacobs; john.n.opiela@nasa.gov, x33594), Eugene Stansbery (KX)

PROJECT OVERVIEW

- The HIMS is designed to monitor particle impacts that could damage a habitat structure during a future exploration mission.
- System performance must be characterized on flexible, inflatable structures.

RELEVANCE/ VALUE TO NASA

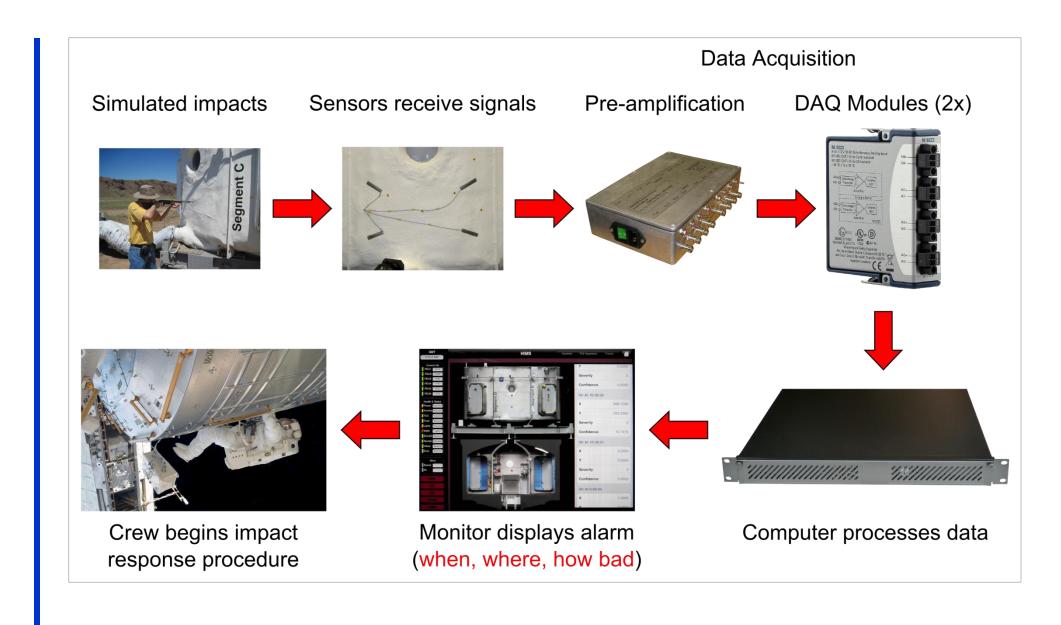
• This mission-enabling technology will improve the safety of future human exploration missions.

OBJECTIVES & OUTCOMES

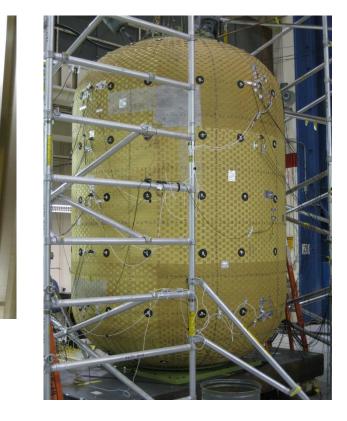
- Experimental data will determine maximum sensor spacing, and hence the number of sensors needed to adequately monitor the structure.
- A report will outline the design, requirements, and anticipated capabilities of a total-structure impact detection system based on this technology.

INFUSION POTENTIAL

- HIMS participates in the AES
 Habitation Systems Project, with long-term plans for flight demonstration (ISS-docked and deep-space).
- Include HIMS technology in NASA/commercial partnerships currently studying inflatable space habitats.



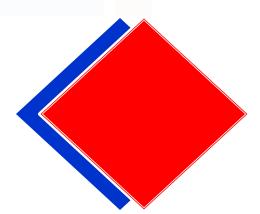
Testing and evaluation on inflatables.



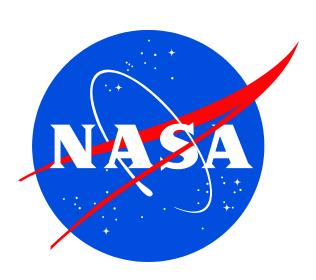
NASA TECHNOLOGY AREA ROADMAP

- Human Exploration Destination
 Systems TA07
 - 7.4.1.2 Internal Systems & Outfitting
 - 7.5.2.2 MMOD & Secondary Ejecta Protection

Tasks	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep
FY12 Project start				Δ								
Identify and acquire samples												
Design and fabricate test fixture												
Conduct low velocity tests												
Hypervelocity tests												
Mid-term TCSR									Δ			
Follow-up tests if needed												
Analysis												
Report development												
Final report delivered												Δ



GIS Technology - Resource and Habitability Assessment Tool



Carlton Allen and Dorothy Oehler / Astromaterials Research and Exploration Science (KA)

3-5126 / 3-4259

carlton.c.allen@nasa.gov | dorothy.z.oehler@nasa.gov

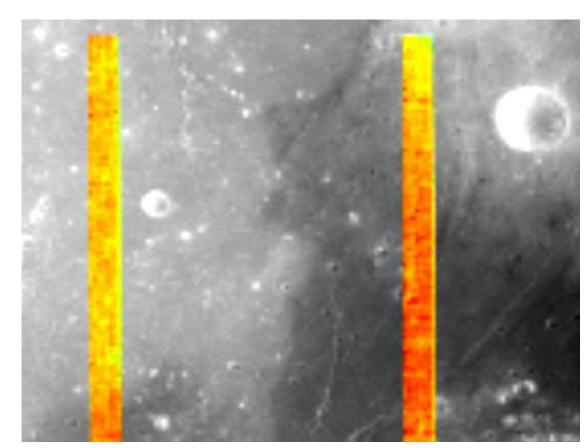
PROJECT OVERVIEW – We are applying Geographic Information Systems to new orbital data sets for Lunar resource assessment and the identification of past habitable environments on Mars. GIS has not previously been used for planetary resource assessment and its applicability to Martian habitability is in its infancy.

RELEVANCE / VALUE TO NASA

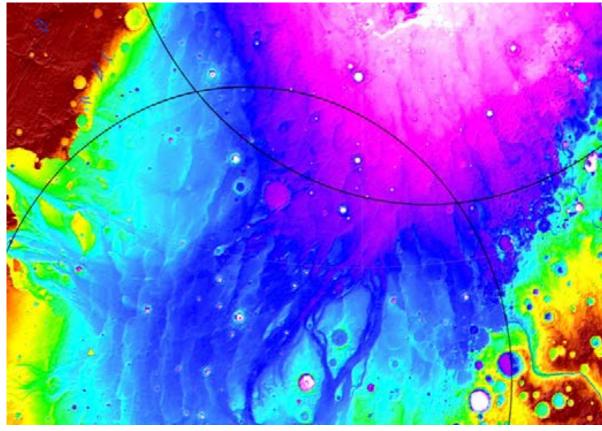
- Lunar Resource Assessment -- key to future exploration and sustainability
- Martian Habitable Environments top priority Mars program goal
- New research and analysis capability for JSC / KA

OBJECTIVES & OUTCOMES

- Map lunar O₂ resources using data from the Lunar Reconnaissance Orbiter – accepted for publication
- Identify sites on Mars having enhanced habitability and high potential to preserve organic biosignatures – accepted for publication
- Dr. Dorothy Oehler was selected as a Participating Scientist on NASA's Mars Science Laboratory mission.



Moon – Oxygen-rich deposit of volcanic ash



Mars – ancient floods and a possible ocean

INFUSION POTENTIAL

- Moon lunar outpost site selection
- Mars landing site selection
- Commercial O₂ production at a lunar outpost

NASA TECHNOLOGY AREA ROADMAP

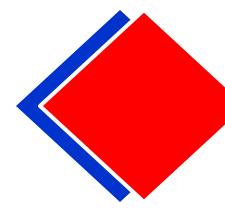
TA07 "Human Exploration Destination Systems" Level II subtopic "In-situ Resource Utilization"

PROJECT DEVELOPMENT SCHEDULE

TASK	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep
Lunar Resource Assessment												
I ntegrate LRO orbital datasets into GIS												
Map pyroclastics; estimate resource												
Martian Habitability Analysis												
Mid-Term and Final TCSR's												
Prepare abstracts & papers for publication												

Project Start TRL (1-9): 3

Current TRL (1-9): <u>4</u>



Green Monopropellant Detection and Decontamination Method Development

PROJECT MANAGEMENT

Benjamin Greene, NTEC-WSTF/RF 575.524.5761 benjamin.greene-1@nasa.gov

Mark B. McClure, NASA-WSTF/RF 575.524.5488 mark.b.mcclure@nasa.gov

PROJECT OVERVIEW

 High performance green monopropellants require means of detection and remediation of spills and residues. This project investigated color tests for spill detection and methods for remediation. Innovation was achieved using COTS test kits, and both fundamental and novel chemistry applied to the monopropellant ingredients.

RELEVANCE/ VALUE TO NASA

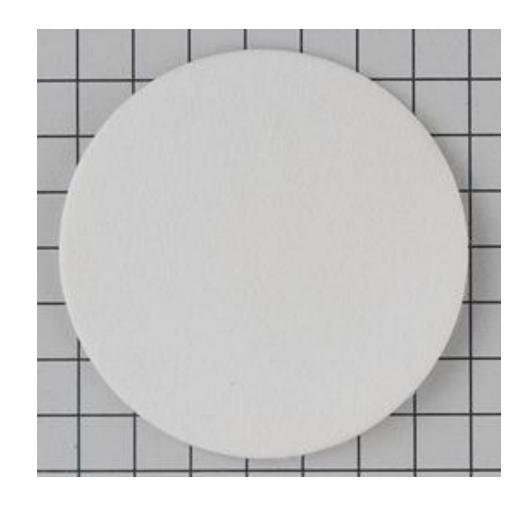
- NASA requires green alternative propellants
- Propellant spills must be detected and mitigated
- Detection and mitigation must be simple and reliable

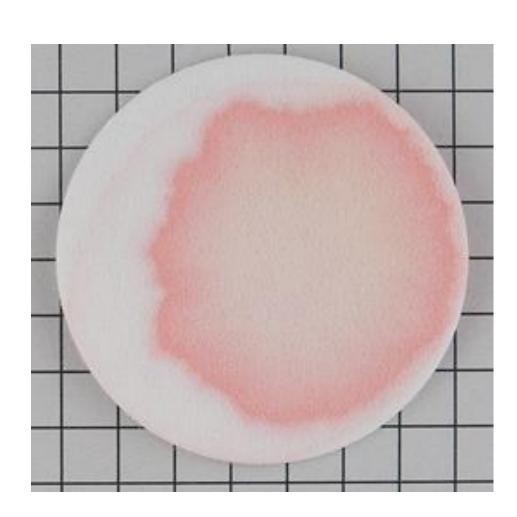
OBJECTIVES & OUTCOMES

- Identify species for detection and mitigation and performed lab tests to obtain visual color changes
- Used COTS test strips, explosives test kits, and lab chemicals and obtained data
- Used instruments to investigate unexpected behavior
- A report will summarize the results of this activity

INFUSION POTENTIAL

- NASA's High Performance Green Propellant initiatives, DoD, DHS, and commercial entities can use these methods.
- The JANNAF Propellant and Explosives Development and Characterization Subcommittee can be a forum for insertion



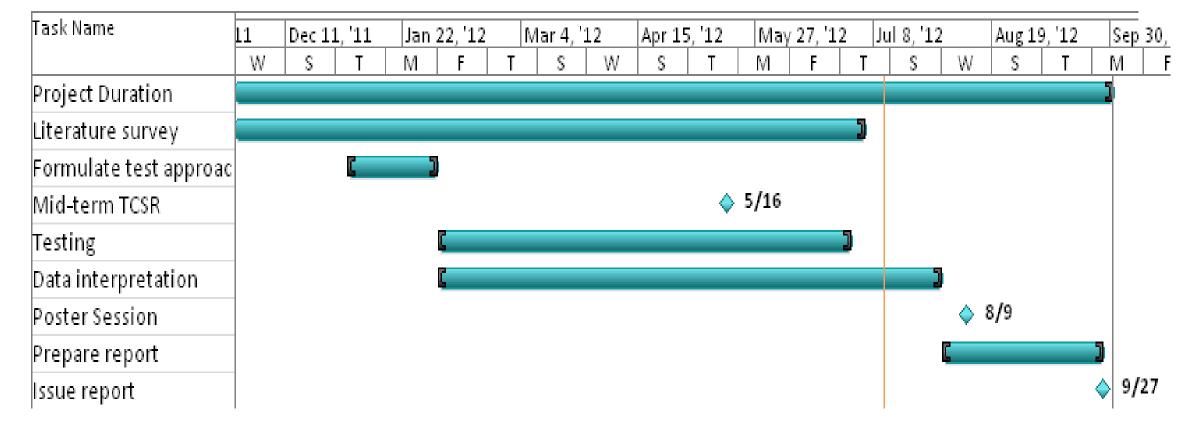


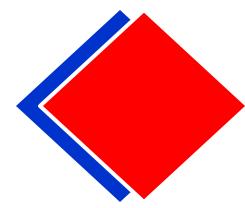
Propellant on a filter pad (L) exposed to an iron solution (R) provides visual detection

NASA TECHNOLOGY AREA ROADMAP

•This project is critical to NASA high performance green propellant initiatives TA02 WBS 2.1 Chemical Propulsion

PROJECT DEVELOPMENT SCHEDULE

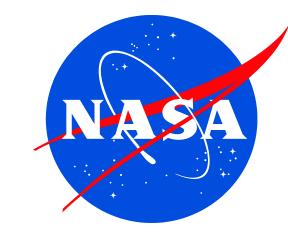




Project Start TRL (1-9): <u>#1</u> Current TRL (1-9): <u>#4</u>

Microgravity Cell Counter

Brian Crucian*, Heather Quiriarte, Terry Guess, Mayra Nelman-Gonzalez, Matthew Roper, Kathleen McMonigal, David Alrahwan and Clarence Sams



PROJECT OVERVIEW

- The ability to monitor hematology parameters during spaceflight is currently an unmet medical requirement (NASA-STD-3001). This project evaluated a DNA stain/CCD camera based technology to provide a White Blood Cell count + differential (granulocytes, lymphocytes, monocytes, eosinophils, basophils) analysis during microgravity conditions.
- This evaluated technology is miniaturized, lightweight, has few moving parts and operates on battery power. This technology generates a WBC and differential analysis. Sample is fingerstick blood ~10 microliters. Analysis time is ~3 minutes 20 seconds. Generates minimal biohazardous waste, no liquids for disposal.

OBJECTIVES & OUTCOMES

Task 1: Engineering evaluation/modification

- -Minimal modifications required to COTS base unit
- -Battery power acceptable for flight
- -Optical path sensitive to perturbation (.287 cm) but stable for flight
- -Cuvette housing must be secured
- -Double-magnetic delivery of cuvette to CCD camera appropriate for flight

Task 2: Validation for medical/research sample types

- -Instrument analysis of both fingerstick and venous blood samples validated against laboratory standard
- -Reagent stability acceptable
- -Loaded cuvette stability acceptable
- -Intra-cuvette precision acceptable
- -Instrument precision found to be acceptable

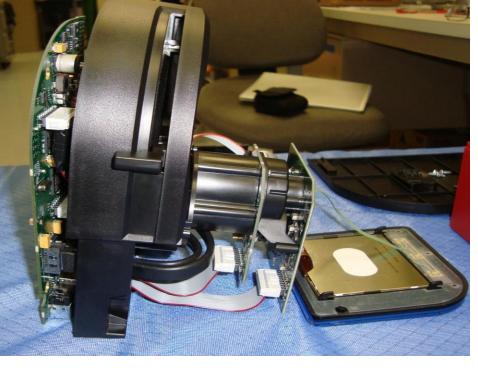
Task 3: Validation during reduced gravity conditions

- -Microgravity sample delivery (capillary action) acceptable
- -Instrument functions in any gravity condition (0xG to 2xG)



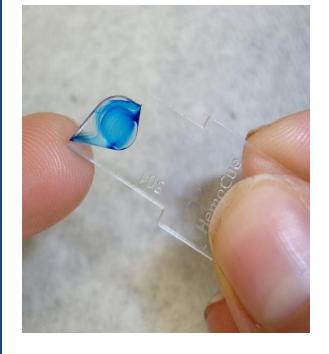
INSTRUMENT





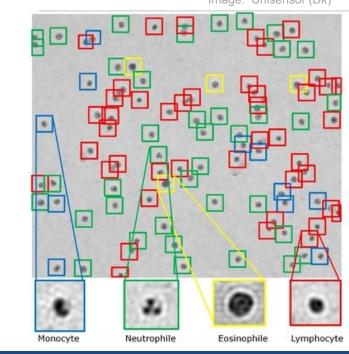
*Author Contact: 281-483-7061; brian.crucian-1@nasa.gov

SAMPLING

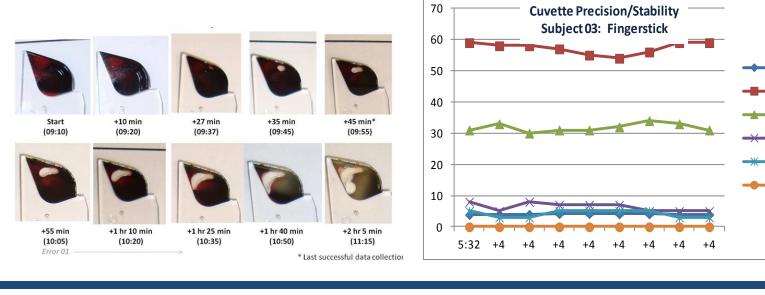




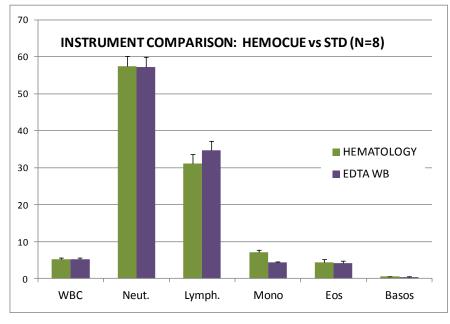
ANALYSIS

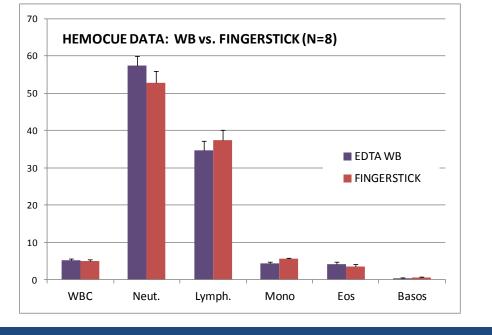


CUVETTE STABILITY

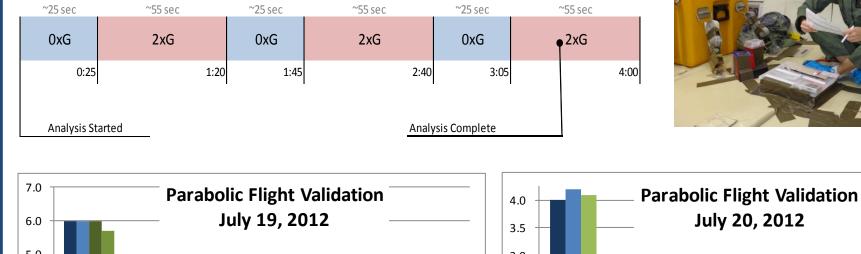


LABORATORY VALIDATION

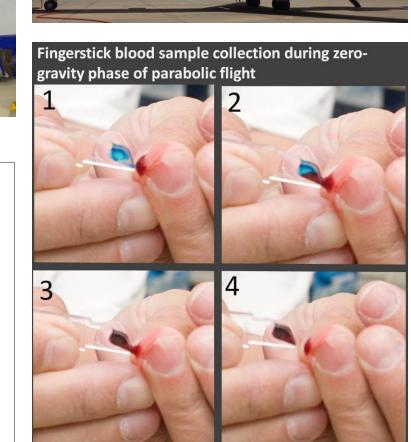


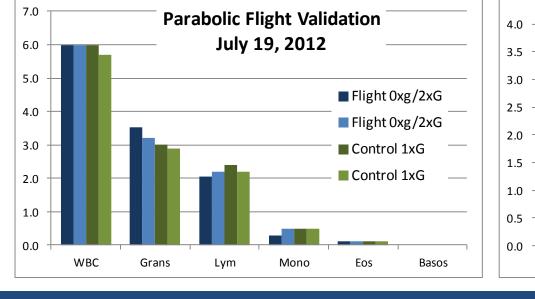


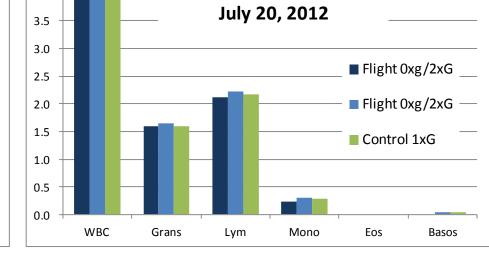










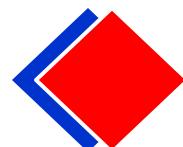


INFUSION POTENTIAL

This technology has been proposed for on-orbit demonstration by the Human Research Program. There is currently no other mature technology that can provide hematology data during spaceflight. This is primarily a spaceflight-enabling medical technology.

NASA TECHNOLOGY AREA ROADMAP

NASA OCT Grand Challenge Addressed: Space Technology Grand Challenge Mapping - Expand Human Presence in Space: Space Health and Medicine. NASA Technology Area Roadmap Addressed: Space Technology Roadmap Mapping: 2.3 Human Health and Performance Technology: Portable In-flight biosample analysis (ref: TA06 pg 15). JSC Topic and Subtopic(s) Technology Addressed: Area 2.1 and 2.3. The proposed device would directly 'provide healthcare capability for exploration missions" by allowing a capability to monitor hematological parameters during spaceflight.











Appendix C

JSC FY'12 CIF Support Project Details Innovation Charge Account

Electrospray Ionization for Water Monitoring

William T. Wallace and Thomas F. Limero / SF2 / Wyle Science, Technology, and Engineering Group

NASA

Contact Info: william.wallace-1@nasa.gov / 281-483-2846

PROJECT OVERVIEW

- Current methods for monitoring the water used on the ISS rely heavily on ground analysis of archival samples. Air monitors presently on board the ISS could be used for trace analysis of the water samples.
- Electrospray ionization (ESI) is a powerful and widely used ionization technique for analysis of biomolecules in solution and provides a potential means for introducing water into the current monitors.

RELEVANCE/ VALUE TO NASA

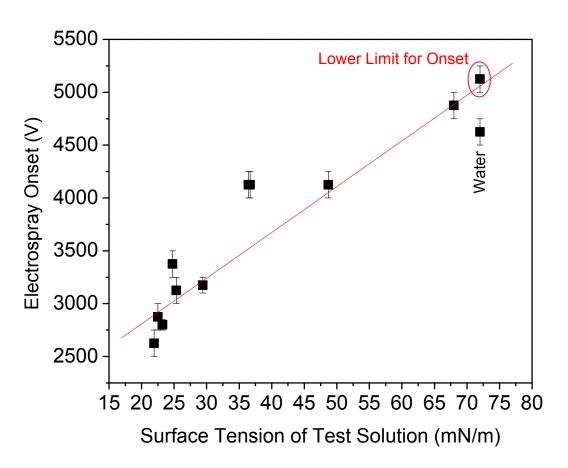
 The ability to analyze water samples (and possibility biological fluids) on orbit will limit/eliminate the need for sample return.

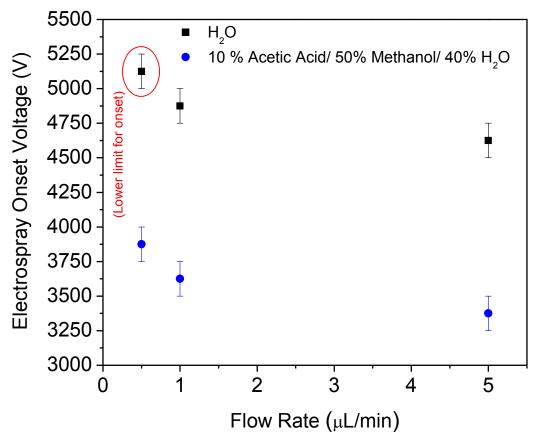
OBJECTIVES & OUTCOMES

- The objective of this project is to determine the optimal parameters necessary for electrospray formation.
- The product of this work is a report detailing the necessary conditions to use ISS water for electrospray.

INFUSION POTENTIAL

• The infusion potential of electrospray lies in its potential to be interfaced with types of instrumentation previously or currently used on ISS. These include differential mobility spectrometry (Air Quality Monitor) or ion mobility spectrometry (Volatile Organic Analyzer). The ability to analyze water samples in real time makes ESI a potential ionization source for future exploration missions.





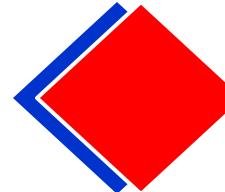
Effect of surface tension on ESI formation

Effect of flow rate on ESI formation

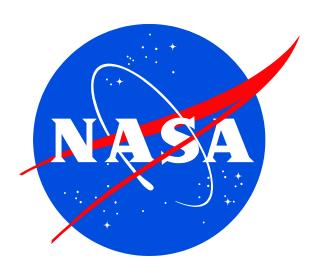
NASA TECHNOLOGY AREA ROADMAP

• This project is relevant to TA-06 Human Health, Life Support, and Habitation Systems, aligning with 6.4 Environmental Monitoring, Safety, and Emergency Response.

	Pro	ject: Electrospray Ioniz	ation for Water Monit	oring	
		Start Date: Jan 3, 2012	End Date: Apr 20, 2012		
Januar	ry 2012	February 2012	March 2012	Apri	1 2012
Kick-off					
	Ordering a	nd Construction of ESI			
			Testing of ESI with Ca	mera	
					Report



Testbed for Aerothermal Test Technique Development



A. BRANDON OLIVER & JESSIE POWELL

Applied Aeroscience and CFD Branch (EG3) brandon.oliver-1@nasa.gov, x37141

PROJECT OVERVIEW

 Assess the feasibility of developing a low-cost, smallfootprint wind tunnel facility for testing innovative techniques for obtaining aeroheating data

RELEVANCE/ VALUE TO NASA

 The cost of aerothermal testing can be considerably reduced if advanced data reduction techniques can be developed and verified

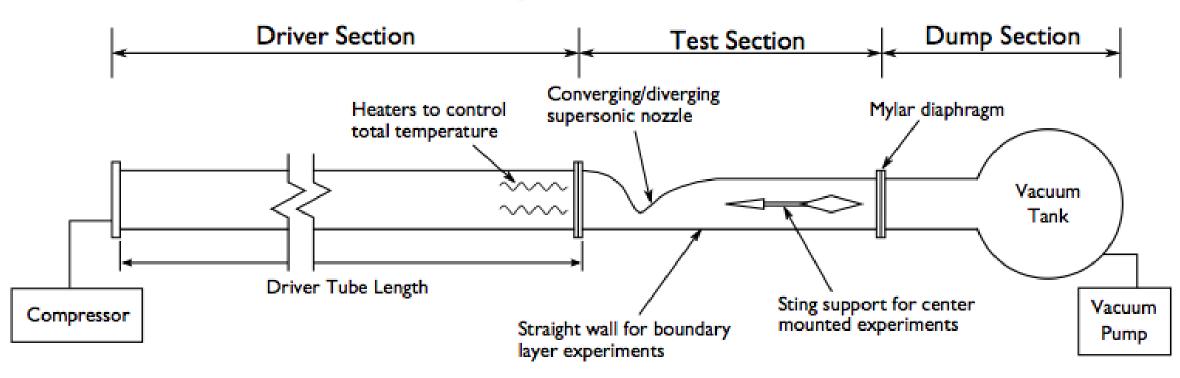
OBJECTIVES & OUTCOMES

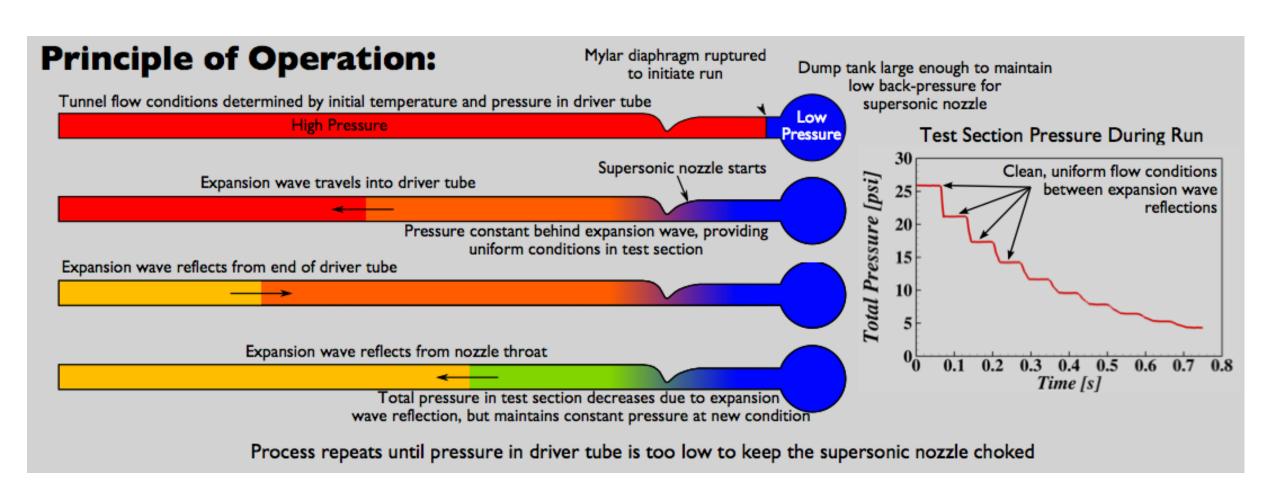
- Demonstrated that, contrary to analysis prediction, a reduced footprint driver tube would not provide the necessary performance without additional design work
- Performed the major design work for a conventional Ludwieg tube facility

INFUSION POTENTIAL

• Conventional aerothermal testing instrumentation and techniques require highly specialized facilities which greatly increase the cost of new vehicle development. Developing novel and innovative testing techniques can open the door to cheaper and more common facilities. More testing data means better computational and analytical models, which will reduce the cost to projects like Orion for developing aerothermal environments.

Schematic of a Typical Ludwieg Tube:

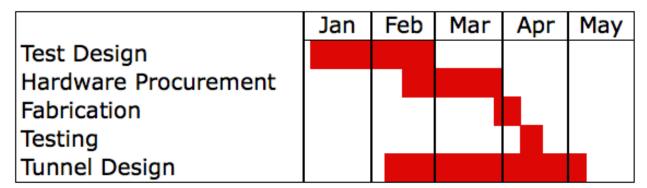




NASA TECHNOLOGY AREA ROADMAP

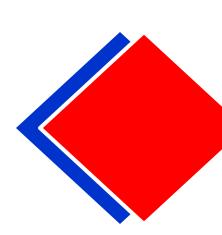
- Entry, Descent, & Landing Systems
 - Improve modeling and simulation of aeroheating environments, reducing the cost of vehicle development

PROJECT DEVELOPMENT SCHEDULE

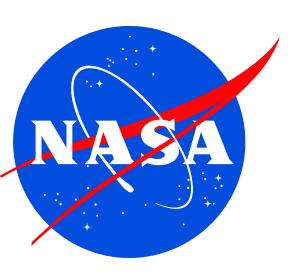


Project Start TRL (1-9): 2

Current TRL (1-9): 3



Rocket Fuel Synthesis by Fischer-Tropsch Process



PROJECT MANAGEMENT

Rama kumar Allada Ph.D, EC2 (ESCG) 281-461-5403/rama.allada@escg.jacobs.com

PROJECT OVERVIEW

- Sabatier has been developed to supply fuel during Mars missions by converting Martian atmosphere to methane.
 However, methane rocket technology is still under development, and current propulsion systems rely on liquid hydrocarbons.
- This study explores using fischer-tropsch to generate liquid hydrocarbon fuels for Mars return.

RELEVANCE/ VALUE TO NASA

- Gas-to-liquids (GTL) can produce kerosene (RP-1) that is compatible with current propulsion systems.
- Reduce the risks and costs associated with developing and certifying methane-engines. .

OBJECTIVES & OUTCOMES

- Assessed feasibility and process economics through models and detailed analysis.
- Provided a conceptual design of GTL fuel plant suitable for Mars exploration missions.

INFUSION POTENTIAL

- Specifically geared towards Mars exploration and can be inserted through ISRU programs.
- Commercially used to produce transportation fuels from natural gas. USAF is also looking at fischer-tropsch as an alternative to petroleum based jet fuel.

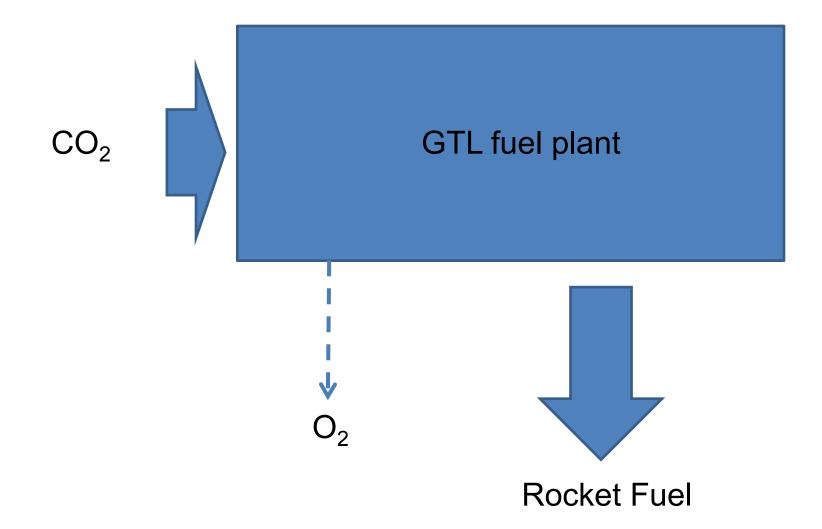
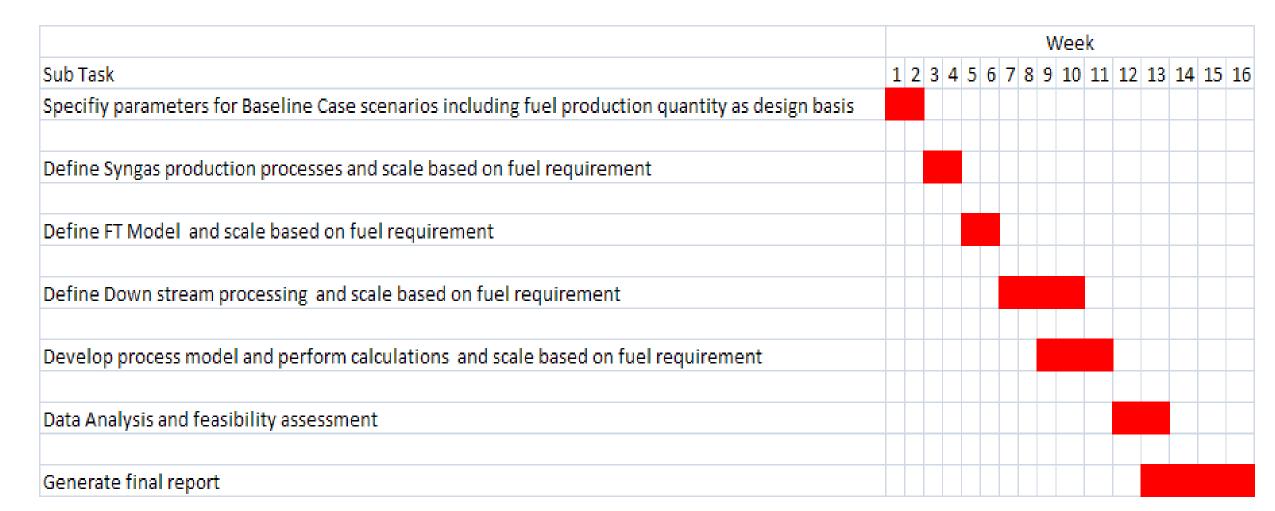
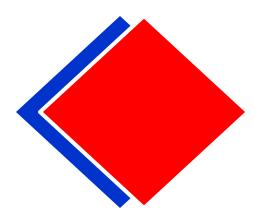


Figure 1. Conceptual Design of ISRU plant for Mars RP-1 production. The process produces RP1 along with some oxygen.. Technology is currently under review by NASA Tech Transfer office (MSC-25291-1).

NASA TECHNOLOGY AREA ROADMAP

•The focus of this project aligns to the TA07 roadmap with specific applicability to ISRU – Consumables Production





Modeling Limbless Locomotion Using ADAMS Locomotion Using ADAMS

PROJECT MANAGEMENT

Prashant S. Rao, Ph. D., Jacobs-Engineering and Science Contract Group Tel: (281) 461-5808; Email: prashant.rao@escg.jacobs.com

PROJECT OVERVIEW

• This study explored the modeling and simulation of limbless locomotion and its application to the space program. Several algorithms were studied: serpentine motion, serpentine motion with sinusoidal lifting, concertina and burrowing.

RELEVANCE/ VALUE TO NASA

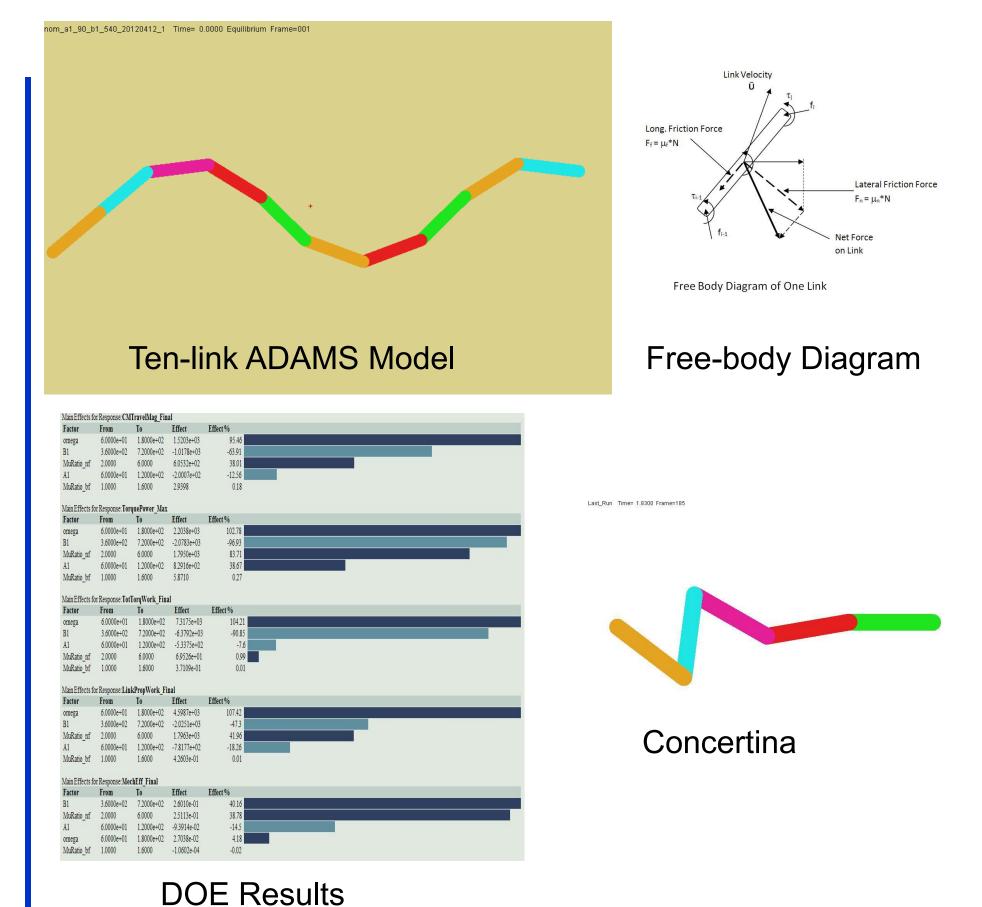
- Serpentine robots will be stable, able to traverse varied terrain (rocky, soft soil, liquid, narrow passageways ...)
- Can be sealed against the environment.
- Can be used to anchor to soil / aggregates.

OBJECTIVES & OUTCOMES

- Study how well ADAMS is suited for modeling limbless locomotion.
- Determine relationships between design parameters and performance.
- Correlate the ADAMS model with test data if avail..
- Investigated 3-link and 5-link &10-link models for serpentine motion, concertina motion, sinusoidal lifting, isotropic friction, simple burrowing model.
- Design of Experiments study to relate parameters to performance.
- Non-dim mechanical "efficiency" defined correlation with Dist/Work – 88%

INFUSION POTENTIAL

 Anchoring to asteroids identified as a top challenge for both robotic and manned missions to asteroids (TA04). Serpentine robots may be able to burrow into loose aggregate/soft soils and act as anchors. Serpentine robots will be particularly useful on missions to bodies with loose soils or with solid and liquid surfaces like Titan.

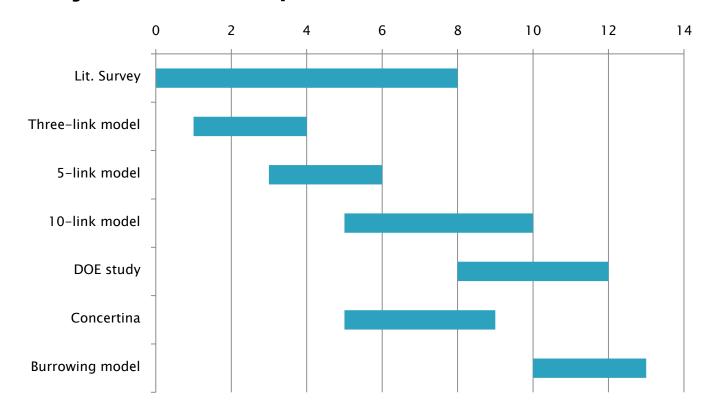


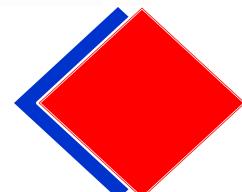
NASA TECHNOLOGY AREA ROADMAP

- TA04 Robotics: 4.2 Mobility (Extreme Terrain & Sub-surface); 4.3 Manipulation Technology/ NEA Human Mission
- TA07 Human Exploration Destination Systems: 7.1 ISRU; 7.6 Modeling, Simulation & Destination Characterization

PROJECT DEVELOPMENT SCHEDULE

Project development start: 1/31/2012



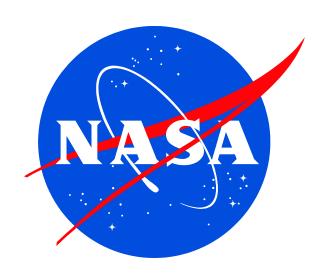


Pitch Synchronous Segmentation of Speech Signals

PROJECT MANAGEMENT

Anikó Sándor, Ph.D. & Kritina L. Holden, Ph.D., Human Factors and Habitability Branch, SF3

281-483-9726, Aniko.sandor-1@nasa.gov, 281-483-8829, Kritina.l.holden@nasa.gov



PROJECT OVERVIEW

• Pitch synchronous segmentation (PSS) is an algorithm that allows speech to be accelerated without a negative impact to intelligibility. At NASA it could be used to improve flight controller and crew communications.

RELEVANCE/ VALUE TO NASA

 Application of PSS and acceleration to speech channels could decrease workload and increase efficiency of crewmembers and flight controllers who have to monitor single or multiple channels of speech communication during missions.

OBJECTIVES & OUTCOMES

Objectives

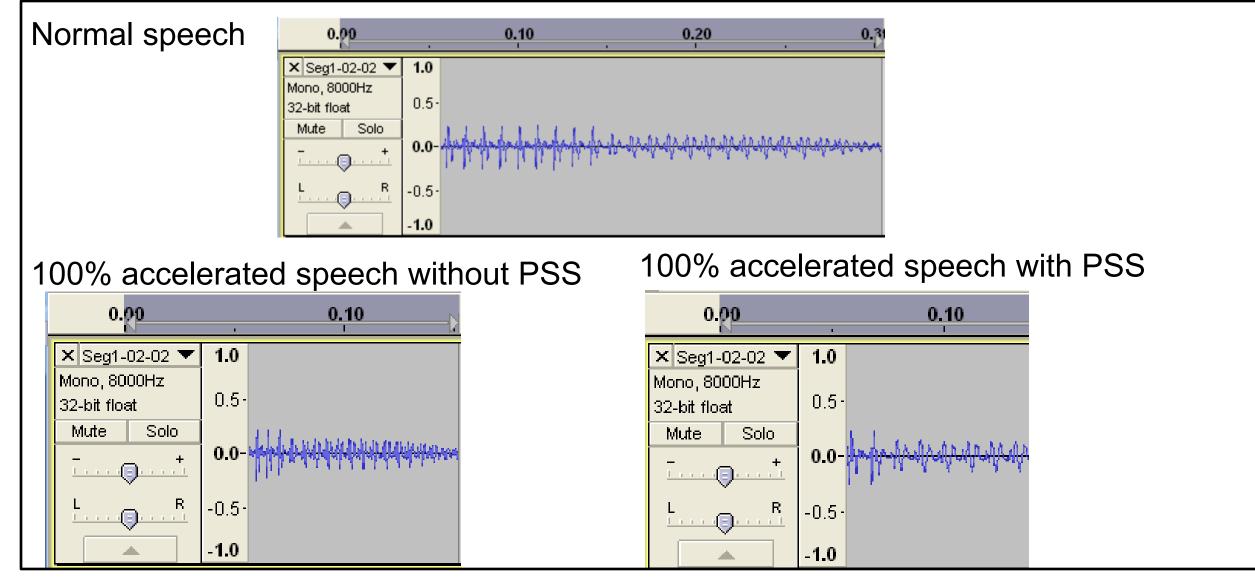
- Collaborate with the Naval Research Institute (PSS patent owners), and the University of Houston Clear Lake (also currently investigating PSS).
- Complete a feasibility assessment by conducting subject matter expert interviews regarding the potential benefits of PSS
- Create and evaluate demonstrations of processed sounds with crew and MOD representatives

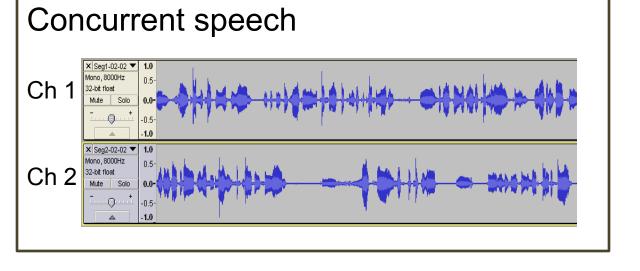
Outcomes

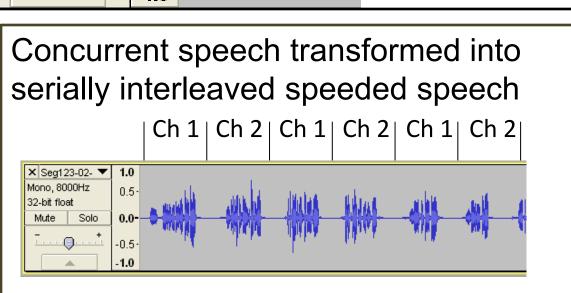
- Two key application areas were identified:
 - Immediate accelerated playback of ground control communication with crew (to confirm dialog that was missed)
 - Accelerated playback of recordings for troubleshooting anomalies
- Use of PSS for live, concurrent speech requires further research to determine the cost and benefits.

INFUSION POTENTIAL

- With further investigation and development, PSS and accelerated speech could be applied to current MOD operations, analogs (e.g., DSH), and ISS operations.
- This technology could also be applied in the air traffic control environment, or other control center environments that rely heavily on communication.







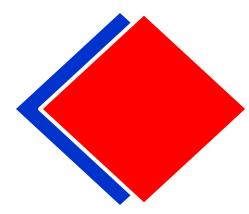
NASA TECHNOLOGY AREA ROADMAP

 TA07 – Human Exploration Destination Systems section / Mission Operations and Safety subsection

PROJECT DEVELOPMENT SCHEDULE

Weeks 1 - 8

- Meetings with US NRL and UHCL on prior and current PSS work
- Tour of Digital Voice Intercom System (DVIS) facility at Wyle
 Weeks 9 16
 - Researched ISS and Shuttle sound recordings in the NASA audio collection; sounds processed at NRL
 - Meetings and evaluation with crew, flight controllers, crew representatives



Augmented Reality to Enhance Crew Medical Training

PROJECT MANAGEMENT

Lui Wang / ER; William Buras / SA-Tietronix; Yoshino Sugita / SA-Wyle 281-483-8074 & lui.wang-1@nasa.gov . Collaboration: David Martin/SK2 Ultrasound Instructor; David Ham/SA Ultrasound System Integrator; Victor Hust/SK

Project Overview

Augmented Reality (AR) tools for medical training can provide real-time, in situ guidance, reducing training burden and improving crew proficiency. Recent advances in AR technology simultaneously reduce the technology's footprint while increasing effectiveness of training and real-time support.

Relevance / Value to NASA

NASA consistently searches for efficiencies in astronaut training. Our portable, intuitive tool will:

- Save crew training time while increasing proficiency
- Decrease need for ground support and enable on-orbit refresher training
- Can be expanded to additional training procedures

Objectives & Outcomes

The objectives were to:

- Identify the medical training procedure that would benefit from AR support
- Design the best hardware configuration for an AR prototype

The outcomes of this pilot project were:

- Identified medical training procedure for AR tool development (Ultrasound).
- Identified a series of tool features that would significantly improve training and operational support:
 - Visualize current and ideal image in visual field
 - 3D guidance of transducer position refinement
- Identified potential collaboration and bench-marking opportunities

Infusion Potential

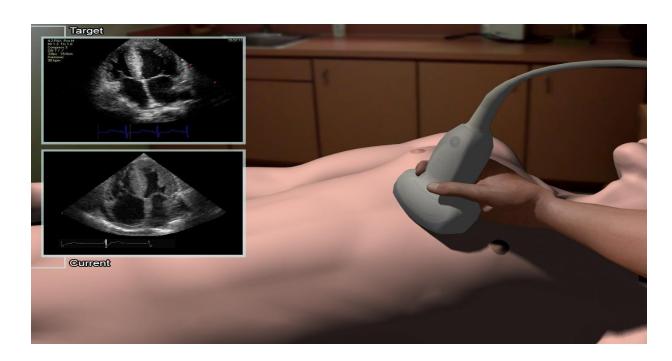
The technology will be matured and infused through series of demonstration with increasing fidelity from ISS training facility to on-orbit ISS DTO demonstrations. The ISS Program is striving to minimize crew time spent on training and reliance on ground support for operations.

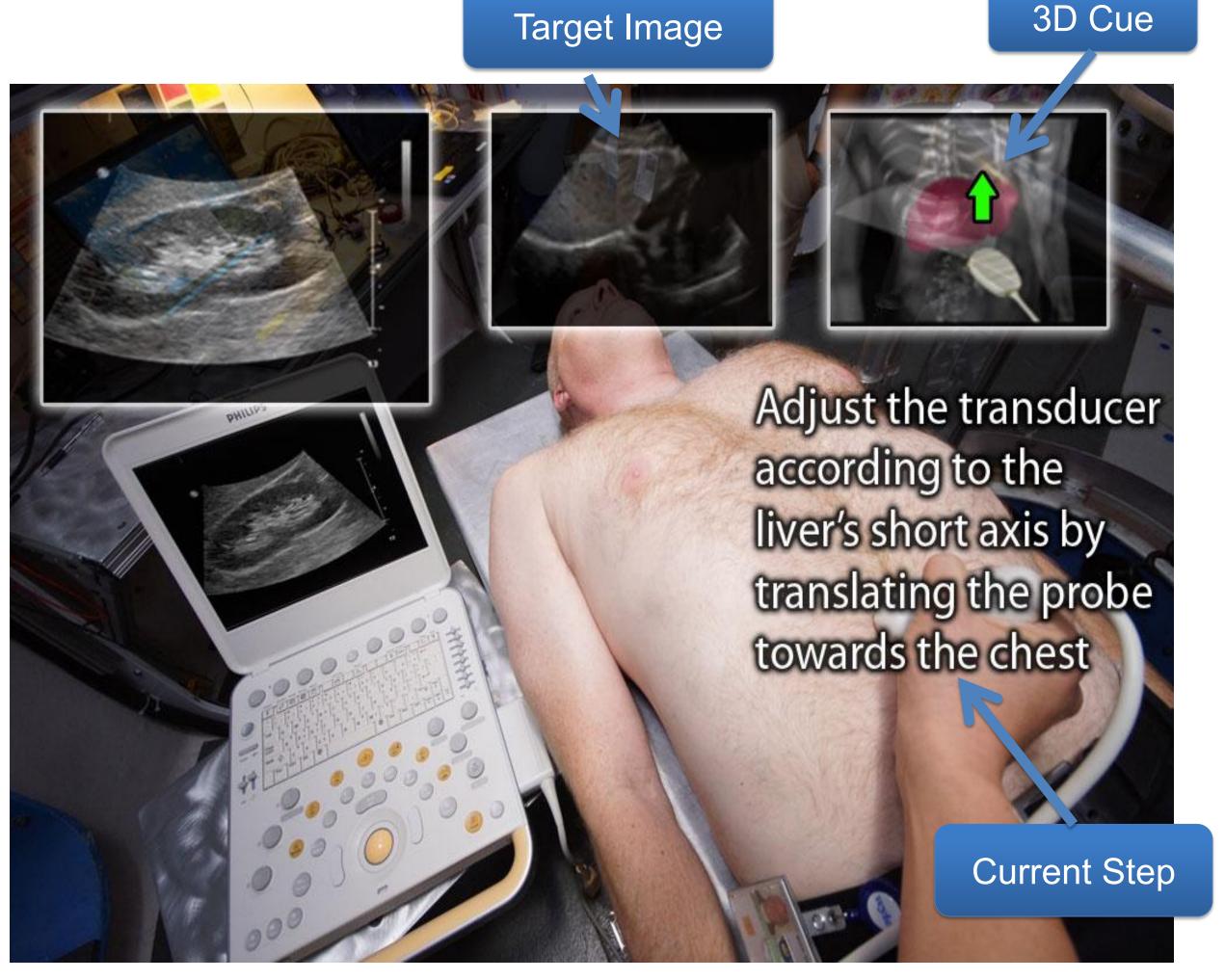
NASA Technology Area Roadmap

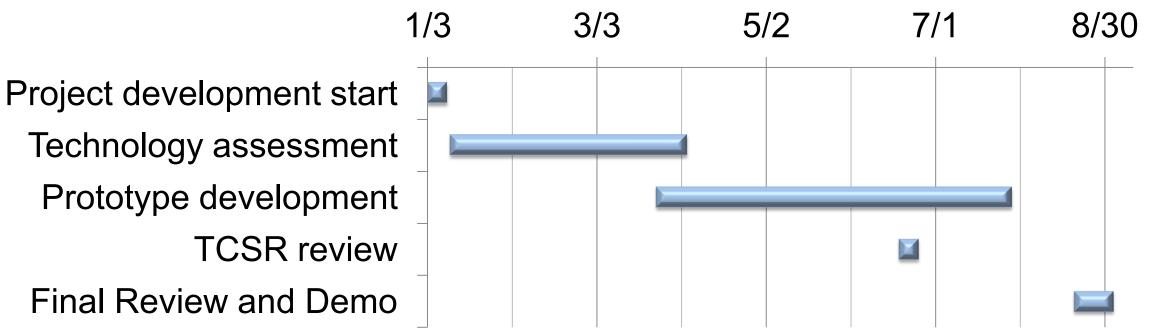
- 4.0/4.4 Human Systems Interaction (Just-in-Time human performance support),
- 4.0/4.5 Autonomy (enable crew autonomous operation and reduce dependency on ground support),
- 6.0/6.3 Human Health and Performance (enhance situational awareness, reduce cognitive overload),
- 7.0/7.5 Mission Operations & Safety (reduce human error, improve operational efficiency).

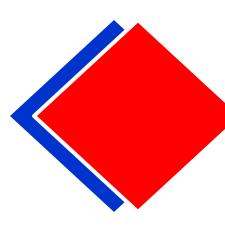












Project Start TRL: 2

Finish TRL: 3

Parachute Cord Tension Sensor

Satish Reddy, ESCG, 281-461-5533, Satish.Reddy@escg.jacobs.com Robert Wilkes, Jr., ESCG, 281-461-5216, Robert.WilkesJr@escg.jacobs.com

PROJECT OVERVIEW

 A small, simple, sensor using pressure film technology was developed to measure the Orion main parachute suspension line tension during deployment. Multiple design concepts were investigated and down selected to one that provided linear, low scatter measurements. Static and dynamic validation tests were performed that provided calibration.

RELEVANCE/ VALUE TO NASA

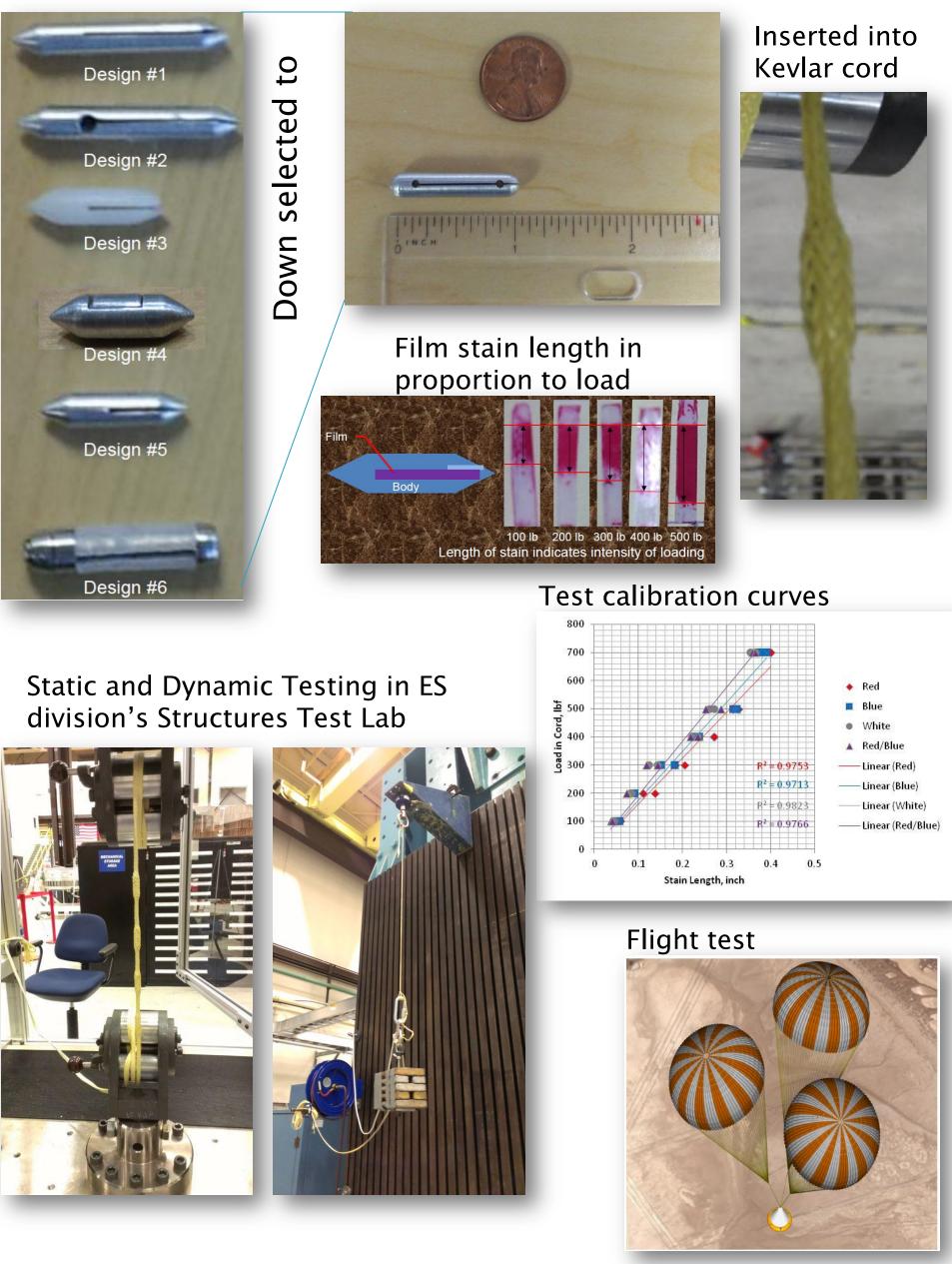
This invention allows accurate
 measurement of parachute cord loads
 that were previously estimated using
 analysis techniques. This will allow
 elimination of uncertainty load factors
 and better sizing of parachute hardware.

OBJECTIVES & OUTCOMES

 4 calibrated sensors delivered for a Orion CPAS drop test in the Yuma desert.

INFUSION POTENTIAL

- Presented to the Orion CPAS (the parachute system for the Orion/MPCV vehicle) program.
- Expected to be manifested to fly on a November 2012 drop test.



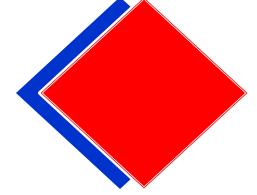
NASA TECHNOLOGY AREA ROADMAP

TA-09 – Entry, Descent and Landing

PROJECT DEVELOPMENT SCHEDULE

Project development start: 1/20/2012
Design/Analysis complete: 3/23/2012
Prototype manufacturing: 4/6/2012
Validation testing completed: 4/20/2012
ICA funded work completed: 4/19/2012

- Jacobs Technology funded final design completed: 6/10/2012
- ES division funded calibration test completed: 6/20/2012



Unmanned Microgravity Flight Program



P.I.s - J. Fox & M. Hart

Goal/Innovation: Microgravity experiments between 5 & 15 seconds require flight on a manned full-scale aircraft. Small micro-G parabolic experiments could be flown on an unmanned jet aircraft.

Unmanned aircraft flights can be scheduled faster, executed faster, turned around and re-flown faster and for a lower price than a full-scale manned aircraft.

Aircraft

- Troybuilt "DV8R" platform
- Wingspan: 83"
- Length: 87"
- Weight: 22 lbs dry
- Design thrust: 22-30 lbs
- -Heavy duty retractable gear with brakes
- Payload Capacity: ∼8 lbs
- Power plant: Kingtech K170-E gas turbine
 - ~ 40 lbs thrust
 - Idle ~ 34,000 rpm
 - Max ~ 123,000 rpm
 - Weight: 3.5 lbs.
 - EGT: 700*C
 - 25 hrs between servicing
- -Cost > \$8 K

-URL: http://www.youtube.com/watch?v=JCmiE7zNGTs

Accomplishments / Milestones

- 6/04 Project development start
 - Met with JSC RC club, NASA zero-g pilots, micro-g program lead
 - · Walkdown of full-scale Zero-G aircraft
- 7/08 First part ordered
- 7/28 Aircraft delivery
 - · Aircraft assembled, modified, & tested in 3 weeks
- 8/18 Payload completed
- 8/21 First engine test
- 8/30 Payload test on full-scale micro-g plane
- 8/31 Final review or report or demo
- 9/30 Est. Project development completed

Future Prospects

- Begin ground handling test trials end of Jan'12
- Scheduling future payload flight experiments
- Begin Autopilot test trials with funding allocation
- Begin negotiations with NASA Aircraft Ops & obtain flight certification expected late FY'12 Q2



Non-Powered Spectrophotometry



For Lighting

PROJECT MANAGEMENT

Toni A. Clark, P.E., Organization: SF3 281-483-0857, toni.clark-1@nasa.gov

PROJECT OVERVIEW

- This project researches the concept of documenting light spectra but without the use of a powered spectrophotometer.
- The premise is that an optical solution is sufficient to document spectra for light sources such as those on ISS.

RELEVANCE/ VALUE TO NASA

 The spectrum of a light affects crew health. This solution does not require power or a calibration cycle.

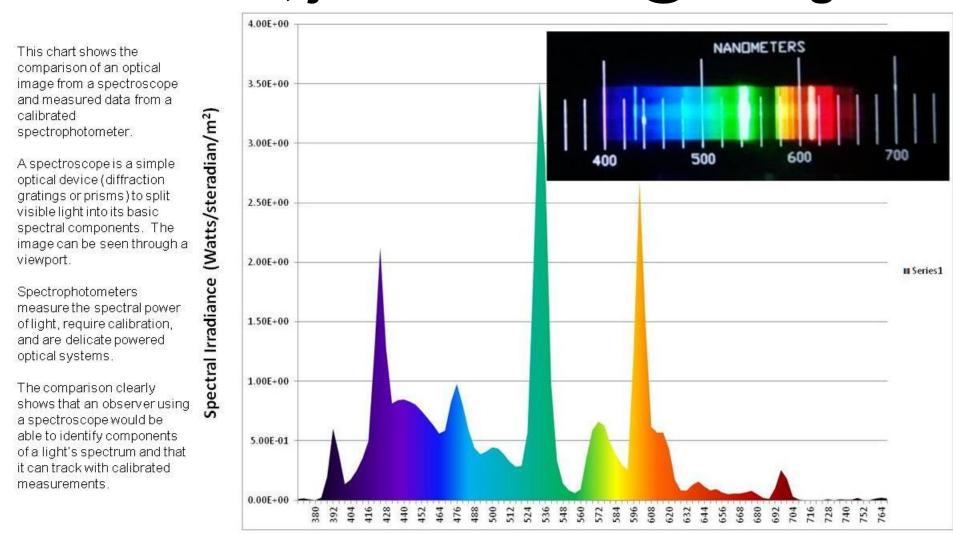
OBJECTIVES & OUTCOMES

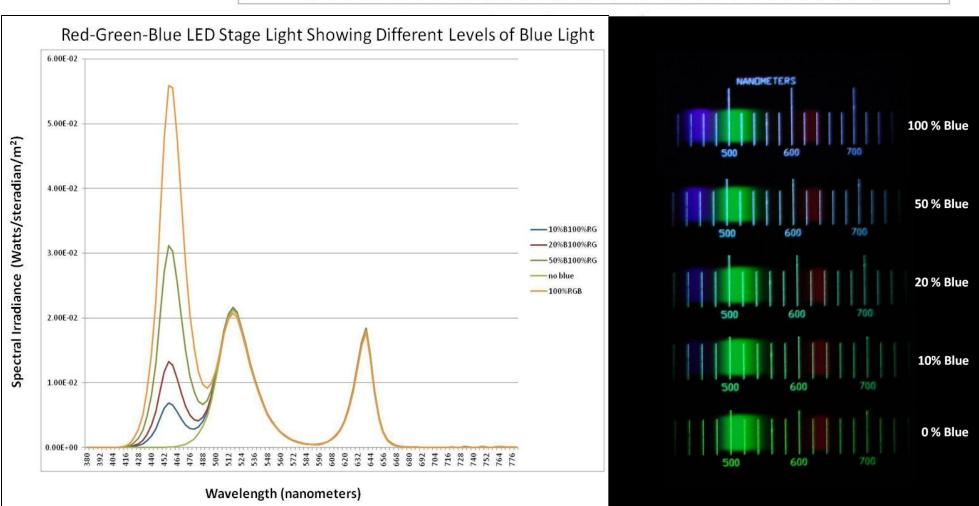
- Person must be able to distinguish unique spectra using spectroscope alone.
- Unique spectra are discernable to the naked eye.
- A camera can be put up to the viewport of a spectroscope to archive and document what the user sees.

INFUSION POTENTIAL

- The results from this project show that simple optical devices that use optics alone (diffraction gratings, prisms, lenses) can be used to document the spectrum of light.
- The ISS program needs a simple device to monitor lighting that has spectral performance criteria.
- Other applications that have spectral requirements can use this method.

Jim Maida, Organization: SF3 281-483-1113, james.c.maida@nasa.gov

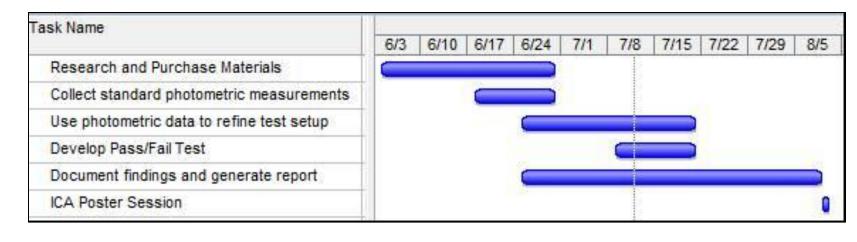




NASA TECHNOLOGY AREA ROADMAP

- TA3: Space Power & Energy Storage
- TA6: Human Health, Habitation, & Life Support Systems
- TA8: Science Instruments, Observatories, and Information **Systems**

PROJECT DEVELOPMENT **SCHEDULE**



Significant Milestones:

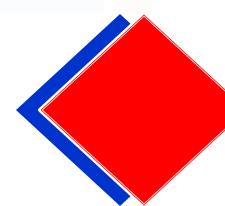
Purchase of hardware: Early June

Hardware Delivered/Test Start: Mid June

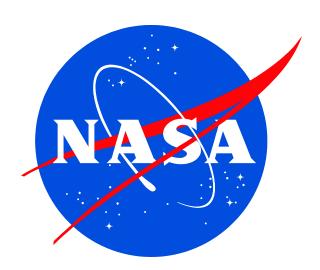
Lab verification of a sound concept: Late June

Detailed Testing and Documentation of Results: July

Project Start TRL (1-9): 2 Current TRL (1-9): <u>6</u>



Coupled Human-Space Suit Mobility Testing



PROJECT MANAGEMENT

Lindsay Aitchison/EC5, lindsay.t.aitchison@nasa.gov, x38657 Ishita Jain/EC5, Brad Holschuh/Mass. Institute of Technology

PROJECT OVERVIEW

Current EVA mobility studies only allow for comparisons between how suits move when actuated by a human and how the human moves when unsuited. Small wireless inertial measurement units (IMUs) will be implemented to provide coupled data collection on human and suit motions during suited mobility evaluations.

RELEVANCE/ VALUE TO NASA

A better understanding human-suit interaction will allow engineers to identify space suit design parameters to optimize EVA performance and reduce injury risk associated with fit and posture issues that can be implemented in EMU upgrades and/or future exploration suit designs.

OBJECTIVES & OUTCOMES

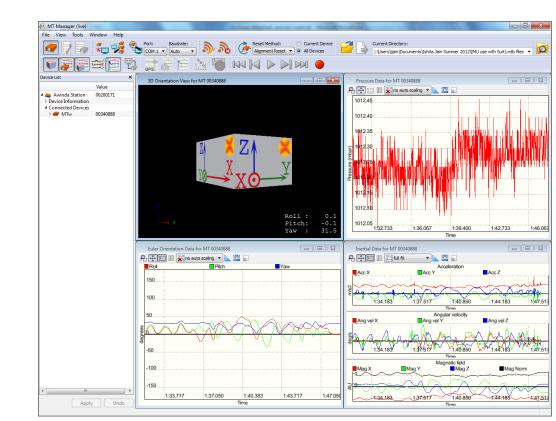
- •Purchased Xsens Technologies MTw development kit with six IMUs that can be coupled to Vicon MX for simultaneous motion capture
- •Developed analysis code, sensor set-up, and protocol to measure joint motion in shirtsleeves condition
- •Demonstrated minimal data loss when signal transmitted through pressurized space suit
- •Forward work: Team with ABF to
 - •Refine IMU analysis code using standard inverse kinematics approach similar to Vicon data analysis method
 - •Collect simultaneous data on Vicon and MTw systems to compare human and suit elbow, knee, and torso joint ranges of motion

INFUSION POTENTIAL

Benchmarking of current suit prototypes using coupled motion capture techniques will increase understanding of current design capabilities and limitations to aid development of new exploration suit requirements for FY13.

XSENS MTW IMU SYSTEM

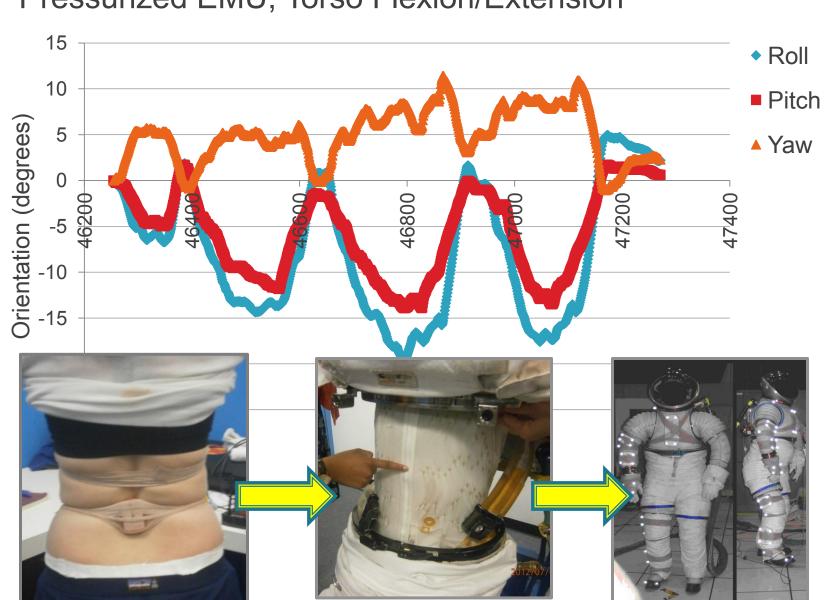




*Images taken from Xsens MTw User Manual

PRELIMINARY DATA

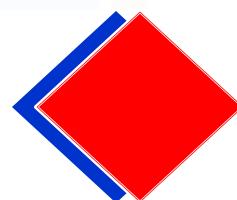
Pressurized EMU, Torso Flexion/Extension



NASA TECHNOLOGY AREA ROADMAP

This project supports the goals of Technology Area 06 EVA Systems Pressure Garment and Human Health and Performance HSI Tools/Methods.

	May	June	July	Aug	Sept
Purchase System					
Develop Analysis Code					
Code Validation					
Combined Vicon/IMU Testing					
Data Analysis and Reporting					



Foot Pedals for Spacecraft Manual Control

PROJECT MANAGEMENT

Stanley G. Love (CB and YA), Lee M. Morin (CB), and Mary McCabe (EV)

Phone: 281-244-2618; e-mail stanley.g.love@nasa.gov



Fifty years ago, NASA decided that the cockpit controls in spacecraft should be like the ones in airplanes. But controls based on the stick and rudder may not be best way to manually control a vehicle in space. A different method is based on submersible vehicles controlled with foot pedals. A new pilot can learn the sub's control scheme in minutes and drive it hands-free. We are building a pair of foot pedals for spacecraft control, and will test them in a spacecraft flight simulator.

RELEVANCE/ VALUE TO NASA

Engineers at JSC are now designing the cockpits of future spacecraft. A novel scheme for manual vehicle control may be of great value for their work.

OBJECTIVES & OUTCOMES

- Mechanical fabrication of the first prototype (four control axes) is now in work. Electronics fabrication is complete.
- The first prototype will be complete and available for simulator "test flights" by September 2012.

INFUSION POTENTIAL

• This project is directly applicable to the Flight Deck of the Future, the Multi-Mission Space Exploration Vehicle, and other JSC future vehicle projects. If successful here, it could find wider application in commercial spaceflight.



The DeepWorker 2000 submersible is a simple and successful vehicle that uses foot pedals for 4-axis motion control.

Pedals, articulation mechanisms, centering mechanisms, and microswitch wiring harnesses for this project as of July 9.



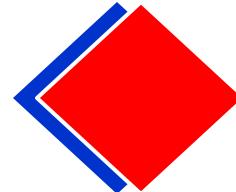
NASA TECHNOLOGY AREA ROADMAP

This project aligns with the following NASA Technology Area Roadmap areas:

- •TA 06-12, Human Health and Performance.
- •TA 04-9, Human-Systems Interfaces.

PROJECT DEVELOPMENT SCHEDULE





Project Start TRL (1-9): 6 (marine environment) Current TRL (1-9): 6 (spacecraft simulator)

Novel Ultrasound Assessment of Dynamic Muscle

PI: Jessica Scott/USRA, jessica.m.scott@nasa.gov; 281.483.8398. Collaborators: Natalia Arzeno/Wyle; Timothy Caine/Wyle; David Martin/Wyle; Jacqueline Perticone/NSBRI; Kyle Hackney/Wyle; Lori Ploutz-Snyder/USRA.

PROJECT OVERVIEW

• Reports on skeletal muscle atrophy are typically based on study of cross-sectional area, a measurement that ignores more detailed changes in skeletal muscle form and structure during contraction. The use of novel and portable ultrasonographic techniques to evaluate dynamic skeletal muscle morphology may provide critical information regarding the underlying mechanisms of microgravity-induced strength and performance loss.

RELEVANCE/ VALUE TO NASA

• Information characterizing skeletal muscle morphology is of fundamental importance for sustaining human presence in space and extending the exploration of our Solar system.

OBJECTIVES & OUTCOMES

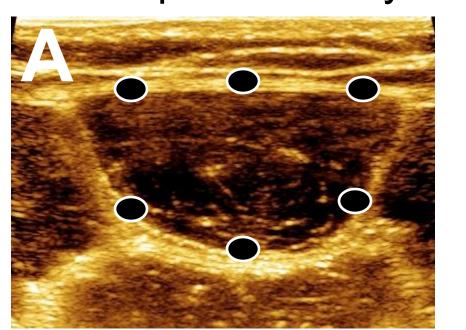
- We have completed baseline ultrasound data acquisition, developed a novel MATLAB analysis program, and have acquired pilot ultrasound data.
- The final product of this study will be a novel assessment method that can improve characterization of skeletal muscle morphology. An additional product will include a manuscript detailing the innovative technique and the applicability of assessing skeletal muscle form and structure in a microgravity environment.

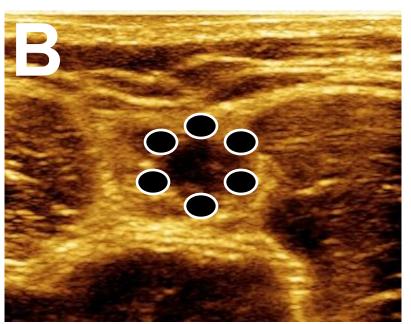
INFUSION POTENTIAL

- The new assessment technique will be used to further assess dynamic skeletal muscle structure using subjects participating in a microgravity analogue study. This study will specifically examine the impact of disuse on dynamic skeletal muscle morphology and function. Ultimately, it is anticipated that this technique will be used by long-duration astronauts as a tool to assess muscle structure and function in-flight so that augmented countermeasures can be implemented if declines are
- The five technique could also be used to enhance the understanding of skeletal muscle atrophy in bed-ridden patients and sarcopenia in older individuals.



Acquisition of dynamic skeletal muscle

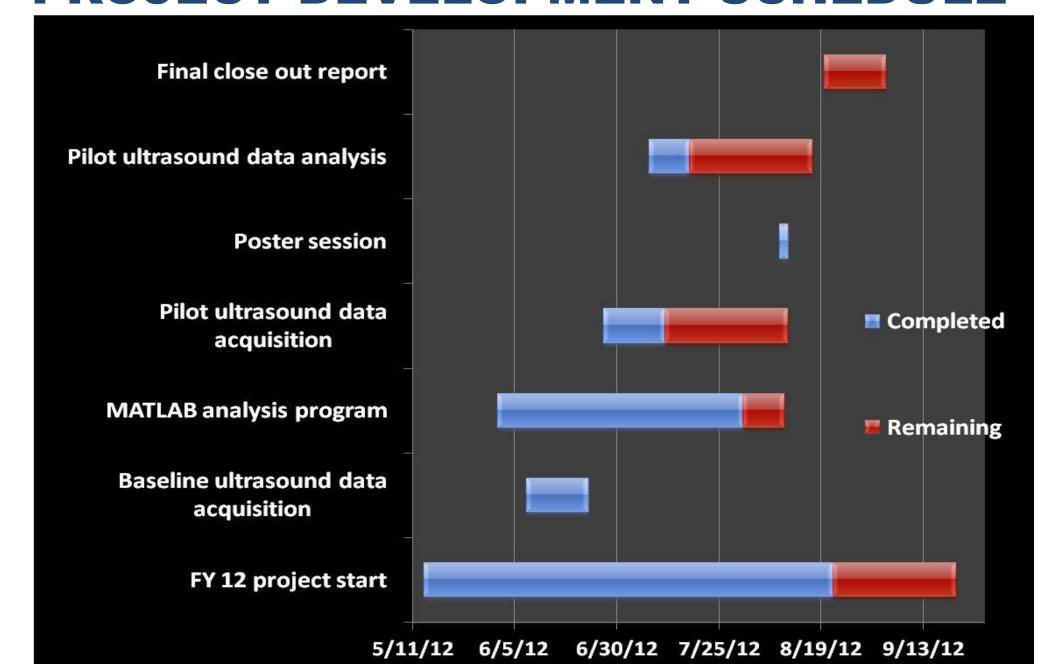




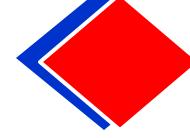
Tracking dynamic skeletal muscle (rectus femoris) in A) relaxed state; B) contracted state

NASA TECHNOLOGY AREA ROADMAP

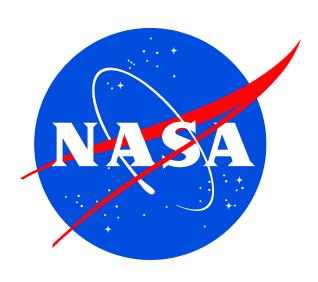
•This project directly focuses on the TA 06 'high priority' long duration health to provide a novel technology that will enhance a crew's ability to effectively, reliably and safely complete long-duration mission tasks.







Crew Health And Recreation Gear Exercise Device (CHARGED)



Michael Li, ESCG, 281-461-5376, feng.li@escg.jacobs.com
Satish Reddy, ESCG, 281-461-5533, satish.reddy@escg.jacobs.com
Christine Gebara, ESCG, 281-461-5398

PROJECT OVERVIEW

 A magneto-Rheological (MR) fluid based exoskeleton leg demonstrator was developed to help long duration exploration mission crews obtain exercise with entertainment during flight and at their destination.

RELEVANCE/ VALUE TO NASA

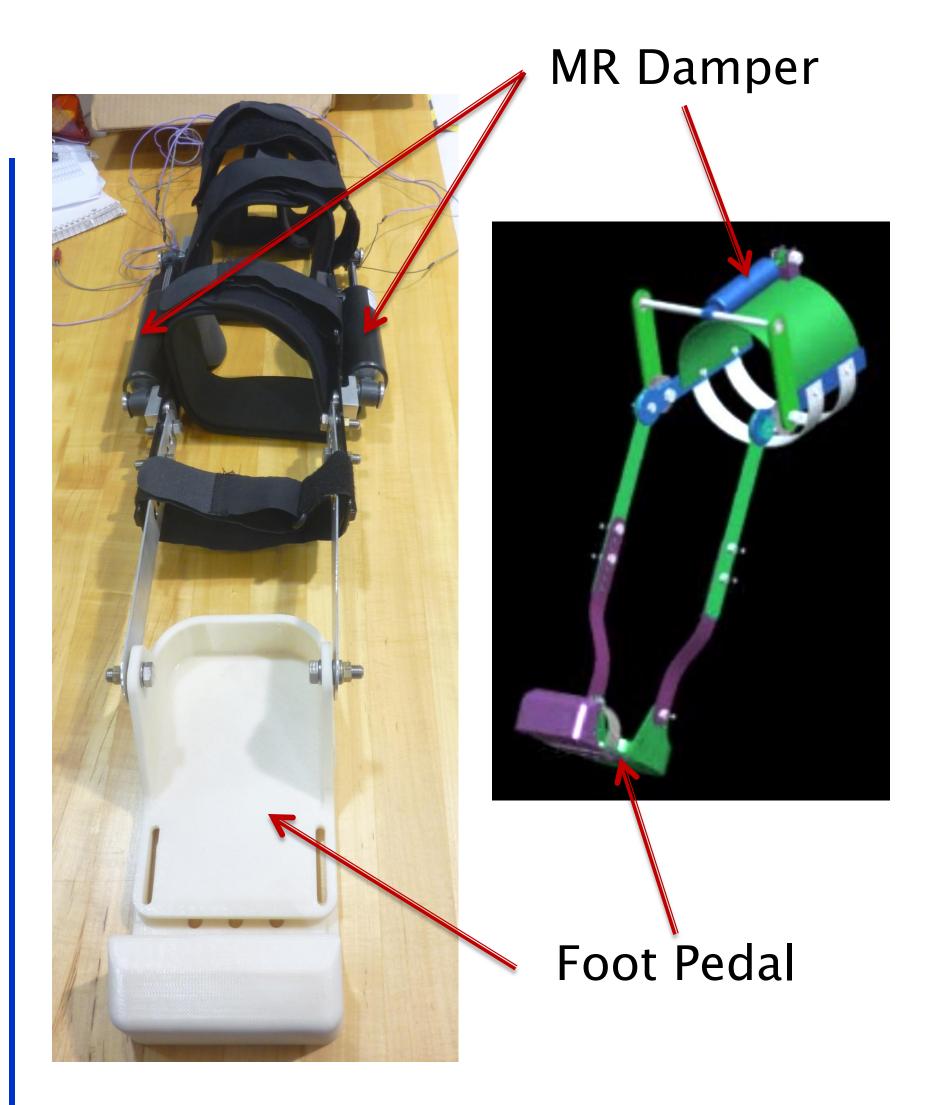
 This technology is to replace the bulky, high maintenance exercise devices (as used currently in the ISS) for long duration missions

OBJECTIVES & OUTCOMES

- Demonstrate that large compressive forces can be driven through the lower leg bones with the help of the foot pedal.
- A prototype of the leg demonstrator, math model, and test report.

INFUSION POTENTIAL

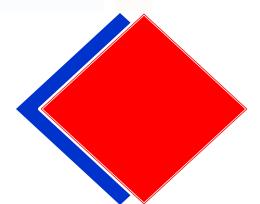
- The vision is to eventually develop a one-piece crew exercise gear to replace existing exercise devices, such as TVIS, CEVIS, ARED, and T2, and add a recreation / entertainment capability for long duration space missions. JSC/ER and SF have expressed interest in it
- The MR damper used in this hardware is a commercial off the shelf item extensively used in modern cars. MR technology has been demonstrated to work well on the ISS in reduced gravity



NASA TECHNOLOGY AREA ROADMAP

 TA-06 – Human Health, Life Support and Habitation Systems

WE	C Tack	Task Product/deliveables Milesto				Schedule (weeks)													
VV	idsk	Product/deliveables	Milestolles		2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
1	Spring 2012 ICA kick-off	Contract WAD	5/31/2012	•															
2	Design complete	CAD model or sketch	6/22/2012																
3	Fabrication complete	Prototype with foot pedal	7/13/2012																
4	Testing complete	Concept confirmation	7/20/2012																
5	IR&D poster session	I&RD poster and presentation	8/9/2012										♦						
6	Refinement complete	Refined/optimized prototype	8/31/2012													♦			
7	Project closeout	Final report and presentation	9/14/2012																♦



Compact Termination for Structural Soft-goods

PROJECT MANAGEMENT

Bob Wilkes, ESCG, 281-461-5216, robert.wilkesjr@escg.jacobs.com

PROJECT OVERVIEW

 Glass fiber offers unique advantages for structural applications, but is hampered by a sensitivity to bend radius. The goal of this project is to determine the geometric limits of a potted end termination, and to assess weight and volume savings over a traditional sewn pin & clevis termination..

RELEVANCE/ VALUE TO NASA

 Space environments are particularly harsh for the high-strength fibers we have come to rely on for soft structures. Kevlar, Nomex, Nylon, and other synthetic fibers are broken down by exposure to the combination of vacuum, atomic oxygen, and ultraviolet radiation. Glass fiber does not have this same susceptibility, but requires an end termination that does not bend its fibers.

OBJECTIVES & OUTCOMES

 A series of tests which vary the size of a potted end termination to determine the minimum size needed to maintain full strength of the webbing.

INFUSION POTENTIAL

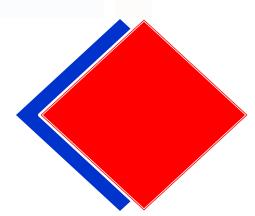
Damage-tolerant inflatable habitats



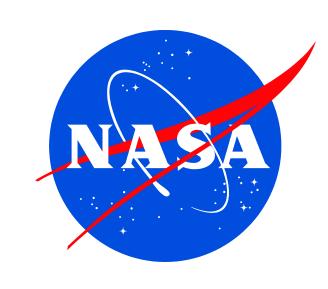
NASA TECHNOLOGY AREA ROADMAP

- TA-06, Habitation Systems
- Application is for Space Colonization, specifically for inflatable structures made from structural soft-goods

	Current Schedule	Wee	k End	ing da	ate								
	Milestones	6/15/2012	6/22/2012	6/29/2012	7/6/2012	7/13/2012	7/20/2012	7/27/2012	8/3/2012	8/10/2012	8/17/2012	8/24/2012	8/31/2012
		1	2	3	4	5	6	7	8	9	10	11	12
1	Analytical model development												
2	Procure / fab materials												
3	Produce samples												
4	Tensile test												
5	Summarize findings & report												



Inside-Out Manufacturing of Multifunctional Composites



PROJECT MANAGEMENT

Charles S. Hill, ES4. 281-483-8825, charles.s.hill@nasa.gov

PROJECT OVERVIEW

- Demonstrate process to manufacture a complex shaped composite structure with imbedded wiring and fluid handling without the use of tooling.
- Utilize the core as the tool and build parts from the inside-out, placing utilities before composite structure.

RELEVANCE/ VALUE TO NASA

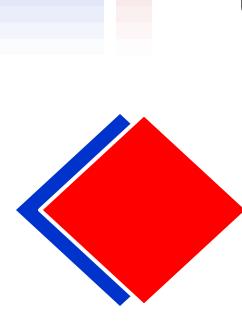
- Enables imbedding of service utilities in composite structures for protection and mass reduction.
- Reduces need for costly large tooling in low volume and prototype production.

OBJECTIVES & OUTCOMES

- Prove feasibility and illustrate utility of concept.
- Produced small complex part with wiring and fluid channels.

INFUSION POTENTIAL

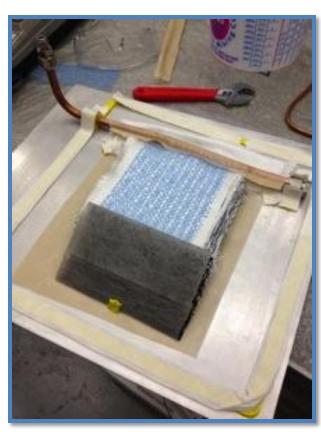
 Evolved manufacturing process may be utilized in next generation spacecraft design as well as commercial transport, aircraft, and automobiles.



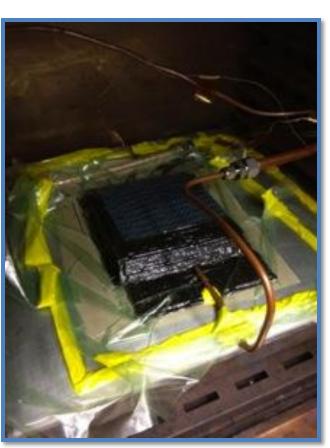












NASA TECHNOLOGY AREA ROADMAP

- •: TA-12 .2.2 Structures:
 - 12.2.2.1.1 Lightweight Concepts
 - 12.2.2.5.2&6 Innovative, Multifunctional Concepts

PROJECT DEVELOPMENT SCHEDULE

- Collecting imbed-able electronic circuits, fluid channel and fittings.
- Identifying formable rigid core flat sheet and foam-inplace core materials.
- Assemble core with utilities, layup, bag and cure.
- Test internal circuits and fluid channels.
- Report Complete
 - Project Start TRL (1-9): 2
- •9/27/2012

Current TRL (1-9): 3

Future Autonomous and Automated Systems Testbed FAAST

PROJECT MANAGEMENT

Angela Lenort/EG6

ph: 281-244-5491 e-mail: angela.n.lenort@nasa.gov

PROJECT OVERVIEW

FAAST is an R/C helicopter platform that is being developed by the Aeroscience and Flight Mechanics Division (EG) as a lowcost, low-risk, hands-on way for engineers to test autonomous and automated (A&A) system architectures, algorithms, and sensors. It is also envisioned as a platform for building trust in A&A systems among key stakeholders such as program/project management, crew members, and operators.

RELEVANCE/ VALUE TO NASA

Greater autonomy and automation in human spaceflight can:

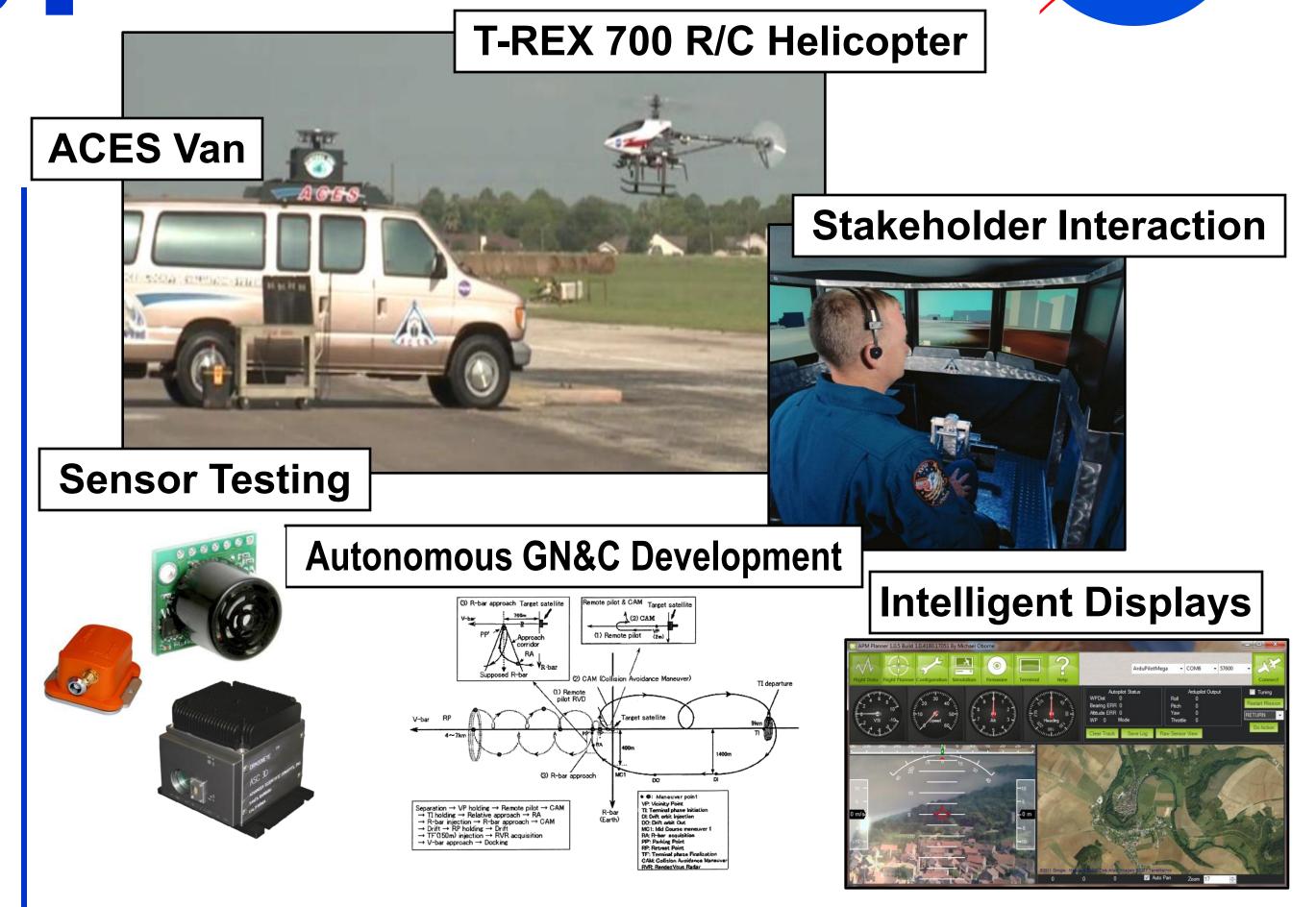
- Reduce lifetime operations costs by decreasing dependence on ground systems and increasing configuration flexibility,
- Increase the amount of time devoted to science objectives by reducing crew workload, and
- Enable the Agency goal of conducting exploration missions beyond LEO where communication lag is a concern.

OBJECTIVES & OUTCOMES

Our intended product is a system capable of performing autonomous waypoint navigation, enabling future research into autonomous rendezvous and docking, takeoff, and landing.

INFUSION POTENTIAL

- Perform JSC roof inspections for Center Operations.
- Potential Civil Air Patrol applications/partnership.

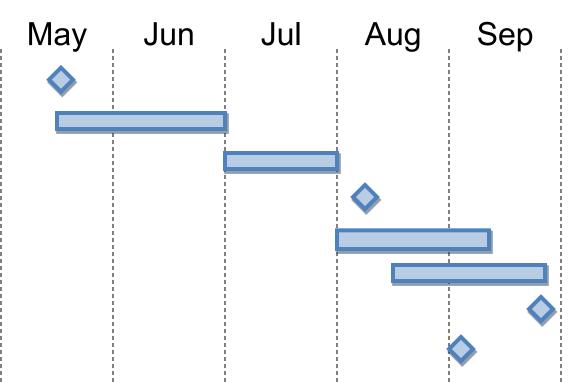


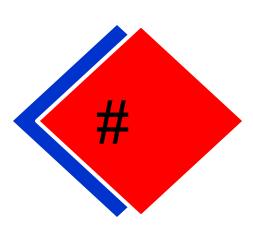
NASA TECHNOLOGY AREA ROADMAP

FAAST is aligned with the goals of TA04 (Robotics, Tele-Robotics, and Autonomous Systems) in the areas of Sensing & Perception, Mobility, Human-System Integration, Autonomy, and Autonomous Rendezvous and Docking.

PROJECT DEVELOPMENT SCHEDULE

Authority to Proceed (5/14/12) Sensor Research Sensor Procurement Poster Session Sensor Integration into Helicopter Platform **System Testing** System Demonstration JTWG and Senior Staff Briefings (9/1/12)





Project Start TRL (1-9): 2 **Current TRL (1-9): 3**

Interface Anywhere

PROJECT MANAGEMENT

Max Haddock, NASA, Human Interface Branch/EV3, 281.483.7241, maxwell.d.haddock@nasa.gov

Shelby Thompson, Lockheed Martin, Habitability and Human Factors Branch/SF3, 281.244.8701, shelby.g.thompson@nasa.gov

David Overland, Human Interface Branch/EV3, 281.483.4304, david.overland-1@nasa.gov.

PROJECT OVERVIEW

 Current interfaces require controls in which the crewmember must stop during their task and move to a monitor and input device. Our goal is to demonstrate virtual control of an interface through a blend of voice recognition, gesture control, and projection technologies.
 Whereby, making it possible to control an interface from nearly any location.

RELEVANCE/ VALUE TO NASA

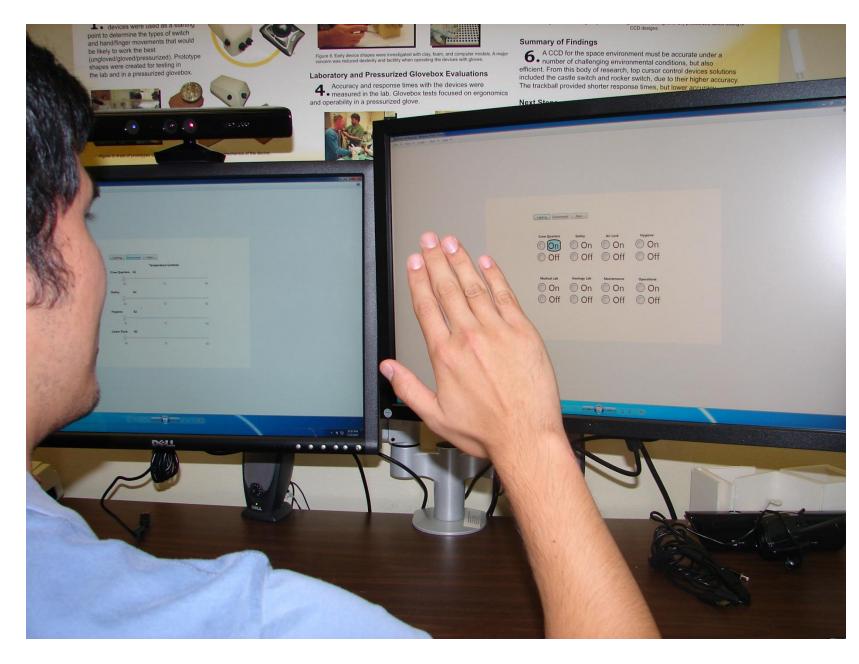
- Demonstrate the capability to decouple the control interface from a physical location in a spacecraft to any location.
- This all but eliminates crew productivity losses caused by work task interruptions to translate to physical control interfaces.

OBJECTIVES & OUTCOMES

- Conduct trade-studies between different technologies that would provide a mobile interface.
- Conduct human factors comparative evaluations.
- Produce a final report of the evaluations.

INFUSION POTENTIAL

- Project provides information that can be demonstrated in the Deep Space Habitat to outline further development.
- Commercialization using mobile interfaces and development of gesture technology.

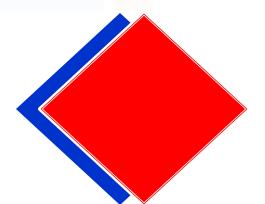


Participant manipulating a prototype interface via the Kinect system.

NASA TECHNOLOGY AREA ROADMAP

- This new use of technology aligns with TA04.4.1 Multi-Modal Human-Systems Integration, 4.4.4 Intent Recognition & Reaction, Sensing & Perception, Integration.
- Human performance information will align with the Human Factors & Performance under TA06.

Milestones	May	June	July	Aug
Hardware Trade Study				
Device Control Virtualization				
Gesture Recognition and Control Development				
Mid-term TCSR, Poster Session				
Voice Control Development				
Testing and Integration				
Engineering Evaluation and Final Report				



Gesture Commanding of a Robot While Wearing EVA Gloves

PROJECT MANAGEMENT

Neta Ezer, Ph.D., Anikó Sándor, Ph.D. Human Factors and Habitability Branch, SF3

281-483-2226, neta.ezer@nasa.gov, 281-483-9726, Aniko.sandor-1@nasa.gov

PROJECT OVERVIEW

- Gesture commands allow a human operator to directly interact with a robot without the use of intermediary hand controllers.
- There are two main types of hand gesture interfaces:
 - Data glove-based devices are worn by the human and capture hand movements through embedded sensors.
 - Computer vision techniques interpret hand movements by using the video feed from cameras.
- The goal of the project is to assess the feasibility of both types of approaches when the person commanding a robot is wearing EVA gloves.

RELEVANCE/ VALUE TO NASA

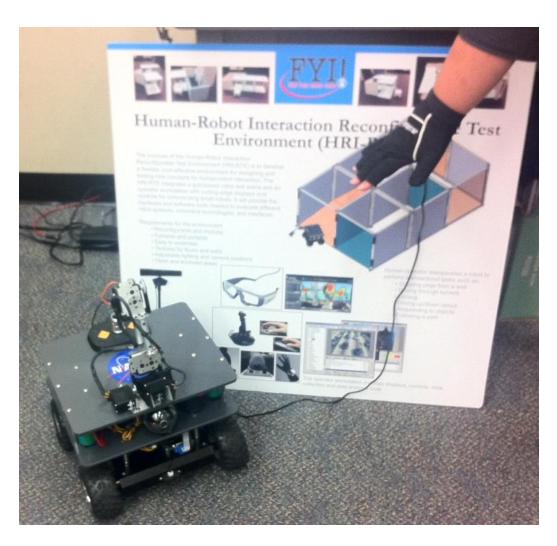
• Gesture commanding can be applied and evaluated with NASA robot systems. Application of this input modality can improve the way crewmembers interact with robots during EVA.

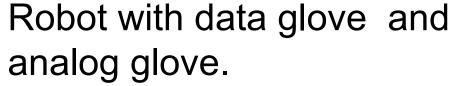
OBJECTIVES & OUTCOMES

- Program a small robot to accept inputs from a data glove inserted into an EVA glove and through computer vision software that can recognize gestures when the user wears an EVA glove. Evaluate approaches for increasing the recognition speed and accuracy of both gesture recognition methods.
- The outcome is a feasibility assessment of the data glove-based and computer vision techniques for commanding a robot through gestures. A demonstration of gesture commanding and outcomes of assessment will be provided.

INFUSION POTENTIAL

- If the results of the assessment show an advantage of one technique over another for commanding a robot with EVA gloves, in-depth studies can be proposed to refine and evaluate the gesture commanding method more thoroughly and develop a full gesture vocabulary.
- Work with the VR lab to share findings.
- Collaboration with Flight Deck of the Future (F.F)
- Technology developed will support the needs of the **Human Research Program**'s Directed Research Project on Human-Robot Interaction.
- The outcomes of the project can be used by other NASA systems that benefit from gesture recognition.



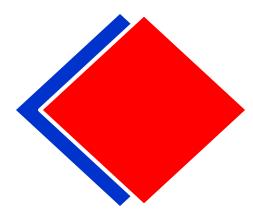




NASA TECHNOLOGY AREA ROADMAP

TA04 Robotics, Telerobotic & Autonomous Systems/RTA Systems
 Engineering

	June	July	Aug	Sep
Project Start				
Develop gesture recognition software				
Program robot to accept gesture commands				
Evaluate gesture recognition methods				
Demonstration & Poster Session				



Stitched Camera Array for Clearance Monitoring

PROJECT MANAGEMENT

Innovator: Zach Drewry – DX2/MOD Robotic Systems, zachary.b.drewry@nasa.gov, 281.244.7726

Collaborators: Matt McGee – DA7/Space Flight Training Management Office

Jim Hansen – DA7/Space Flight Training Management Office



• Quantify operational efficiencies gained by using video stitching software to provide robotics operators with enhanced 360° clearance monitoring in one view

RELEVANCE/ VALUE TO NASA

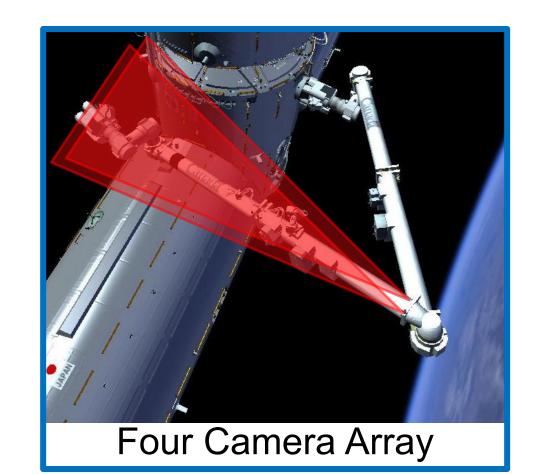
- Reduction in cost associated with mission plan-train-fly phases due to increased operational efficiency
- Advancing the state-of-the-art in clearance monitoring

OBJECTIVES & OUTCOMES

- Obtain and ready test rig, develop test plan/script/ scoring, evaluate stitched camera array with test subjects
- Deliverable white paper detailing the technology, test results, and suitability for use as clearance monitoring tool

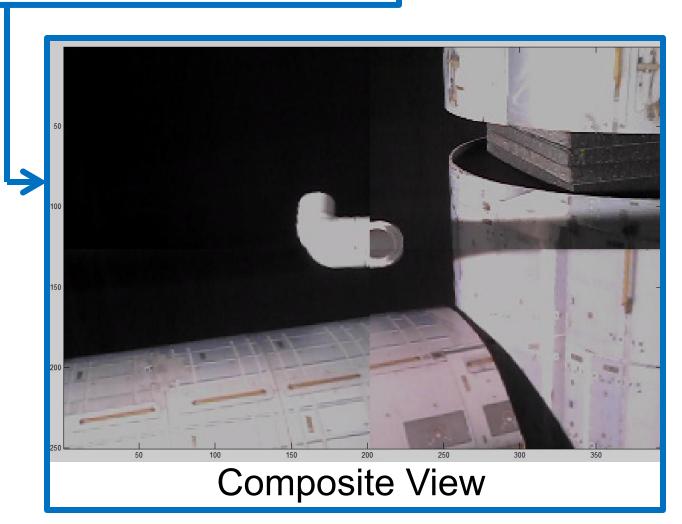
INFUSION POTENTIAL

- Technology could be deployed on Space Station Remote Manipulator System (SSRMS) or underwater Robotic Arm at Neutral Buoyancy Laboratory (NBL)
- Other commercial applications include clearance monitoring for submersible remotely operated vehicles (ROVs), surgical instruments, or tele-robotics





Video Stitching Device



NASA TECHNOLOGY AREA ROADMAP

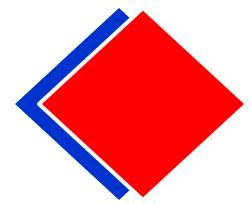
•TA4.4– Robotics: Human-Systems Interfaces

PROJECT DEVELOPMENT SCHEDULE

Obtain and ready test rig	5/14/2012	5/28/2012	2.2w	
Develop test plan, script, scoring	6/4/2012	6/25/2012	3.2w	
Evaluate Camera with subjects	7/2/2012	7/23/2012	3.2w	
Write White Paper	7/30/2012	8/27/2012	4.2w	
JTWG dry run and final brief	8/27/2012	9/28/2012	5w	

Project Start TRL (1-9): 3

Current TRL (1-9): 5



Solar Powered Ceramic Oxygen Concentrator

PROJECT MANAGEMENT

PI: John Graf/EC3; Collaborator: Mike Ewert/EC2

(281)483- 9226; john.c.graf@nasa.gov

(281)483-9134; michael.k.ewert@nasa.gov

PROJECT OVERVIEW

- Developed countries have ready access to 3 different kinds of medical oxygen: bottled, cryogenic, pressure swing adsorption (PSA) generated.
- Developing countries don't have this and it costs lives.
 - Pneumonia is the #1 killer of children there.
- Our project seeks to change that by providing oxygen.

RELEVANCE/ VALUE TO NASA

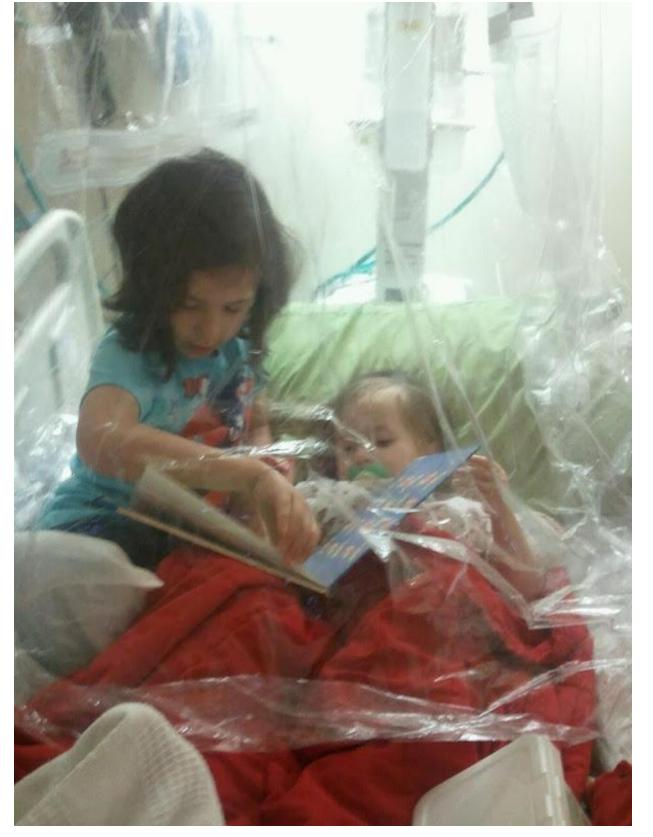
- Space Station also needs pure oxygen and can make it 'out of thin air' with a ceramic oxygen concentrator.
- Solid state device that produces oxygen up to 300 psig without a mechanical compressor.

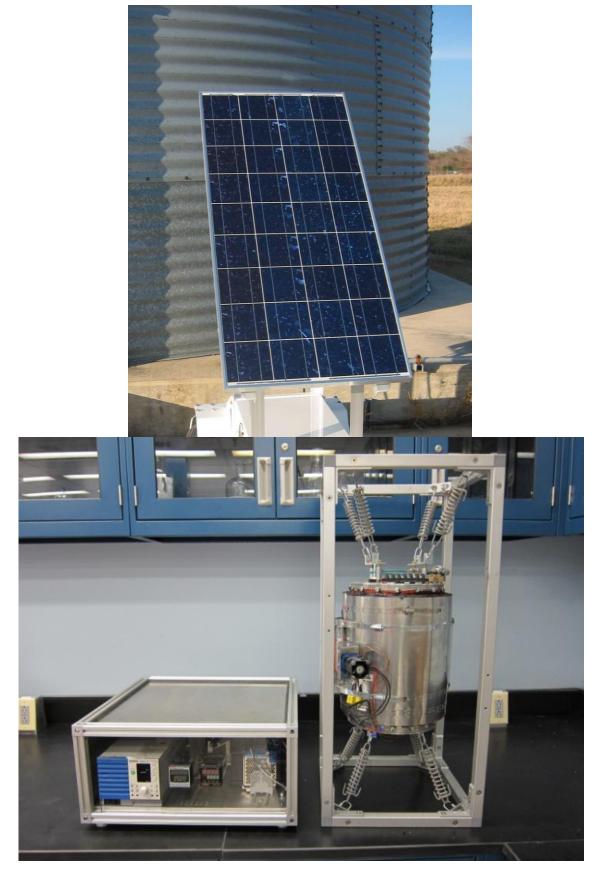
OBJECTIVES & OUTCOMES

- The objective is to convert the currently wall-powered (AC) ceramic oxygen concentrator to run on solar power.
- The product will be a proof-of-concept demonstration.

INFUSION POTENTIAL

- ISS has an immediate application post-shuttle.
- This is a very appropriate technology for medical oxygen in developing countries, which can save many lives.



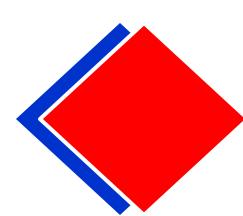


NASA TECHNOLOGY AREA ROADMAP

•Oxygen production is part of technology area TA06, Human Health, Life Support and Habitation Systems: Air Revitalization.

PROJECT DEVELOPMENT SCHEDULE

Solar power design & procurement
 Initial system assembly and test
 Oxygen storage sys. design & procurement
 ICA poster presentation
 Testing
 May-July
 August
 Aug/Sept
 Sept

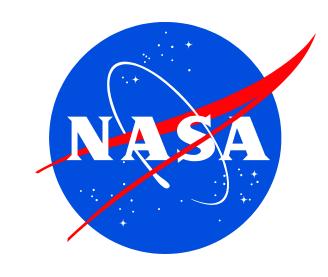


Project Start TRL (1-9): <u>2</u>
Current TRL (1-9): <u>3</u>

Radiation Mitigation Theory

Innovator: Carl Swopes, WSTF-Jacobs, (575) 524-5123, carl.e.swopes@nasa.gov Collaborators: Vernon Natewa, WSTF-Jacobs, (575) 524-5545, v.natewa@nasa.gov,

Michael Wnuk, University of Wisconsin, (414) 217-6665, mwnuk1@wi.rr.com,



PROJECT OVERVIEW

- This research is utilizing a recently discovered, math based color model. Using "Voltage as a function of time" [V(t)] equations with 3 new, unique, proportional, circular constants based on the golden ratio proportions.
- This peer reviewed "color model theory" argues that "color" is applicable to the entire electromagnetic (EM) spectrum, not just the visible light spectrum..
- An understanding of the mechanics of color via a proven, math based color model theory will facilitate the development of a radiation mitigation theory.

RELEVANCE/ VALUE TO NASA

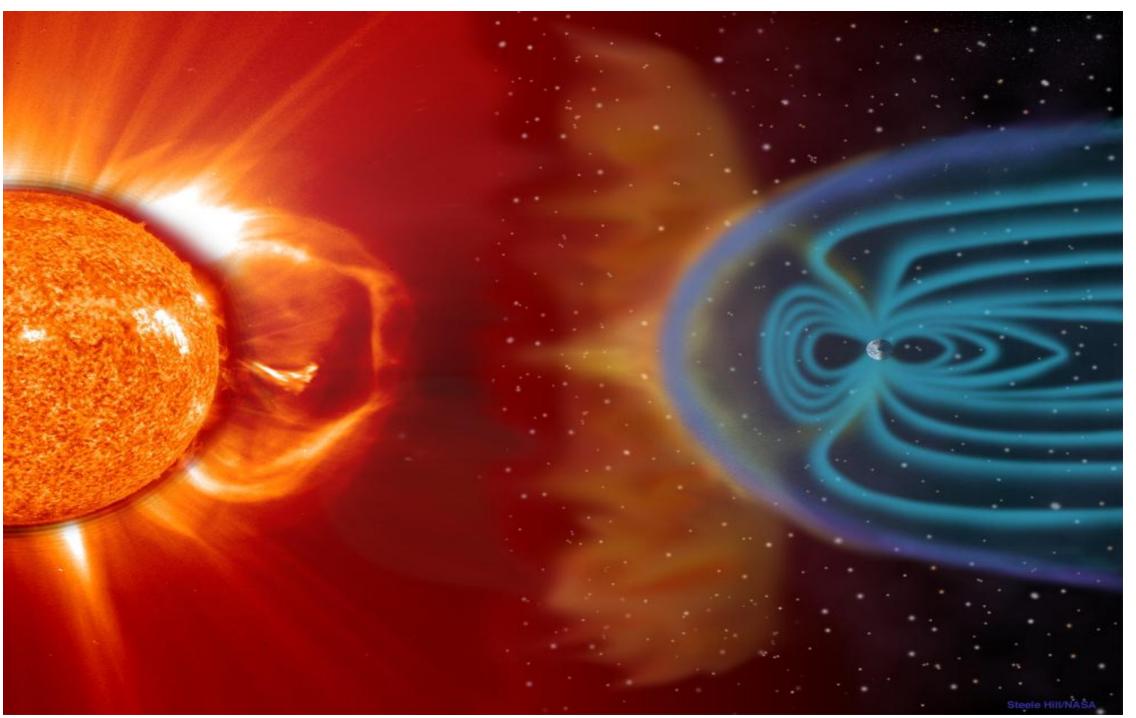
• A radiation mitigation theory will lead to the development of new technologies and/or materials in science and engineering. This will result in the mitigation of radiation sickness for astronauts and space colonists.

OBJECTIVES & OUTCOMES

- Research has identified a compatible math based color model represented by two exponential curves. .
- A final report on the findings will be provided.

INFUSION POTENTIAL

- Protect astronauts and space colonist from radiation sickness in NASA's space exploration programs.
- Protect power grids from radiation storms.
- Reduce line loss in power distribution systems.
- Reduction of heat in electrical components.
- Stealth technology to cancel or mitigate unwanted signals.

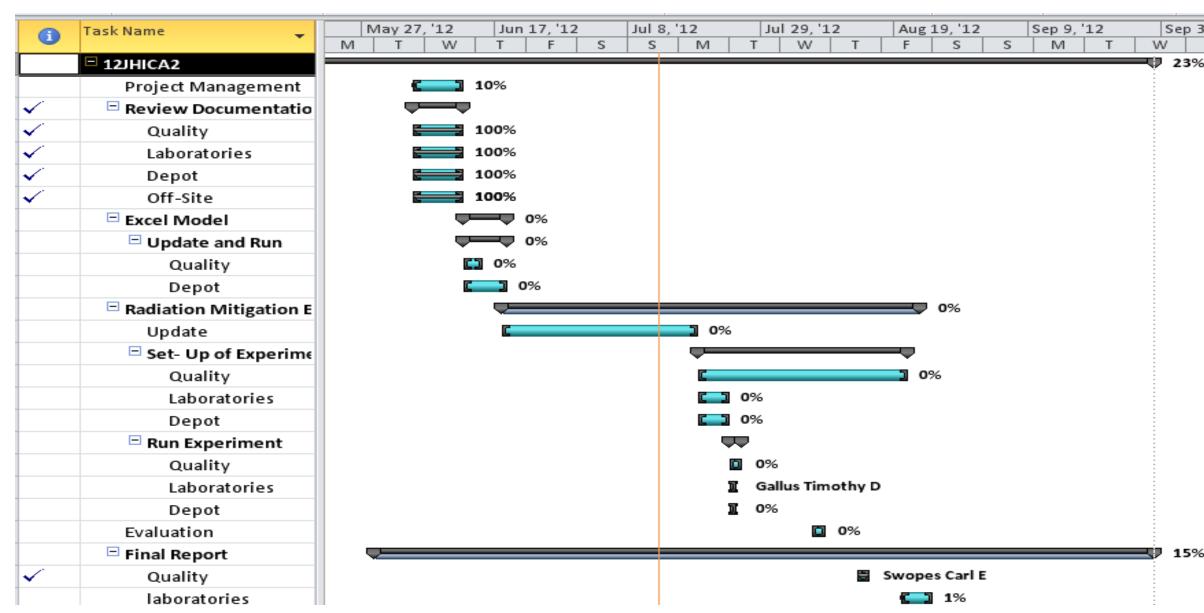


NASA/Solar Dynamic Observatory - sunearththemeSDO.tiff

NASA TECHNOLOGY AREA ROADMAP

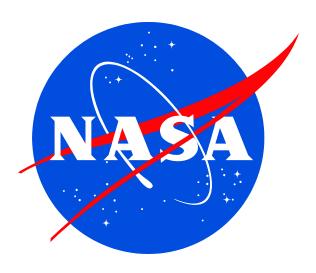
•TA06 Human Health, Life Support and Habitation Systems WBS 2.5 Radiation; TA06 Radiation Mitigation/Biological Countermeasures.

PROJECT DEVELOPMENT SCHEDULE



Project Start TRL (1-9): 1
Current TRL (1-9): 1

Transparent and Instrumented Suit HUT for Mobility and Joint Strain Measurements



PROJECT MANAGEMENT

Sudhakar Rajulu, Human and Environmental Factors Div, NASA JSC

Matt Cowley, Lockheed Martin, Houston, TX Joscelyn Mejias, Rice University, Houston, TX *

PROJECT OVERVIEW

Poor suit fit or functional design reduces performance and with frequent and strenuous suited training, can lead to injury. Data on human-suit interaction is difficult to obtain, but needed to improve future designs. This transparent hard upper torso (HUT) helps designers improve the quantity and quality of suited human data.

RELEVANCE/ VALUE TO NASA

Optimal suit designs reduce injury, increase comfort and improve performance.

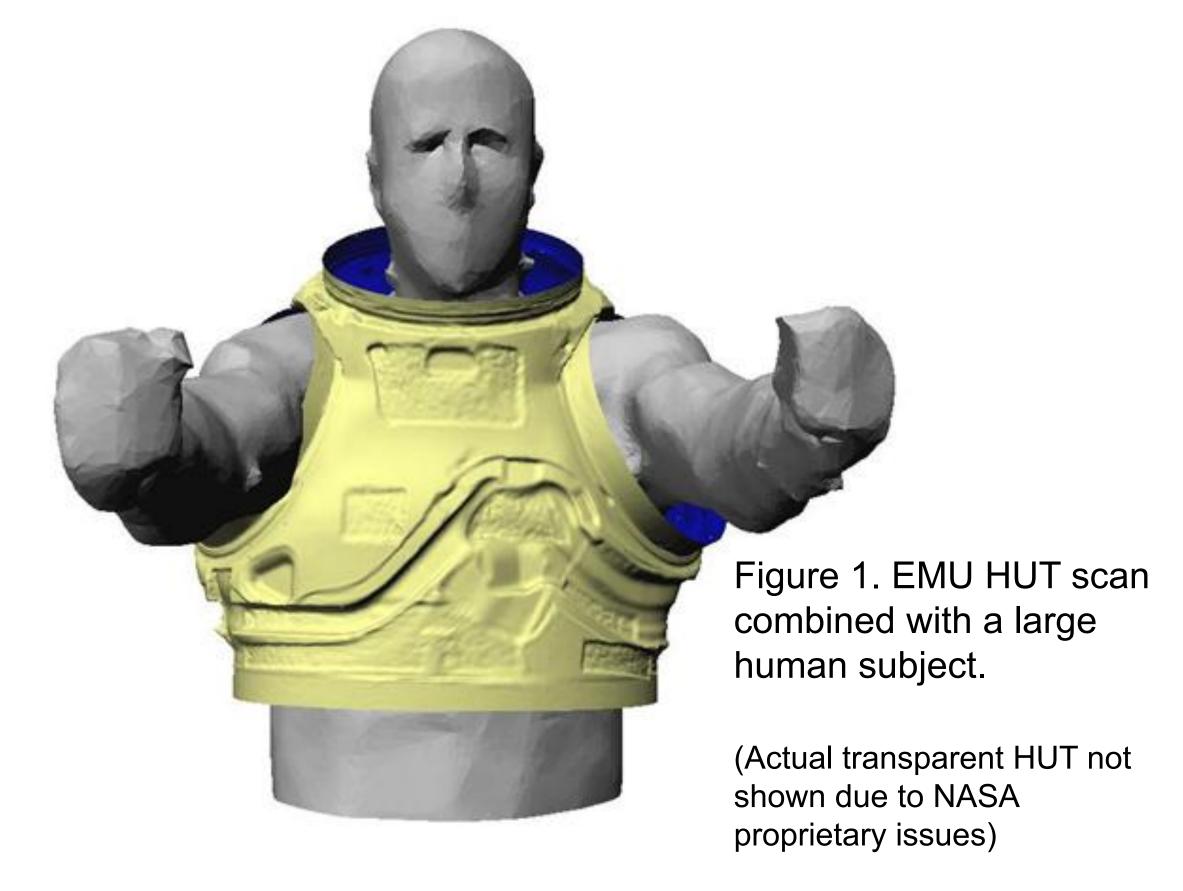
OBJECTIVES & OUTCOMES

A transparent EVA-type HUT prototype was designed and built. The HUT is transparent and measurement friendly. This prototype allows for dynamic fit, mobility, and human-suit contact measurements to be made.

Following manufacture, pilot testing will quantify the data collection improvements.

INFUSION POTENTIAL

This prototype should greatly increase both the amount of data on suit-human interactions as well as the overall fidelity of the data. If deemed successful by stakeholders, this technique will be repeated in future suit design and development processes

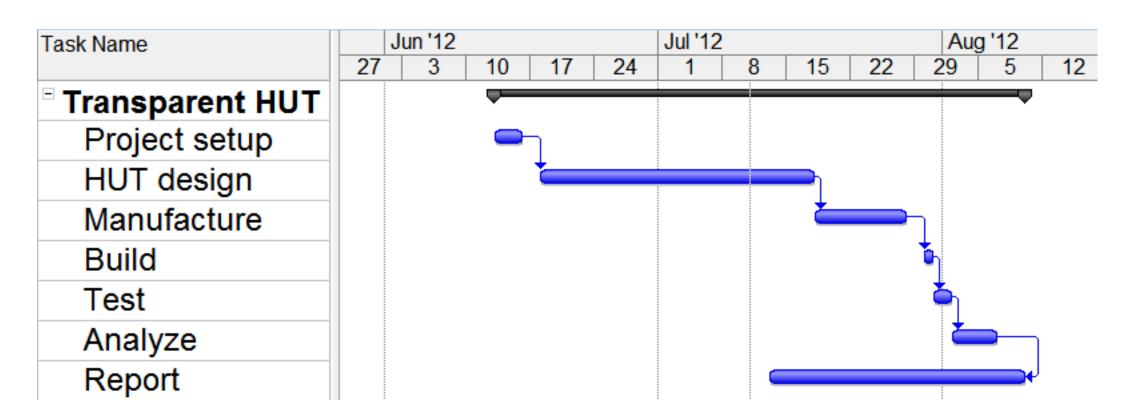


NASA TECHNOLOGY AREA ROADMAP

This project applies to the following roadmaps

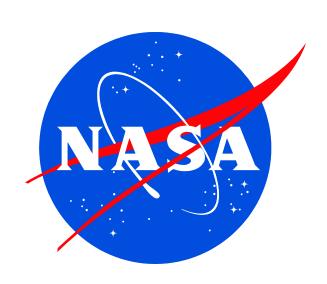
• TA06: 2.2.1 Pressure Garment

• TA07: 7.3.1 EVA Mobility



^{*} This investigation was sponsored in part by the National Space Biomedical Research Institute through NASA NCC 9-58

Textile Strain Gauge For Inflatable Structures



PROJECT MANAGEMENT

Doug Litteken, ES2, x30574, douglas.litteken@nasa.gov Cory Simon, EV3, x31722, cory.l.simon@nasa.gov

PROJECT OVERVIEW

 Develop a gauge that can measure strain and thus load in the straps that make up the restraint layer of an inflatable structure. Current designs use strain gauges on metallic clevises at the ends of each strap, but only provide data at these distinct points.

RELEVANCE/ VALUE TO NASA

 A textile gauge will provide load data throughout the length of the strap and over the surface of the structure, which will allow for better analytical predictions and models and has potential use as an on orbit health monitoring system.

OBJECTIVES & OUTCOMES

- Initial design review was completed through technology research and collaboration of similar designs.
- Small scale testing was completed with a variety of potential solutions.
- Final gauge device was developed and tested with integration on a full scale strap in a tensile test machine to calibrate measured strain vs load.

INFUSION POTENTIAL

- Immediate implementation in upcoming Inflatable Structures testing.
- Can be applied anywhere that axial strain in a textile is important including the CPAS program and the automobile industry (seatbelts).

FINAL DESIGNS:

DESIGN #1

Conductive thread sewn onto fabric using a cover stitch (Collaboration with Guido Gioberto, University of Minnesota) – As the fabric is stretched, the resistance in the stitch changes.

DESIGN #2

COTS Conductive polymer material to be adhered to fabric strap - As the fabric is stretched, the resistance in the polymer changes.

NASA TECHNOLOGY AREA ROADMAP

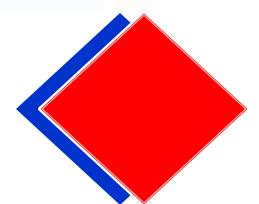
• Direct implementation with expandable structures, as mentioned as a Human Exploration Destination System in 7.4.2 Habitat Evolution.

PROJECT DEVELOPMENT SCHEDULE

May 14 – August 31

- May 25 Literature review complete
- July 6 Down-select design solutions
- August 6 Execute full scale testing
- August 28 Present final results

Task Name	May '12	June '12	July '12	August '12	
Literature Review/Collaboration Research					
Potential Design Selection					
Small Scale Testing					
Procurement/Final Development					
Full Scale Testing					
Analysis and Calibration					
Poster Session/Present Results					



Ion Mobility Spectrometry for Water Monitoring

William T. Wallace/ SF2 / Wyle Science, Technology, and Engineering Group

Contact Info: william.wallace-1@nasa.gov / 281-483-2846

PROJECT OVERVIEW

- Ion mobility spectrometry (IMS) has previously been used on ISS to measure air quality and provides a potential opportunity to also measure water quality.
- Electrospray ionization (ESI) can be used to ionize water samples with no additional preparation for introduction into the ion mobility spectrometer.

RELEVANCE/ VALUE TO NASA

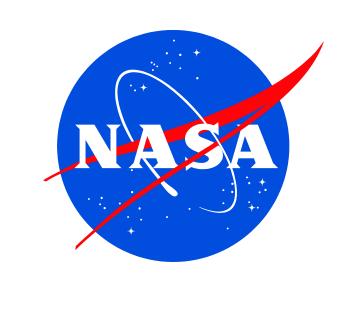
• The ability to analyze water samples (and possibility biological fluids) on orbit will limit/eliminate the need for sample return. Gaining insight into the concentration of specific trace contaminants will aid in mitigation approaches.

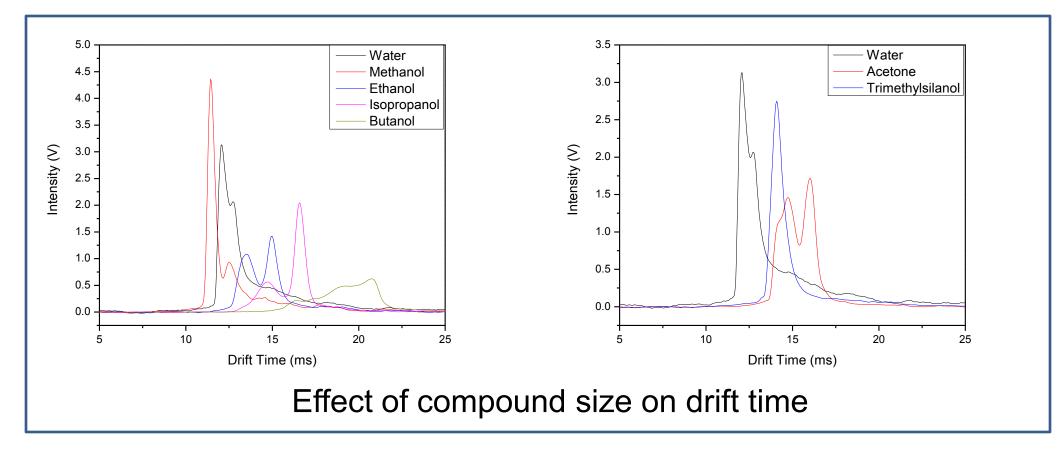
OBJECTIVES & OUTCOMES

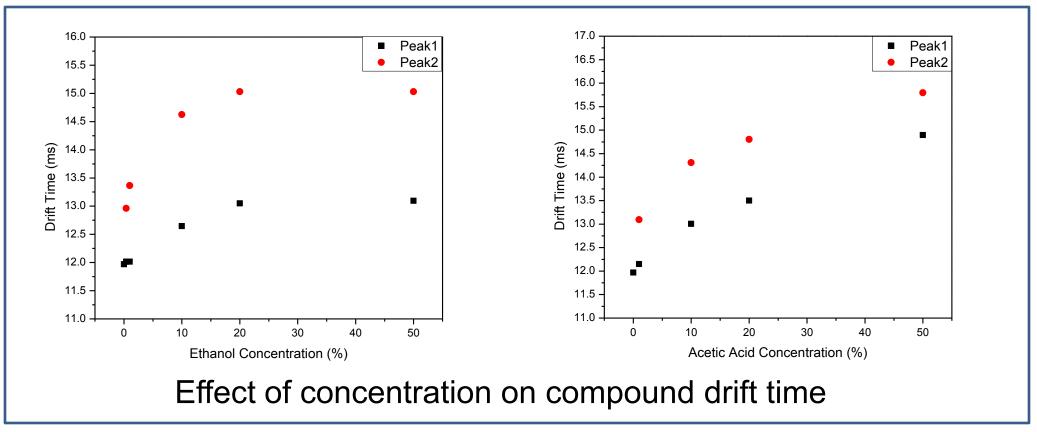
- The objective of this project is to construct an ion mobility spectrometer and combine it with ESI to test samples containing volatile organic compounds present in ISS water.
- The intended product of this work will be a report detailing the changes in drift time of different compounds entering the IMS as well as the effects of changing drift gas and matrix effects.

INFUSION POTENTIAL

• The ability to analyze water samples in real time makes IMS a potential analyzer for future exploration missions. Slight modifications to the ionization source would make it possible to analyze both air and water using a single unit.



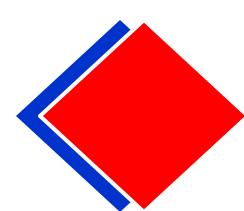




NASA TECHNOLOGY AREA ROADMAP

• This project is relevant to TA-06 Human Health, Life Support, and Habitation Systems, aligning with 6.4 Environmental Monitoring, Safety, and Emergency Response.

		ct: Ion Mobility Spectrom		3727	
		Start Date: May 14, 2012 E	nd Date: Aug. 31, 20	12	
May	2012	June 2012	July 2012	August 2013	
Kick-off					
	Ordering ar	nd Construction of IMS			
		Testing of IM	S with ESI source		
					Report



Variable Property Thermal Control Fluids

PROJECT MANAGEMENT

Thomas J Cognata: ESCG, 2814615415, thomas.cognata@escg.jacobs.com and Moses Navarro: ESCG, 2814615414, moses.navarro@escg.jacobs.com

PROJECT OVERVIEW

 Spacecraft designed to meet current safety standards use a two-loop thermal control architecture. This project explores the merit of dynamic fluids as a technology to enable single loop architecture. A dynamic fluid is a solution or suspension where the composition is adjusted to tailor fluid properties throughout a mission to a spacecraft's environment.

RELEVANCE/ VALUE TO NASA

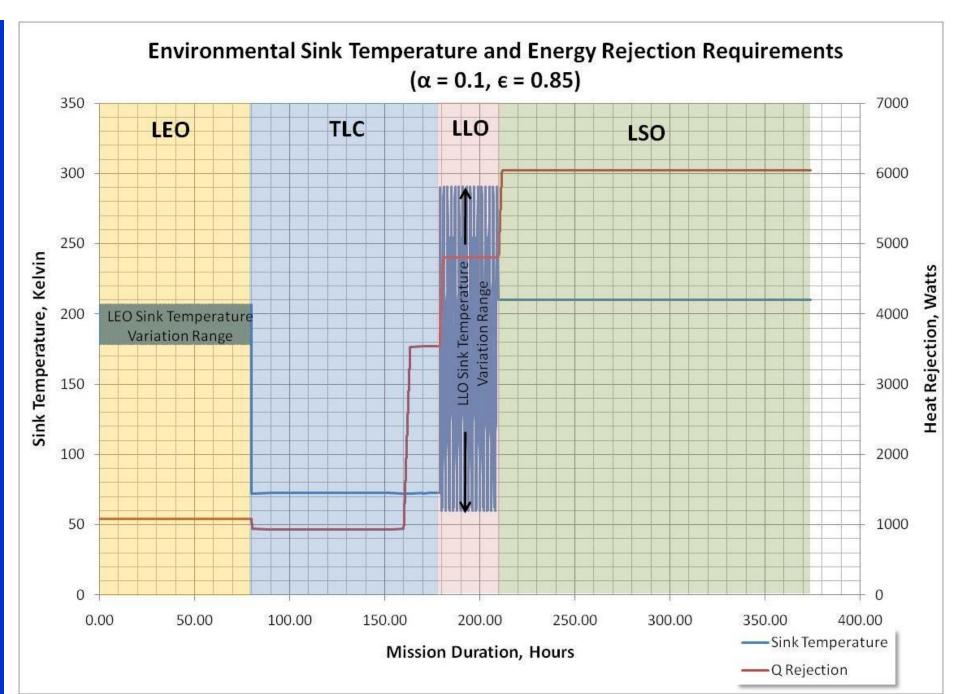
 This promises mass and volume savings by enabling a single loop thermal control architecture.

OBJECTIVES & OUTCOMES

- Evaluate merit by modeling adjustable PGW in portions of a lunar mission. Early results indicate a 17% increase in turn-down ratio using a dynamic range of 10 to 60% PG vs. 50% PG.
- Modeling results and a survey of dewatering technologies, given merit, will be presented.

INFUSION POTENTIAL

 The advanced thermal group within EC2 has been investigating single loop enabling technologies. The merit of this technology may be further investigated and developed for spacecraft applications.



A dynamic mission environment requires a high turndown ratio.

 Has potential as a thermal working fluid with wider operating range than static PGW and better heat transfer properties than synthetic fluids such as Galden and Syltherm.

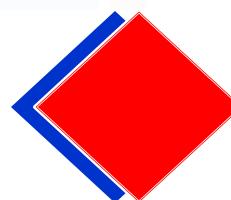
NASA TECHNOLOGY AREA ROADMAP

• This is a technological advancement and is relevant to the areas of Thermal Management Systems and Human Health, Life Support, and Habitation systems.

PROJECT DEVELOPMENT SCHEDULE

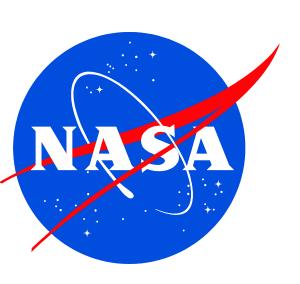
Collect properties and data: May to July
 Develop radiator model: June to Aug
 Evaluate dynamic PGW: July to Aug

Investigate PGW dewatering: Aug



Project Start TRL (1-9): <u>2</u>
Current TRL (1-9): <u>3</u>

Nano-Antenna For Terahertz (THz or T-Ray) Medical Imaging



PROJECT MANAGEMENT

Shian Hwu PhD, JSC/EV/ESCG/Barrios, 281-244-5731, Shian.u.hwu@nasa.gov

PROJECT OVERVIEW

- X-ray imaging could damage human tissues and DNA.
- T-ray imaging does not damage human tissues and DNA due to the non-ionizing radiation nature.
- Investigate/optimize nano-antenna designs using the state-of-the-art computer modeling tools.

RELEVANCE/ VALUE TO NASA

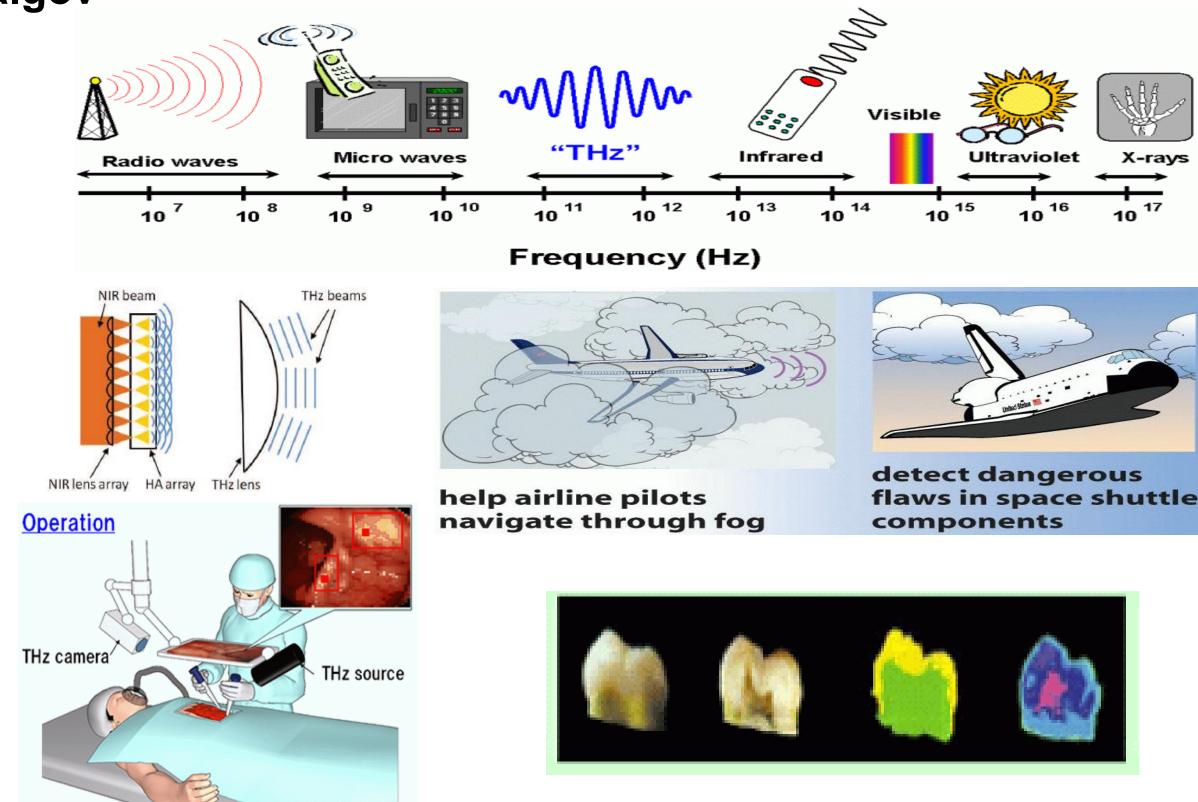
- THz technology has 30 years of applications in space radio astronomy
- T-ray imaging could inspect spacecraft damaging component non-destructively.

OBJECTIVES & OUTCOMES

 Optimize antenna design to increase radiation efficiency and maximize the THz emitter output power.

INFUSION POTENTIAL

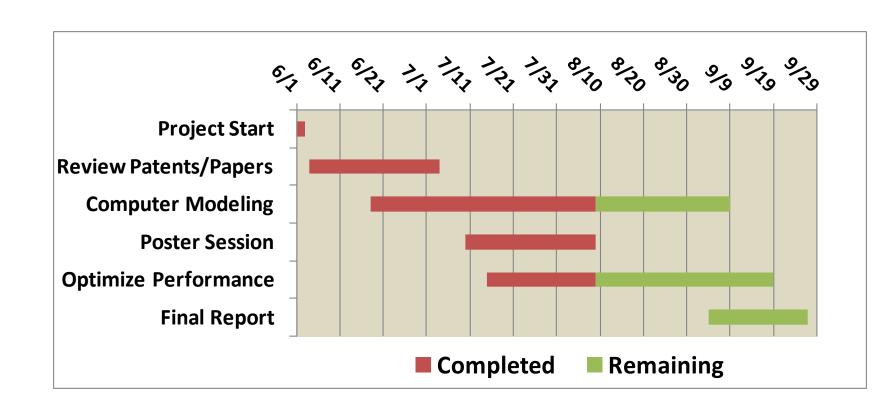
- For astronaut health management and spacecraft structural monitoring
- T-ray imaging facilitate the search for explosives for Airport Security applications.
- Effective detection of epithelial cancer
- Accurate 3D imaging in dentistry applications



NASA TECHNOLOGY AREA ROADMAP

- TA10-17 Nanoelectronics, sensors and actuators are important research area for NASA's mission
- TA10-18 High sensitivity and detection capability and lower power than conventional sensors.

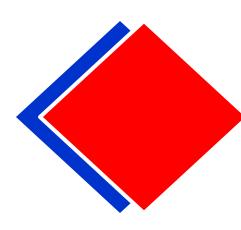
PROJECT DEVELOPMENT SCHEDULE





Project Start TRL (1-9): #2

Current TRL (1-9): <u>#3</u>



Electrochemical Approach to In-Situ, Real-time Detection and Identification of Microorganisms for Manned Spaceflight

DANIEL GAZDA, DOUGLAS BOTKIN / SF2 SHANA KELLEY / UNIVERSITY OF TORONTO

CONTACT INFO: DANIEL.B.GAZDA@NASA.GOV, 281-483-6892

PROJECT OVERVIEW

- Currently, assessing the potential crew health risk associated with a microbial contamination event requires return of representative environmental samples.
- In this project, we are evaluating a novel detection platform that combines an electrical cell lysis chamber with an electrochemical reporter system that utilizes nanostructured microelectrodes (NMEs) for in-flight detection and identification of microorganisms.

RELEVANCE/ VALUE TO NASA

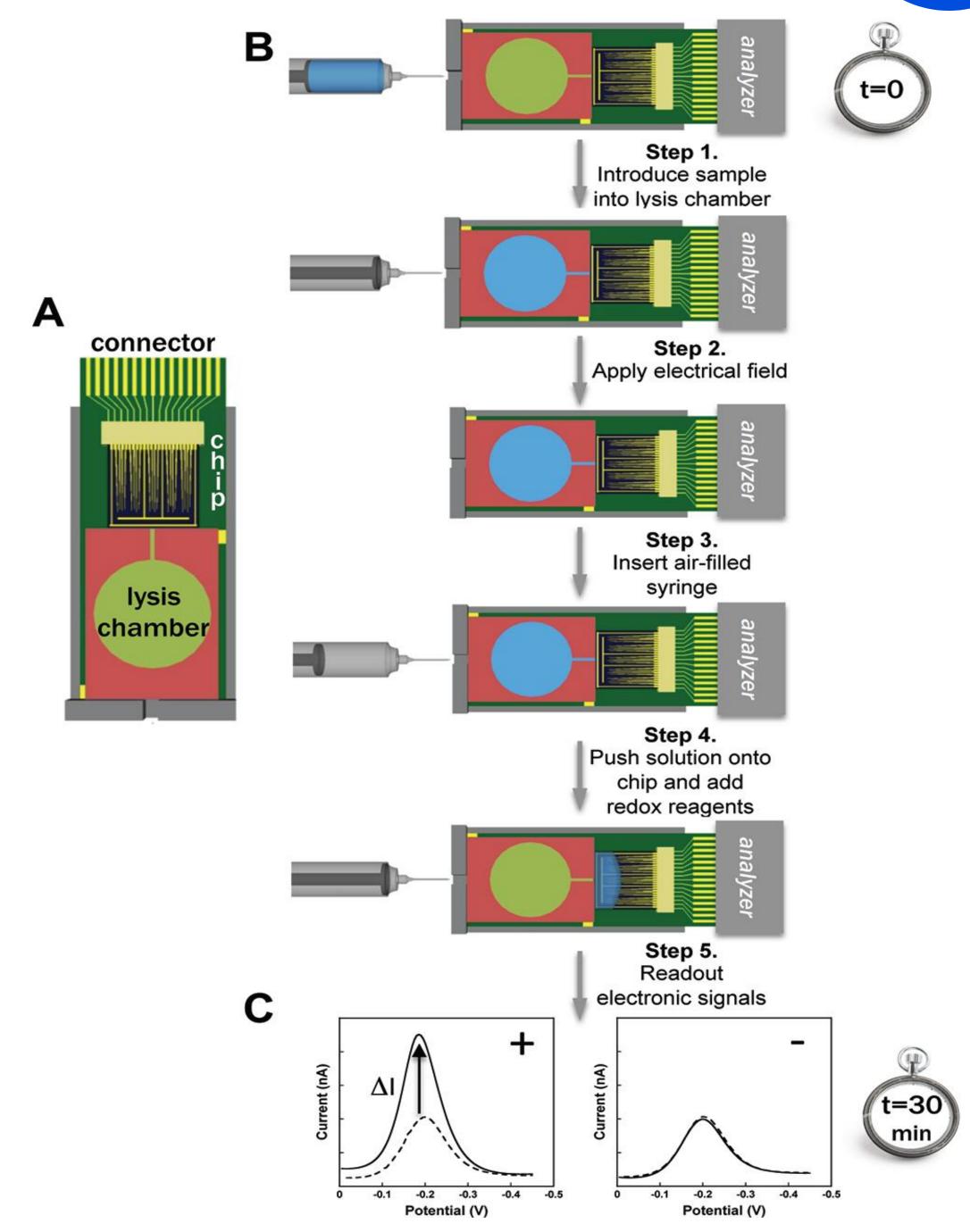
• By providing enhanced in-flight monitoring capabilities we can reduce reliance on archival samples and improve our response to in-flight contamination events.

OBJECTIVES & OUTCOMES

- The objective of this project is to develop and test devices capable of detecting and quantifying target organisms that were recovered from water samples collected on the ISS.
- A secondary objective is to evaluate the potential for the platform to differentiate closely related organisms as well as distinguish pathogenic vs. non-pathogenic organisms.

INFUSION POTENTIAL

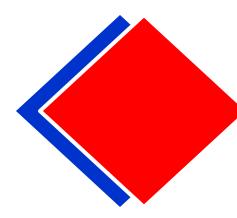
• If this project is successful, follow-on funding would be required to develop a flight ready system based on this technology. However, the portability of the devices and capability provided addresses existing monitoring needs for both the spacecraft and terrestrial environments.



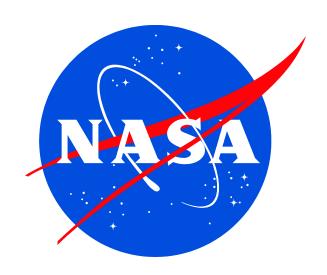
Lam, B., Fang, Z., Sargent, E. H., and Kelley, S. Anal. Chem. 2012, 84, 21-25.

NASA TECHNOLOGY AREA ROADMAP

• This project is relevant to TA-06 Human Health, Life Support, and Habitation Subsystems, aligning with 2.4 Environmental Monitoring, Safety, and Emergency Response.



Integration of Voice and Gesture



PROJECT MANAGEMENT

David Overland/EV3

281-483-4304 david.overland-1@nasa.gov

PROJECT OVERVIEW

 Gesture and positional information provides context to speech. Recent consumer technology has lowered the entry level costs for both speech and gesture recognition.

RELEVANCE/ VALUE TO NASA

 Hands-free computer interaction allows astronauts more time to perform mission tasks.

OBJECTIVES & OUTCOMES

- Survey of the technical field was accomplished. Basic software and hardware, including microphones, cameras and 3D depth sensors was procured.
- Basic equipment functionality has been demonstrated. Groundwork has been laid for continued efforts.

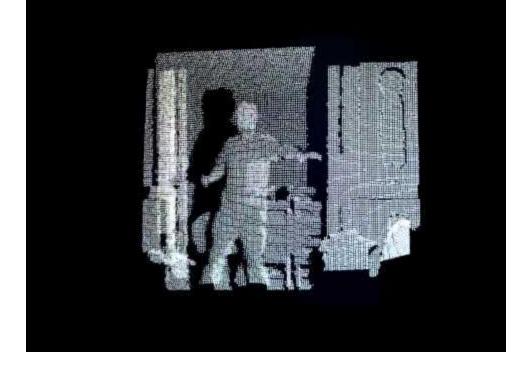
INFUSION POTENTIAL

- Working prototypes will be integrated into the Flight Deck of the Future (F.F). Design principles will be used to develop further prototypes addressing specific simulated mission objectives.
- Speech recognition technologies are being hosted in immersive environments (cars, living rooms).
 Gesture recognition exists in gaming consoles. Frameworks are still needed for integration.





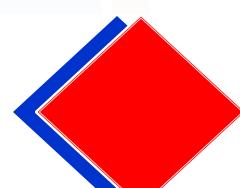




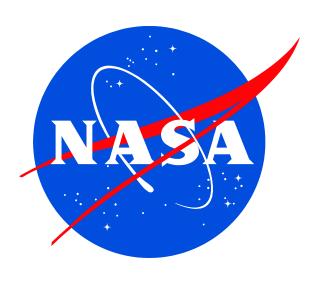
NASA TECHNOLOGY AREA ROADMAP

This project directly addresses
 TA4.4.4 Intent Recognition and Reaction. Determining "implicit operator intent" to provide speech context is the goal of this project.

Project Name	Days	Start	End	14-May	28-May	11-Jun	25-Jun	9-Jul	23-Jul	6-Aug	20-Aug	3-Sep	17-Sep
Integration of Speech &													
Gesture	136	14-May	27-Sep										
Spring ICA	136	14-May	27-Sep										
Project ATP	1	14-May	15-May										
Procure Hardware and Software	81	6-Jun	26-Aug										
Research existing prototypes	81	15-May	4-Aug										
Select prototype for rehosting	7	28-Jul	4-Aug										
Develop prototype and evaluate	56	28-Jul	22-Sep										
Poster Session	1	9-Aug	10-Aug										
Document white paper	21	6-Sep	27-Sep										



Hybrid Windows and Mosaic Video: Reducing Complexity of Space Habitable Modules



PRINCIPLE INVESTIGATORS

Helen Neighbors, NASA, (281) 483-0811, helen.neighbors@nasa.gov, EV3; George Studor, NASA, (281) 415-3986, george.f.studor@nasa.gov, ES2.

PROJECT OVERVIEW

• Explore options for providing direct viewing and image sensing through arrangements of multiple, small portals that accommodate various cameras, sensors, and human eye.

RELEVANCE/ VALUE TO NASA

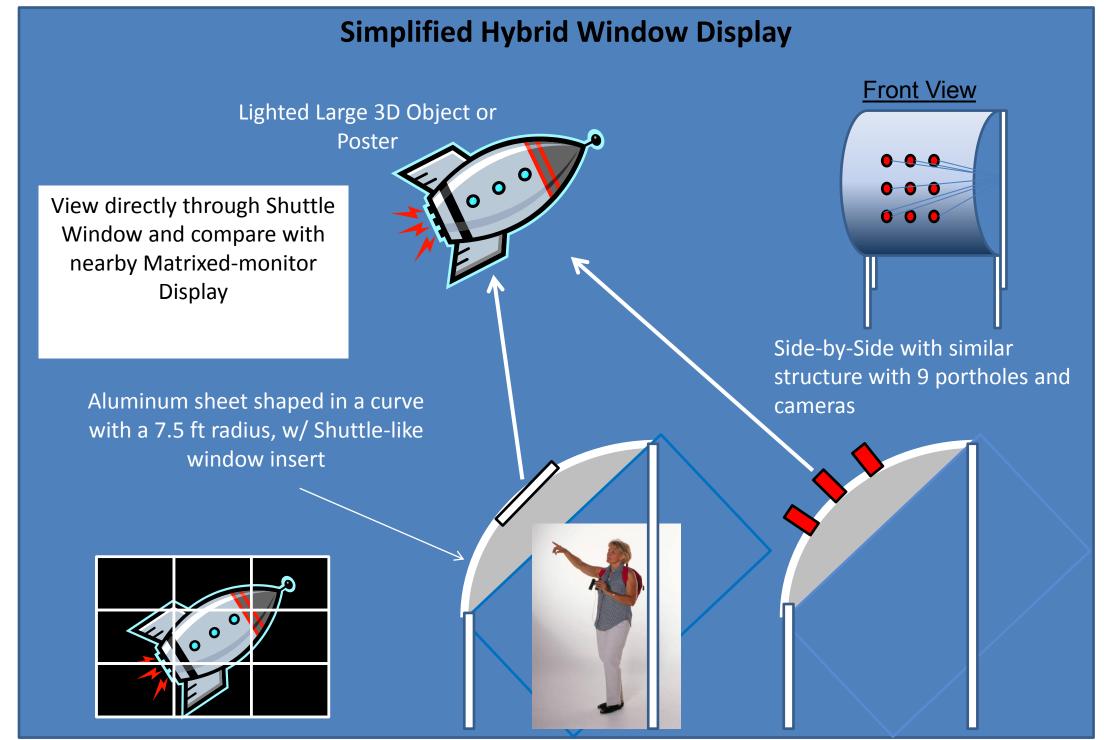
• Enhances design and adds more locations for, direct viewing; easier maintenance; represents less of an impact to a vehicle's structural integrity than traditional windows, and applies to aluminum, composite and inflatable structures.

OBJECTIVES & OUTCOMES

- Architectural studies and design;
- Demonstration and evaluation prototype to be built;
- Human Factors evaluation to be conducted;
- Test report to be generated.

INFUSION POTENTIAL

- Potential for infusion into JSC, MSFC Deep Space Habitat evaluation facility.
- Potential for infusion into undersea applications e.g. NEEMO.



NASA TECHNOLOGY AREA ROADMAP – Aligns with:

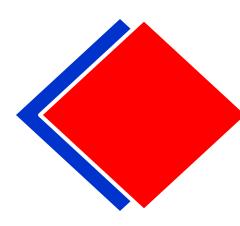
☐ TA07 Human Exploration Destination Systems / Advanced Habitat Systems;

☐ TA12 Materials, Structures, Mechanical Systems & Manufacturing / Structures;

PROJECT DEVELOPMENT SCHEDULE

FY '12

<u> 1st Qtr 2nd Qtr </u>	3 rd Qtr / 4 th Qtr /
Project start	△ 06/12
Poster Session	△ 08/12
Prototype development completed	08/12 📤
Comparative Eval completed	08/12 🔺
Final Report	09/12



Project Start TRL: 1

Current TRL: 2

SINGLE-SIDED TEMPORARY ADHESION IN ZERO-G WITH GECKO AND ELECTRO-STATIC MATERIALS WALKING IN SPACE

PROJECT MANAGEMENTES2/George Studor

george.f.studor@nasa.gov 763 208-9283

PROJECT OVERVIEW

• Demonstrate applications of new synthetic Gecko-feet and electro-adhesion materials to zero-G.

RELEVANCE/ VALUE TO NASA

 Temporary adhesion can be controlled to keep items from floating away during crew ops, including the crew member.

OBJECTIVES & OUTCOMES

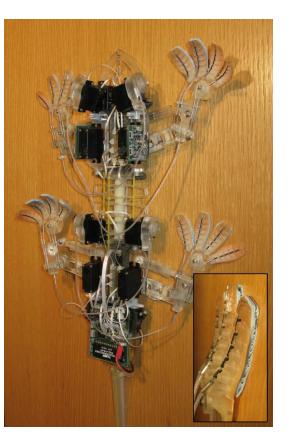
- Build and demonstrate a controllable mechanism to grip using Gecko-material secure sensors or equipment to a smooth surface, or to secure a crew member in a work area.
- Obtain and test an electro-adhesion pad to hold small articles in zero-g, provide adhoc adhesion for a free-flier and to potentially secure and astronaut to any smooth surface.

INFUSION POTENTIAL

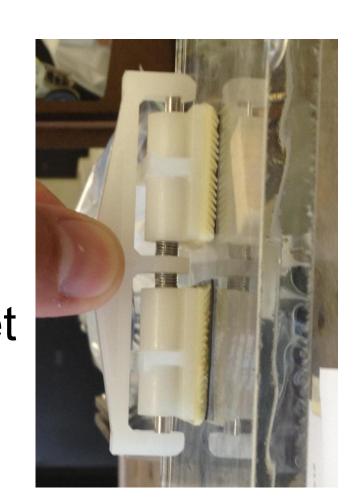
- Additional characterization in ground labs and flight tests.
- Gecko-material pads could replace velcro in many applications and add functionality.such as attaching sensors
- E-A pads provide a portable surface to keep items, even food, from floating away.
- Both feed concept s of crew or robots maneuvering and/or securing themselves in place with min vehicle infrastructure in new vehicles.

JPL/Aaron Parness

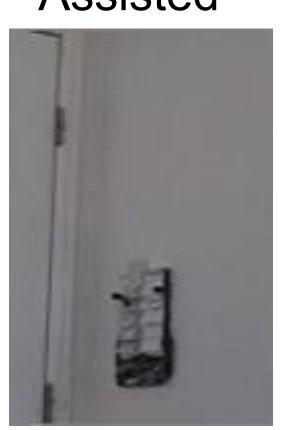
aaron.parness@jpl.nasa.gov 818 393-2236







Gravity Assisted





Gravity
Independent
Docking

E-A Climbing robot

IVA operations

NASA TECH AREA ROADMAPS

7.6.2 Construction and Assembly 7.6.3 Dust Prevention & Mitigation

7.4.2 Habitation Evolution

7.4.3 Smart Habitats

7.2.2 Maintenance Systems

12.2.5 Multifunctional Concepts

12.2.1 Lightweight Structures:

12.1.1 Lightweight Materials

12.5.1 NDE Evaluation and Sensors

12.3.4 Mechanisms Methods

12.3.1 Deployables, Docking, & I/F

2nd Otr 1 2rd Otr 1 1th

Prototype development completed

Testing and Eval Completed

Final Report

09/25

09/12

08/25

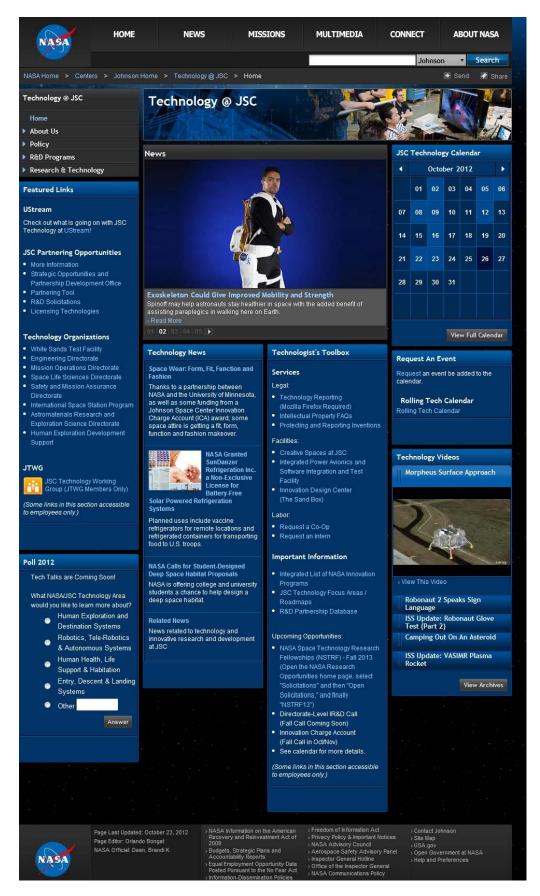
Project Start TRL (1-9): <u>2</u> Current TRL (1-9): 3



Appendix D

Technology at JSC Homepage

Technology @ JSC Website Homepage





Appendix E

The Year Ahead / Technology Calendar FY'13 One-Pager

JSC Technology Development & Innovation Initiatives (FY'13)

Rolling Calendar Rev. 2

